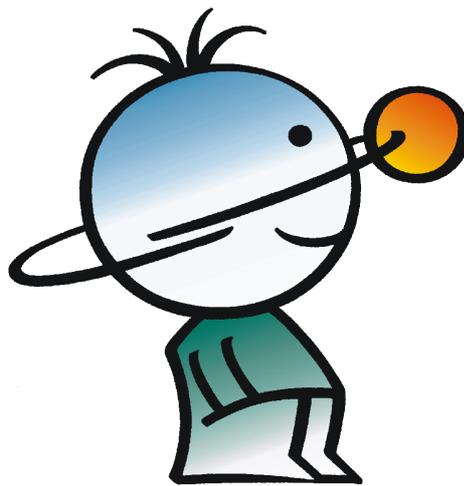


NEWTON

3D Multimedia Lab for Exploring Physics

Mechanics



Users Guide

DesignSoft

2010

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Part



1 Introduction

The virtual world of Newton provides a completely new way of learning physics—the exploration of kinematics and dynamics on a computer in 3D. The virtual world of Newton is ruled by the simulated laws of physics, allowing you to build, manipulate and analyze your experiments freely and interactively.

When creating an experiment in Newton, you can select from a wide range of real world or abstract objects, from the simplest geometrical bodies (brick, sphere, etc.), complex instruments (stands, slope, car, etc.), and constraints (many types of joints and springs). You can adjust their physical parameters (mass, elasticity, friction, etc.); assign to them forces, torques or velocity; and make relationships subject to constraints. You can add virtually any object to Newton using a VRML editor; you may also export your experiments in VRML format.

With the example files included, it's easy to get started. You can alter them and simulate again, and you will see that it's quite simple to create amazing demonstrations.

When running a simulation, the bodies start moving, guided by the acting constraints; are rotated by torques; and collide with each other as in a movie. Actually, you can set up one or more “cameras” and capture their views of the experiment, storing them in an AVI file.

You can also add descriptions to your examples, with explanatory texts, images, and formulas. Using diagrams, it's easy to measure and evaluate the results of your experiments. Several user-defined curves can be displayed on the same diagram, so it's easy to compare the measured data with the results derived from theoretical calculations. You may also change the units of the physical quantities.

Part



2 Installation

2.1 Installation procedure

Minimum hardware and software requirements

- IBM PC Pentium or better
- 128 MB of RAM
- A hard disk drive with at least 400 MB free space
- CD-ROM
- Mouse
- 24 bit true color, fast VGA graphics card with OpenGL Support
- Microsoft Windows 98 / ME / NT / 2000/ XP / Vista / 7
- Novell Netware version 3.12 or later or MS Windows NT / 2000 / 2003 / 2008 Server or later or Linux with Samba file server for SMB clients for the Network versions

If the program is copy protected by a hardware key, the minimum hardware configuration includes also a USB port.

Installation from CD-ROM

To begin the installation, simply insert the CD into your CD-ROM drive. The Setup Program will start automatically if the Auto-Run function of your CD-ROM has been enabled (Windows-Default). If not, Select Start/Run and type:

D:SETUP (Enter) (where D represents your CD-ROM drive).

The setup program will start.



Note: This software may come with copy protection. For further details see the Copy Protection and the Network Installation sections.

Following the Installation Steps

NEWTON's Setup Procedure follows the steps standard with most Windows Programs. There are several screen pages where you can enter or change important installation choices, such as Type of Installation, Destination Directory, etc. To continue installation, click on the **Next** button. You can always step back, using the **Back** button. If you do not want to continue installation for any reason, click on the **Cancel** button. If you elect to cancel installation, the program will ask you if you really want to exit. At this point you can either resume or exit Setup.

Welcome and Software License Agreement

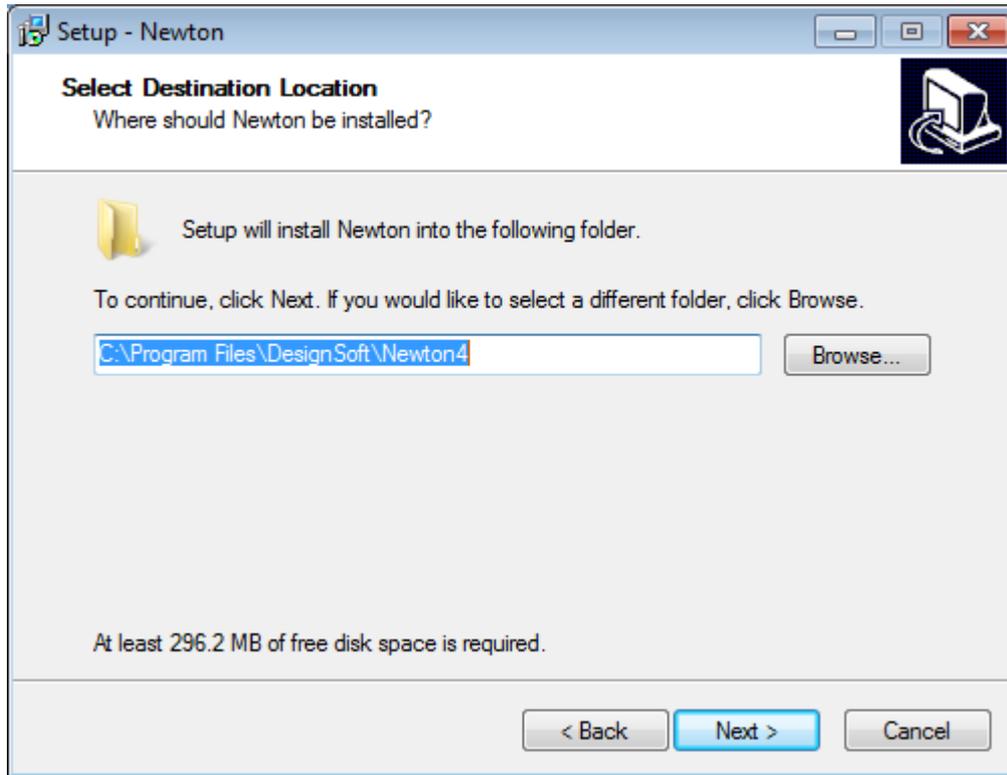
To begin the Procedure, click on the **Next** button on the Welcome Page. The first step is the Software License Agreement.

Note: By clicking on "Yes" you are agreeing fully with DesignSoft's Terms and Conditions for using this software.

Choose Destination Location

Here you can select an Installation Directory other than the one suggested as a default. The default is the Windows Standard Directory for Programs. To change the directory, click on

Browse and select a different drive and/or directory from the Choose Folder Dialog.



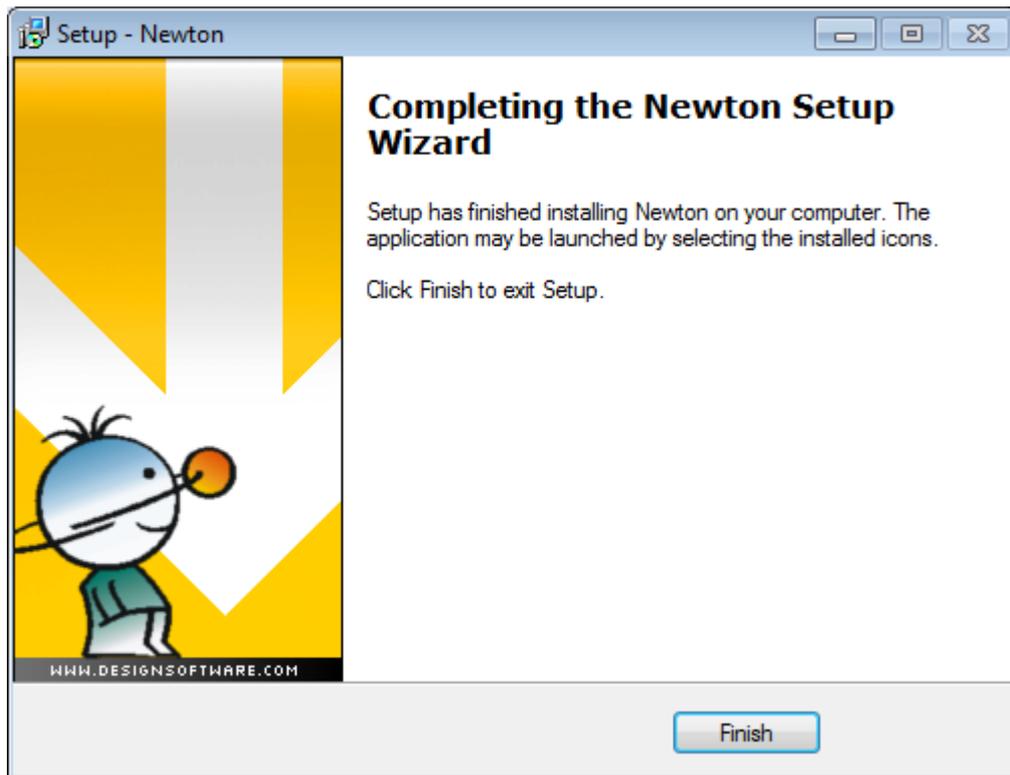
Note: If you are installing NEWTON for Windows to a hard disk that already has an earlier version of NEWTON, you must be sure to use a new directory name for NEWTON for Windows, such as the suggested directory, C:\Program Files\DesignSoft\Newton4, or the working files you have already created will be overwritten and lost. If uncertain, exit setup, copy your NEWTON files safely to another hard disk directory or to floppy disks, then resume setup.

Select Environment Options

In Newton you can set up the settings, private/shared catalog and temporary folder. The Settings folder stores your personal settings. The private catalog folder will store your catalog files, while the shared catalog folder can be used to share catalog files with other users of the same PC or with other users in the network. The temporary folder stores the temporary files of the software. By default these folders are set to common Windows folders however you may change the folders by pressing the browse button.

Completing the Setup

After all the selected files have been copied and the Start Menu entries created, you are asked if you want to place a Shortcut to the NEWTON program file on your Desktop. The last page indicates a successful installation and invites you to open and read a file with the latest information about NEWTON. We urge you to take a moment and review that file. Click on finish when you're ready.



Note: You can read the latest information in the file again at any time by selecting Read Me from the Newton Start Menu Entries. You can also get the latest information about changes or new features by visiting our Web Site, www.designsoftware.com.

2.2 Uninstalling NEWTON

You can uninstall NEWTON for Windows at any time. Note that this will not delete files you have created.

1. To begin Uninstallation, choose **Newton for Windows** from the **Newton Start-Menu Entries**.
2. In the Window that appears, double-click on **Uninstall Newton**.
3. Click on Yes if you are positive you want to uninstall Newton.

After all the files have been removed successfully, an OK Button appears. Click on it and uninstallation is complete.

2.3 Network Installation

To install the Network version of NEWTON, you must log on to your server machine as a user with administrative privileges (Novell 3.x: supervisor, Novell 4.x: admin, Windows NT: Administrator). Then execute the procedure for the Hard Disk Installation on a disk volume that is accessible from the network. Now carry out the following additional steps:

Make all files in the program and user directories sharable:

Novell 3.x:

FLAG *.* S SUB

Novell 4.x:

FLAG *.* +SH /S

Windows NT/2000/XP:

Depending on the setup of your system, you can give the rights to a group (<groupname>) whose members will then have the appropriate rights automatically.

Next make sure that the clients have a mapped drive set to the network drive containing the NEWTON program folder.

To assign (map) a drive letter to a network computer or folder do the following:

1. Open Windows Explorer
2. On the **Tools** menu, click **Map Network Drive**.
3. In **Drive**, select a drive letter e.g. **G:**
4. In **Path** (Win9x/Me/ or **Folder** (NT/2000/XP), select from the drop-down list or type in the network drive (server and share name) or folder name to which you want to assign (map) a **Drive** letter. Note, that share name refers to a shared folder on the server. On Windows NT/2000/XP you can use **Browse** to find the network computer, drive and folder.
5. Set the **Reconnect at Logon** checkbox.
6. Press **OK**
7. **Examples:**
 - Drive: **G:**
 - Folder:** \\servername\sharename
 - or
 - \\MyServer\Volume1
 - \\MyServer\Volume1\Public

After you have set everything up on the Network disk according to the instructions above, you must run the setup program on each Novell workstation where you want to run NEWTON. Using the Run command, start **NSETUP** from the **Newton\NWSETUP** directory. Note, do not double click on the NSETUP icon, but use the Run command instead to start the program.

When you run NSETUP, you must specify the working directory (which should be located on a local drive of the workstation). **The working directory can be on the network; however in this case the path of this directory must be different on every workstation.** After running NSETUP, you will be able to run NEWTON simultaneously on any number of workstations, just as though each workstation had a single user version.

2.4 Copy Protection

Software Protection

If your version of NEWTON is copy-protected by software, select **Authorize** from the **Help** menu. For more information, choose Help from the Authorization dialog or open the file 'DSPNewton.hlp'.

Hardware protection

If you have a hardware-protected version, plug the dongle (hardware protection key) into the parallel (printer) or USB port connector. If you have a printer, connect it through this key. Should you forget to connect the dongle, an error message will come up on the screen:

```
Hardware protection key is not present
```

Note: If you have a dongle-protected version under NT/2000/XP you should install Newton in Administrator mode and restart the computer after installation.

Part



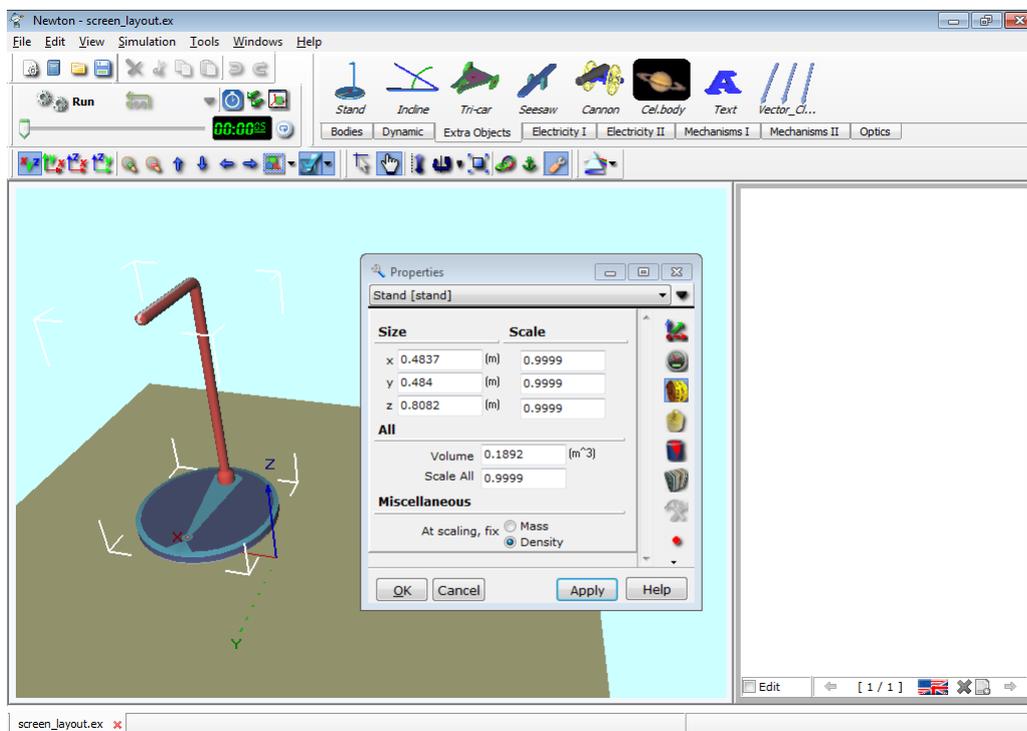
3 Overview

In this chapter we present NEWTON's screen format, controls and menu structure.

3.1 Screen layout

The user interface of the program is divided into six main parts:

- 3D Window
- Description Window
- Toolbars
- Menus
- Status field
- Dialogs



On the left side of the initial screen you can see the 3D Window, where you can edit or track the ongoing experiments in a 3D perspective view.

Use the  control buttons (Camera bar), to change your point of view. Rotate the scene, zoom-in or zoom-out, and select special top or side views. Even if a portion of the experiment is obscured from one vantage point, you can adjust the camera and bring it into view. You can also rotate the scene by holding down the left mouse button and moving the mouse, zoom in and out by holding down the right mouse button, or shift the scene by holding down both buttons and moving the mouse.

Using the  control buttons (Scene bar) and the mouse, you can modify objects and their positions in the 3D window. The first two icons choose between

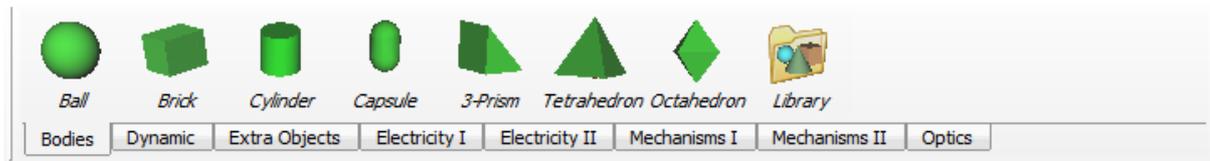
the geometric and physical editing modes. Using the geometric editing mode, objects can be moved freely without regard for their logical and dynamic relationship to the other objects. The Bodies can slide into each other without collision, and the constraint parameters can be altered using the mouse.

Using the  physical editing mode, the bodies collide and slide against each other, remaining on their track according to the constraints. The next three icons give you control over vertical position, object rotation, and zoom setting. The last two icons are used to build various relations among the object, link and anchor.

The right window (Description Window) presents explanations, pictures, or diagrams. Diagrams can display the curves of the experiment based on the simulated or theoretical results. The Description Window may also contain interactive elements, including buttons, edit fields, radio boxes, check boxes, or track bars. The Description Bar presents icons that you can use when editing or creating the Description Window.



On the top of the application window you can see many toolbars. One of the most important of them is the **Object Bar**.



It contains the icons of the commonly used bodies, constraints and auxiliary objects that you can use in your demonstrations. The different types of objects are grouped on different tabs. Click on an icon to pick up the selected object and place it into the 3D window.

The  toolbar helps you in performing file operations.

In some situations, pressing the right mouse button will bring on-screen a context menu to give you quick access to commonly used commands related to the selected graphical object or to the panel you clicked on. You can find these by right-clicking the objects in 3D Window or the graphical objects of the Description Window.

One of the most important dialogs, which you can access by right-clicking or double-clicking an object, is the Properties Window, where you can set or modify the attributes of the bodies and dynamic objects.

You can quickly toggle between open demonstrations using the tabs at the bottom-left corner of the main window. In the bottom-right corner there is the Time field. It displays the elapsed (virtual) time of the running simulation.

3.2 Running demonstrations

Newton comes with many prepared example demonstrations. Select the File/Open command to load them.

When you load an example, the 3D and Description Windows will show the 3D experiment and the explanations (if any) respectively.

You can rotate the point of view by clicking on a blank area of the 3D Window, holding down the left mouse button, and moving the object to the desired position. If you click with the right mouse button, you can step back and forward. You can slide up or down in the space by moving the mouse and holding down both mouse buttons simultaneously.

Click on the  (Run) icon to start the simulation. The simulated laws of physics will guide the bodies in their motion. To stop the simulation, click on the  (Stop) icon; it appears in place of the Run button when an experiment is running. You can reset the scene by clicking on the  icon.

The smoothness and speed of the motion depend on your computer speed and screen resolution. If a simulation requires a lot of calculations, and your PC's processor isn't fast enough, the simulation will not move smoothly and in realtime. In this case, use the  (Playback) function. It plays the last simulated demonstration smoothly and continuously from the PC's DRAM memory.

Part

IV



4 Getting started with examples

In this tutorial chapter, we will show you step-by-step how to use the program and how to make convincing experiments and demonstrations. We recommend that you take the time to walk through all the examples, not just read them.

The instructions for the first and second tutorials are detailed, while the later examples build on the knowledge acquired from these and are not presented as thoroughly.

4.1 Demonstrating free fall and making diagrams

Our first example is very simple: you are to investigate the movement of a ball constrained by the constant gravitational field of the earth. You will learn how to set the basic properties of the bodies and how to depict their movement via diagrams. Later, the measured data will be compared with the results derived from theoretical calculations. You can find this pre-built example in the Freefall.ex example file.

Create a new experiment by clicking on the  (New) icon. This will call up empty 3D and Description Windows and the screen shows only a tabletop.

Here's how to modify the point of view in the 3D space: to rotate the vantage point, click and hold the left mouse button on an empty area of the 3D Window and move the mouse in the selected direction. To step forward and back (zoom-in and zoom-out), press and hold the right mouse button. To slide in any direction, press and hold both mouse buttons. Note that you can do the same but in larger steps using the  toolbar controls.

Perhaps you'd like a special top or side view of the scene – use the  toolbar buttons to select another view, or the  button to revert to the general 3D view. Using the

 control buttons (Scene bar) and the mouse, you can modify objects and their positions in the 3D window. The first two icons choose between the **geometric**  and **physical**  editing modes. Using the geometric editing mode, objects can be moved freely without regard for their logical and dynamic relationship to the other objects. The Bodies can slide into each other without collision, and the constraint parameters can be altered using the mouse.

Using the  physical editing mode, the bodies collide and slide against each other, remaining on their track according to the constraints. For example, if a body is linked to a hinge, it can move only on a circular track. Because more editing can be carried out in the physical editing mode, it is the default. In the following instructions, you only have to switch to the geometric mode if requested.

Let's start building our first simple experiment.



You can find the body named “ball” on the Bodies page of the Objects toolbar. Click on its icon and the body will immediately appear in the middle of the 3D area. To move the ball to its initial position, use the mouse as follows. To change the location, press and hold the left mouse button over the ball and move the mouse over the scene. This will move the

body in the xy plane and keep the z coordinate unchanged. To place the body properly in the z direction, press down and hold the  icon and use the mouse.

The properties of the ball can be set in the Object Properties dialog. This window will appear if you double click on the ball.

The property window gives access to several pages of properties grouped according to function. For example, on the Location page the position and rotation can be changed, while on the Size page the size of the body can be reset. Each kind of object can have different panels. Clicking on the body invokes the default page, showing the material properties group. On the right side of the window there are icons which you can use to switch to another page of properties.

At the top of this window there is a combo box that contains a list of all the objects currently present in the 3D scene. If you would like to alter its properties, select an object by name and change the appropriate settings. In this list you will find, in addition to the object's name, its identity. All objects have a name and an identity, and they are not the same. The identity, as it identifies the object, cannot be used with more than one object at the same time. It is a combination of a short character string—generally an English word or abbreviation—and a number. There are restrictions: special character cannot be used, for example +-*/[>() or space. We will reserve these special characters for later use; for example, in defining curves in diagrams.

The name of the object can be anything; it can contain more than one word; and the same name can belong to more than one object.

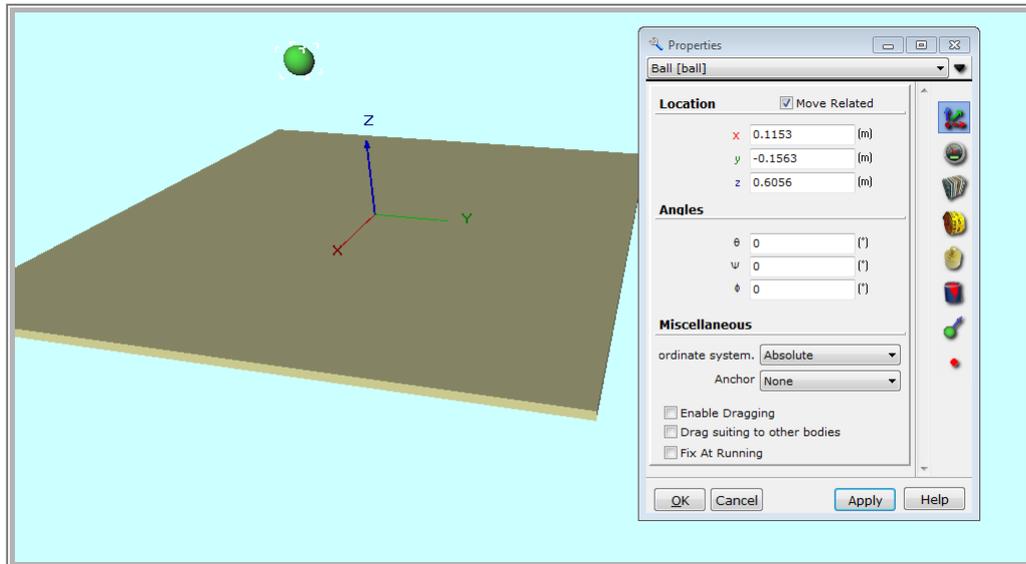
You can easily change an object's name or identity. Select the object and click on the command 'Rename...' in the Edit menu. Alternatively, right-click anywhere in the properties window and a context menu will appear with the command 'Rename'. Name the ball 'Rubber Ball'.

Click the  icon to bring up the Material panel. There is a combo box on this page with commonly used materials. For material, select "Rubber" for now. There are other fields on this page—density, friction, elasticity, etc.—but we will accept their default values now. Press the Apply button to use these new settings.

The color of the ball can be changed on the  Appearance page. The ball in the picture below has been assigned a light blue color.

The dimensions of the body may be altered on the  (*Size*) page. Assign 10 centimeters to the diameter (radius equals 0.05 meters) in the first field of the Size panel.

To assign a mass to the body, bring up the  Inertia panel.



Click on the  (*Inertia*) icon and set the value of Mass to 0.8 kg. Note that since an object's mass is directly proportional to the density, the density of the ball is changed as well.

Using the  (*Location*) panel, set the ball's position to $(x=0, y=0, z=2)$ or $z=2\text{m}$. Adjust the scene by stepping back using the  icon until both the ball and the table can be seen.

Start the simulation. Click on the  **Run** (*Run*) button and watch the ball on the screen.

After falling briefly, the ball bounces off the table. Note that the simulation doesn't stop by itself. To stop it, click on the  **Stop** (*Stop*) button. Click on the  **Reset** (*Reset*) icon to reset the experiment environment to its pre-simulation state.

Making diagrams

Now let's create diagrams to represent the motion of the ball.

In the middle of the table, a coordinate system indicates the origin of the 3D space. By default, the positions versus time diagrams are made using this coordinate (reference) system. The three gray axes that are drawn from the origin, perpendicular to each other, represent the three (x, y, z) directions in the space. In this example, we will display the position of the ball on the z axis as a function of time.



First, be sure that the Description window is in the Edit mode. This is the default for new projects, but you can always switch to Edit mode using the Edit checkbox at the bottom left corner of the Description window. When this window is in Edit mode, you should see the vertical Description toolbar with icons to help you create the contents of the window.

Find the (*Diagram*) icon  and click on it to bring up the Diagram properties window. In this context, you could create a curve and place it in a diagram in the description window. But sometimes you want to just define an empty diagram to prepare for a curve that you will add later. Let's do that now.

Click the OK button. Place the diagram in the Description window as follows. After pressing the OK button, a small coordinate system will appear on the canvas under the cursor. First, move the mouse to the position where you want to place the top left corner of the diagram and click there. After this the diagram size will change as you move the mouse. Moving the mouse now will determine the bottom right corner of the diagram and if it is in its place, click with the left mouse button again.

If you need to modify the size of the diagram, select the diagram by clicking anywhere within its area, and move the graphic cursor above one of the little marking squares appearing in the corners. Use the basic Windows mouse techniques to click and drag the marking squares to their required places. Lastly, you can move the whole diagram by clicking within the diagram area and dragging it with the mouse.

Now let's add a curve to the diagram. Double click on the diagram area, and the Diagram

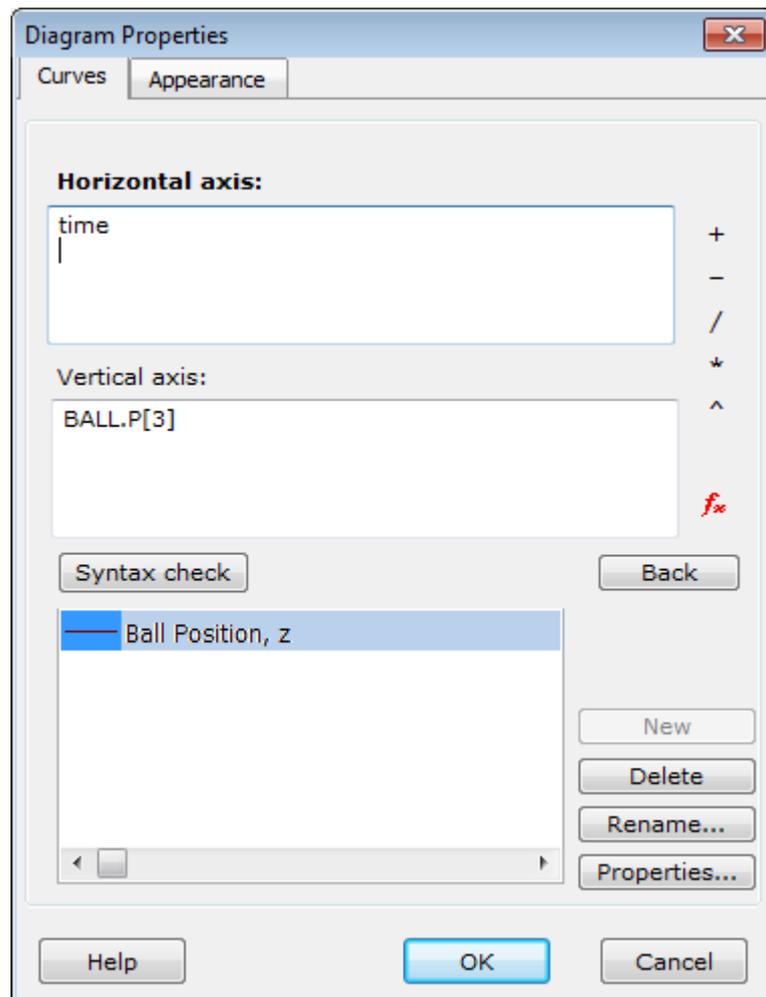
properties window will appear again. This is a two-page dialog. Clicking on the tabs at the top you can change between the pages **Curve** and **Appearance**. On the Curve page you can create, alter and delete curves, and on the Appearance page you can set the general appearance of the diagram, such as the scaling of the axes, format of numbers, etc.

Select the Curves tab to activate its panel. There are two different ways to define a curve. We will use the quicker and easier method, but its possibilities are limited.

Look for the tree view list in the upper part of the window. This presents the variable of the scene object in a tree-structure. Clicking on the ball displays its physical variables, and clicking on the position node expands the three components of the position vector. Select the z component and click on the Add button below. This will tell the diagram tool to draw the position z versus time. Click the OK button to apply this setting.

Starting the simulation again, we see Newton plot the vertical component of the ball's position versus time. The curve is a parabola, a parabola that corresponds to the motion of a body accelerated by the gravitational field. Note that this curve was created with data obtained using numerical methods.

Now let's add the same curve, only created by theoretical methods. This will let us compare the two methods. First, however, to make the theoretical curve, we have to use another method.



Bring up the Diagram Properties window again by double-clicking on the diagram. On the Curves page click the Edit button. This removes the object tree view from the screen. Two text fields and some new buttons appear. These two text fields show the variables assigned to the axes.

Select the previously created curve (“Position z”) and note the simple expressions in its edit fields. In the previous step, where we selected the z-position of the ball, we have generated the curve by actually filling in these expressions. Before creating more curves let’s study the properties of this existing curve.

The Edit fields of this dialog are called Horizontal axis and Vertical axis. In each field there is an expression already; „time” in the Horizontal axis and Ball.p[3] in the Vertical axis field. When the simulation is running, these two expressions are evaluated at every time step, and the two values together provide the point of the curve.

The ‘time’ expression is a global variable of the simulation; it defines the elapsed time from starting. The ball.p[3] expression is a reference to the z component of the ball’s position. Here the ‘ball’ is the identity of the scene object we are examining, ‘p’ means the position of the ball and ‘[3]’ means the 3rd (z) component of the position vector.

All the other variables of the bodies and other objects can be used; moreover, you can use mathematical functions.

You don’t have to remember all the available expressions and variables of your experiment. If you click on the  icon, a dialog listing all the available and appropriate variables and functions will appear. You can browse and insert them into the edit field by pressing the Insert button.

Now we are finally ready to make a new curve. Click on the **New** button and write into the fields the expressions shown in the figure below.



The screenshot shows a dialog box with two input fields. The top field is labeled 'Horizontal axis:' and contains the text 'time'. The bottom field is labeled 'Vertical axis:' and contains the text 'BALL.P[3]'. To the right of the fields are several icons: a plus sign, a minus sign, a forward slash, a star, and a caret. At the bottom right is a red 'fx' icon. At the bottom of the dialog are two buttons: 'Syntax check' and 'Back'.

The word ‘time’ defines the horizontal axis variable to be the simulation time. The vertical axis is assigned the expression

$2-(9.81/2)*time^2$, written as the equation $z = z_0 - \frac{1}{2}gt^2$ in Newton. The term $z_0 = 2$ is the initial position of the ball.

You can write the expression in more than one row if this is more comfortable, but in this case you have to use another form. Let's rewrite the example using this form.

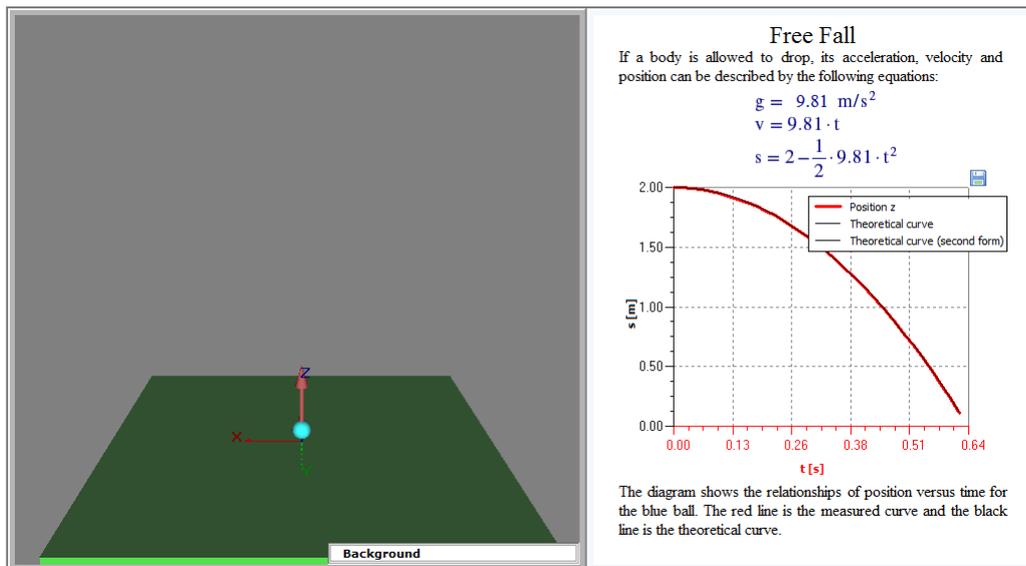
```
var
  z0 : real;
  a  : real;
begin
  z0 := 2;
  a  := -9.81;
  result := z0+1/2*a*time^2;
```

end.

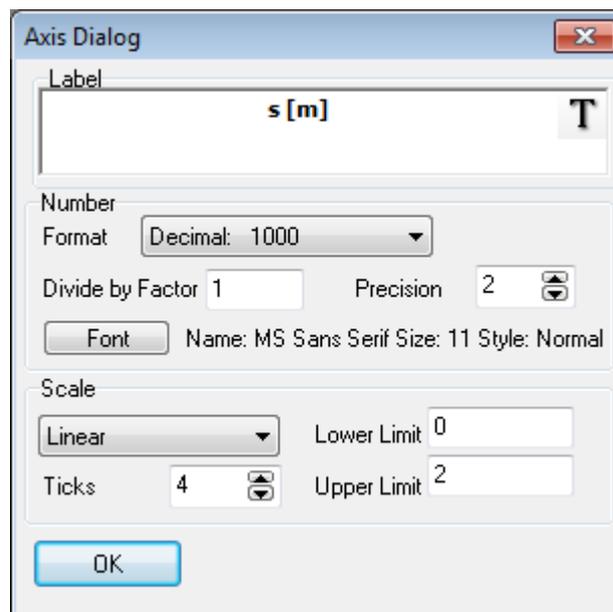
This is a short piece of code in a Pascal-like language where between the begin...end rows you can list your commands, such as 'z0 := 2;'. You must always include the line 'result :=...'; the value of this expression will be plotted as the given axis point. Any variables you use must be declared between the var...begin rows. Be careful that every command line is terminated with a semicolon, and that a period follows the last 'end.' To learn more about writing simple or multi-line expressions, see the chapter 'Newton Interpreter.'

Now we'll change the color of the first curve we created. Select this in the Curve list and click on the Properties button, which can be found in the right bottom part of the window. Set the color to Red and the width to 3.

Close the windows and run the simulation again.



While the ball free falls to the table, the two curves overlap, as you can see in the picture.



To set the axis properties, double-click an axis and work in the axis properties dialog that pops up. For example, adjust the upper limit of the time axis to 1.6, and then close it using the OK button.

You can prevent the simulation from running continuously. In the Simulation menu, locate the Time settings... command and click on it. In the window that opens, you will see the Period panel. Set the “final time” checkbox on and set the time to 1.5s.

4.2 Force and velocities

In this chapter you can learn how to add constant forces to a body, how to adjust them using the mouse in the 3D window, and how to assign an initial velocity to the body. This experiment can be found in the file named ‘Const_Force.ex’.



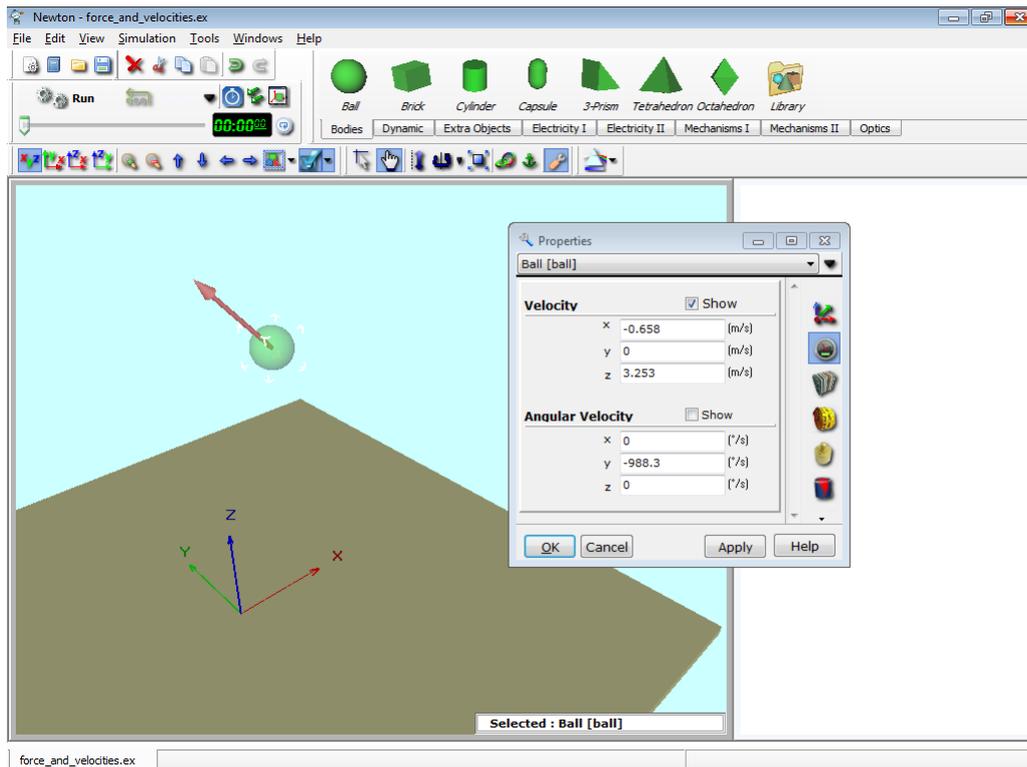
Create a new example and place a ball on the scene by clicking its icon on the Object Toolbar. Move the ball to one of the table’s corners by double-clicking on the ball and setting its position value on Location page of the Properties window. Type these values into the position fields:

$$x=1\text{m}, y=1\text{m}, z=0.5\text{m}$$

Set the ball’s color to blue on the Appearance page. Set the z component of the velocity on the Velocity page to 2m/s.

To verify the entries, click the **Show** check button above the edit fields to show the velocity arrow in the 3D Window. You can immediately see in the 3D window that the ball now has a red arrow emanating from the body’s center of mass.

There’s a more intuitive way to adjust the initial velocity. Using the mouse, select the vector then click on the vector’s head by pushing the left mouse button. This will let you set the vector’s direction. If you click on the vector’s shaft, you can change its magnitude.



When you need to set a property to an exact value, use the Properties Dialog. Now let's set the velocity to $x=-1.5$, $y=0$, $z=1.7$ m/s. Next, we will add calibration ticks to the curve of the ball's motion. Right click on the ball and in the context menu choose the Track / Points command. Now the body will leave markers along its path so we can examine the trajectory. Start the simulation. The ball falls to the table in a parabolic arc, bounces up, and after a few more bounces falls off the table. Stop the simulation  and press reset  to get back to the initial state.

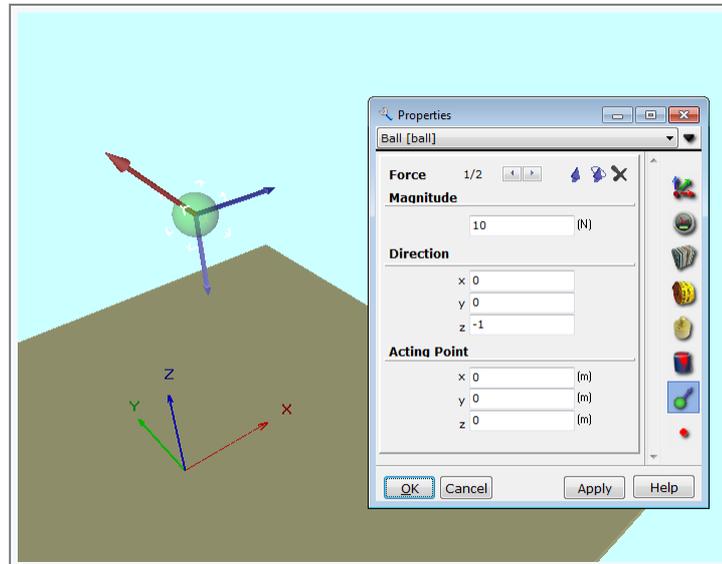
Clicking the  (Force fields) icon brings up the Force Fields window. Here you can set all the external forces acting on the body: gravitational force, Coulomb force, and fluid resistance. It can be seen that gravity is set to constant acceleration and its value is $g = 9.81 \text{ m/s}^2$ as on the surface of the Earth. These are default settings in all new experiments.

Try the experiment with gravitation set to "none". Click on the OK button and see what happens. The ball will move along a constant line with constant speed, and won't fall to the table.

Stop the simulation and return to the original state by clicking on the reset button. Now we will add a constant force acting on the ball. Select the body and click on the force icon



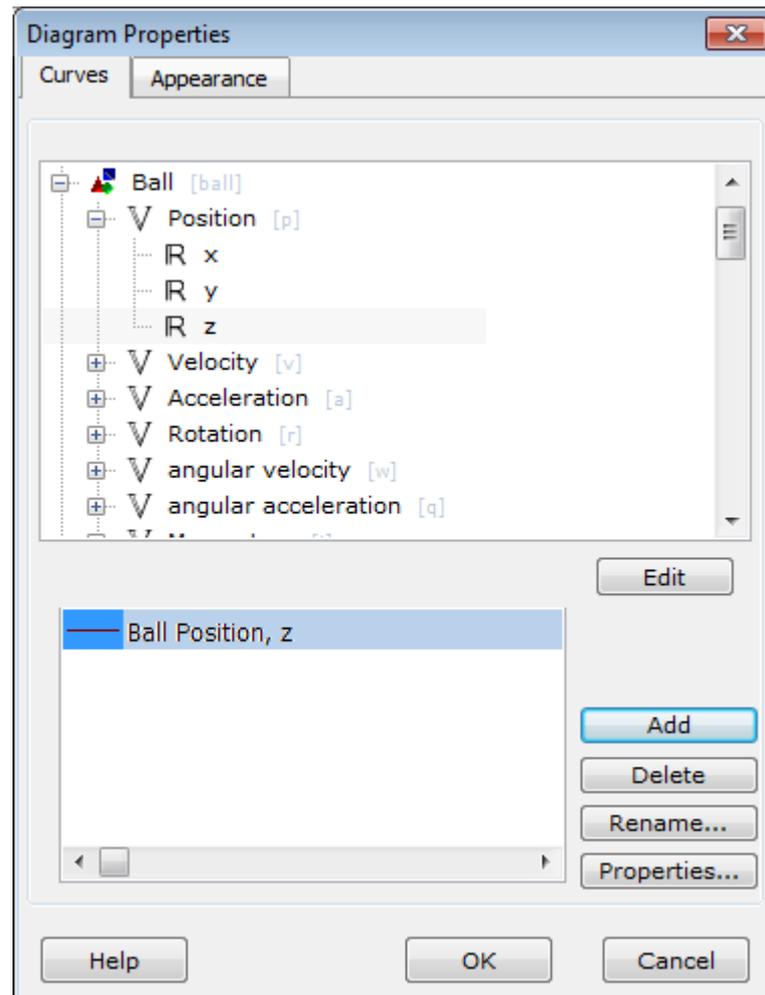
on the dynamics tab of the Object toolbars. In the 3D window you can see the blue force vector originating from the body's center of mass. You can alter the force vector in the same fashion as seen earlier with the velocity vector. Click on the tip of the vector to set its direction, and click on the shaft to set the strength of the force.



Add one more force to the body

Double-clicking on the Force's blue arrow brings up the Properties dialog. From this dialog, you can set the force's parameters. Set the two constant forces with the help of this panel. The first vector should be a force of 1N, and its direction $x = 0, y = 0, z = -1$, pointing downwards. The second vector's force should be 2N, and its direction $x=1, y=0, z=0$, (horizontal).

Start the simulation and observe that the body's velocity is changing linearly, indicating a constant acceleration. The body's motion will stay in a planar zone, because there is no velocity or force in the y direction.



Let's make some diagrams of the vertical component of the motion. Click on the Diagram icon on the Description window toolbar. The diagram dialog appears so that you can define curves.

Choose the Ball/Position /z node and click the New button. This defines a new curve that will draw the z component of the position versus time. Click on the OK button and place the diagram on the Description Window. You can change the axis settings of the diagram by double-clicking.

To compare a theoretical curve to the curve calculated by Newton, you can draw the analytical and the numerical results on a single diagram. First, we'll solve for the analytical solution of this problem.

There is no gravitational force, so only the two constant forces accelerate the body. Since the bigger force doesn't contain a component in the vertical (z) direction, we need only take into consideration the smaller force. Restating the problem, the $F_z = 1.7$ (N) force component acts on the body and accelerates it in the z direction. The object has $v_z = 1$ (m/s) initial velocity and $z = 0.5$ (m) initial position (we set these parameters earlier).

According to Newton's second law ($F = ma$), the acceleration is:

$$a = F / m = -1 \text{ (N)} / 0.1 \text{ (kg)} = 10 \text{ (m/s}^2\text{)}$$

Next, we need the expression that describes the position versus time function of an object

with constant acceleration. This is the function:

$$s = 1/2at^2 + v_0t + s_0,$$

Substituting the values:

$$s = -5t^2 + 1.7t + 0.5,$$

Put a curve for this equation on the diagram. Click twice on the diagram area (not on an axis or curve, because then the axis or the curve dialogs will appear). In the diagram properties window click on the Edit button. The upper part of the window will change, the object tree view disappears, and the two edit fields appear for directly defining the expression to the diagram.

If you click on the curve created earlier you will see the two expressions of that curve. You need to place the new expressions. Click on the new curve, and write in the horizontal axis edit field:

time

And in the vertical axis edit field:

$$-5*time^2+1.7*time+0.5,$$

This format is required for Newton. The format below is perhaps more familiar, but they both define the same equation, $-5t^2 + 1.7t + 0.5$ equation.

An alternative and more elegant way of defining this curve for the diagram is to store the initial value of the ball's position and velocity instead of writing the numerical (1.7 and 0.5) values directly into the expressions. For this we have to use multi-line form:

```
var
  p0,v0 : vector;
begin
  if StartTime = Time then
    begin
      p0 := ball.p;
      v0 := ball.v;
    end;
  result := -5*time^2 + v0[3]*time+p0[3];
end.
```

In this example we have two variables, p0 and v0, which are of the vector type. We store in them the initial value of the ball's velocity and position at the beginning of the experiment, when StartTime is equal to Time. The p0 and v0 variables are then used in the 'result := ...' row. To learn more about writing code, consult the chapter 'Newton Interpreter.'

Using this form of curve definition you can change the position and the velocity of the ball freely. The theoretical curve will always use the altered values and correspond with the simulation curve.

Change the attributes of the earlier curve to differentiate it from the new curve. Select the curve and click on the **properties...** button. On the Curve dialog set the color to yellow and the width to three.

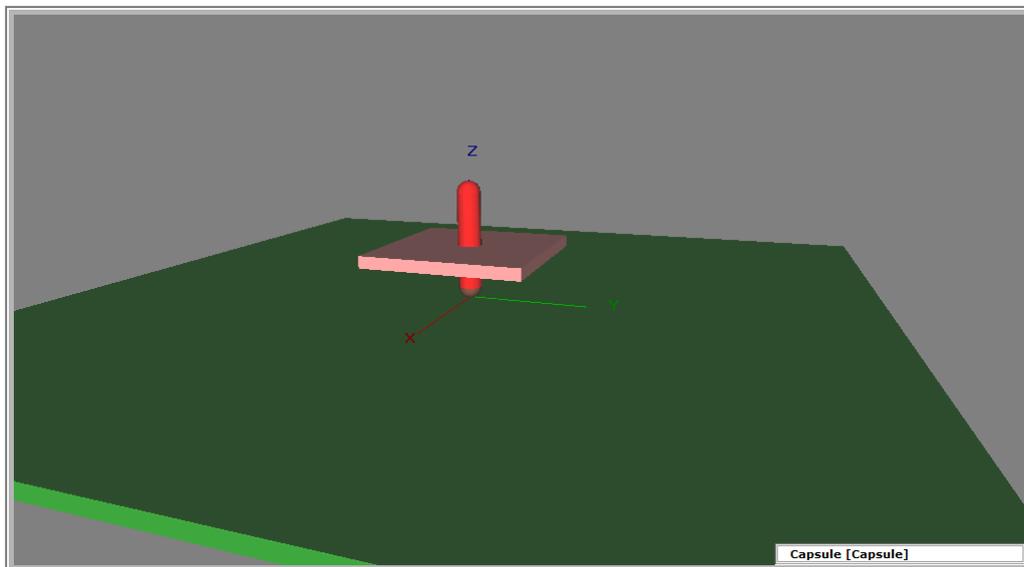
Close the dialogs and start the simulation. If everything has been done correctly, the theoretical curve and simulation curves will exactly overlay each other.

4.3 Fix Joint

In Newton, it is possible to fix two or more bodies rigidly to each other. Now the bodies must move and rotate together and share an aggregate mass and inertia. The motion of this assembly is very similar to that of a simple body except that the material properties of the two bodies can be different. Consider two cubes with different friction coefficients. Put the cubes on the table and push, Repeat with the other cube's surface facing downward. Note that the friction force will be different depending which side is in contact with the table.

In this chapter you will learn how to build a gyroscope from a brick and a capsule rigidly fixed together. The dynamic object you thus create will be called Fixjoint.

1. Get the brick and capsule from the Object bar and place them in the scene. Change their color– the capsule to red and the brick to light blue.



2. Resize the bodies. The radius of the capsule should be 0.03m, its length 0.3m. The side of the brick should be $x, y = 0.4\text{m}$, $z = 0.03\text{m}$.
3. Get a FixJoint from the object bar and place it on the 3D window.
4. Select the three objects with the mouse and press down the  (Link to...) icon. This causes the two bodies to be linked to the Fixjoint. The position of the FixJoint will be the center of mass of the two bodies.
5. In Physical mode, dragging either of the two objects drags the other with it. The two bodies' relative position to each other can only be adjusted in geometric mode, so click on the geometric  icon. Position the two objects according to the picture below.
6. Assign an initial velocity to the gyroscope. Since the bodies don't have independent velocity, only collective, their velocity cannot be altered individually on the Properties window. The collective velocity can be changed on the FixJoint Properties window, at the velocity page. Set to $(-60, 10, 2000)$ -re. Their first two values mean a small change in the exact rotation around the z-axis, which makes the motion of the gyroscope more

interesting.

7. Start the simulation.

4.4 Experiments with spring

In this experiment, a force acts on a body via a (linked) spring. The force of the spring model in Newton is composed of two parts; the first is a linear force in elongation that wants to stretch the spring back to its unstrained length. In the second term the force overcomes friction and is proportional to the velocity of the body. Expressed in an equation:

$$F_s = -D\Delta x - b v$$

Here Δx is the difference of the actual length and the unstrained length, D is the stiffness, v is the velocity, and b is the friction coefficient.

The behavior and use of the spring object will be explained in two examples. In the first, we attach the spring to a stand and link it to a ball to examine harmonic oscillation.



1. Place a spring  and a ball  on the scene clicking the appropriate icons of the object toolbar.
2. Select both the spring and the ball at the same time, and click on the  (Link to...) icon. This links the spring to the ball. Note that you can select two objects at the same time by selecting the first then clicking on the second while the CTRL button is pressed on the keyboard. Another way to link a spring to an object, to click and hold down the left mouse button at the end of the spring, then move the cursor to the object. When the left button of the mouse is released, the spring links to the object.
3. To set the parameters of the spring, double-click on it and work within the Properties Window that appears. Set the Stiffness of the force to 35N/m, and the unstrained length to 0.4 m.
4. Change the Location page of the properties window by clicking on the  (Location) icon. Adjust the z component of position of the spring to 0.8 m.
5. Place the ball under the spring and lift the ball up. You can do this by pressing down the  (move up/down) icon. This constrains the ball movement to up and down only.
6. Go to the inertia page of the properties window and set the mass of the ball to 0.5kg.
7. Start the simulation by pressing down the  button.

Notice that the end of the spring that is not linked stays in rest during the simulation.

Let's include a stand in our experiment.



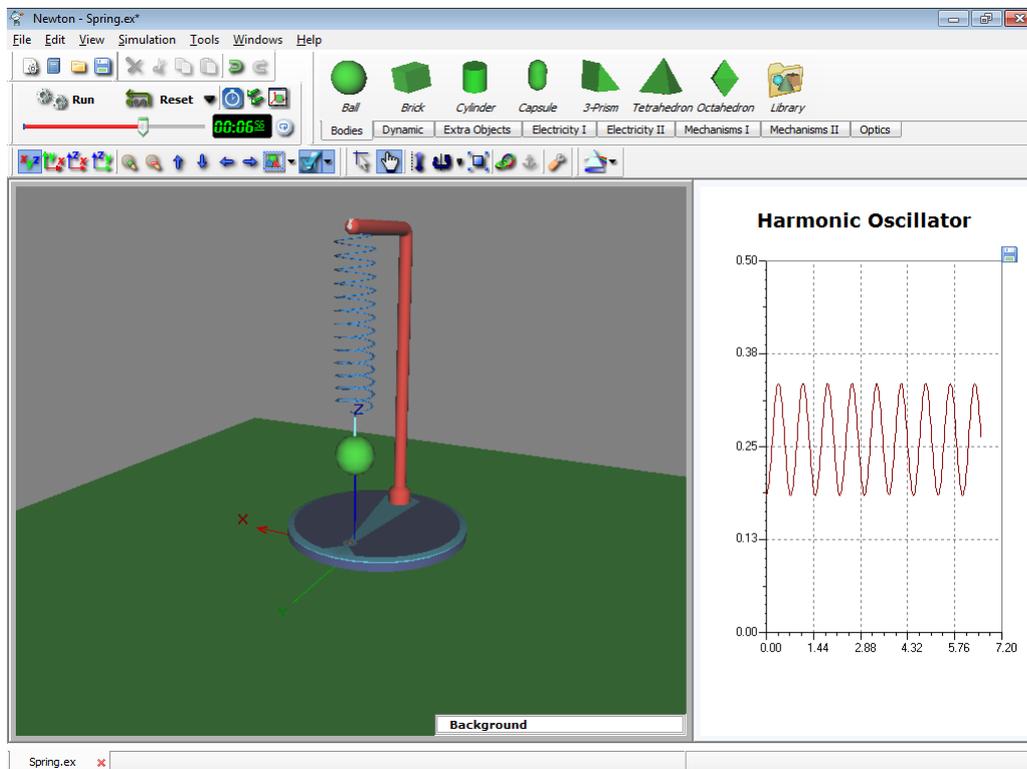
8. Place a stand from the Object toolbar  on the scene.
9. Drag the spring under the Stand and lift it up until it touches the bar of the stand.

10. Anchor the spring to the stand. Select the spring. Then click on the  icon and then on the stand. Moving the stand now will drag the spring with it. To cancel the anchor, first select the body, then press down the anchor icon, and click anywhere on the background of the scene. You can also work with anchors from the Location page of the Properties window.

11. You can change the width of the spring. Press down the  icon and move the cursor to the spring. Adjust the spring width by moving the mouse up or down. Note that this changes only the appearance, not the mechanical behavior.

12. Start the simulation with the  (Run) button.

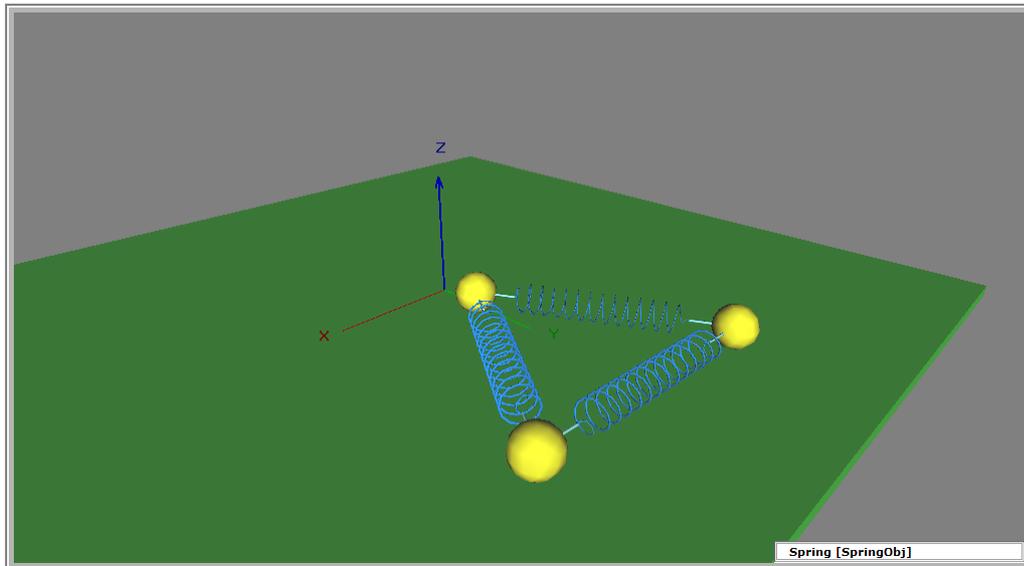
The default setting of damping is zero—there is no damping. You can set the friction coefficient from the spring page of the properties window by double clicking on the spring. Try the value 0.1



The unstrained length of the spring can be set while viewing the 3D window. Lift the ball to the desired unstrained position, click on the spring with the right mouse button, and select the unstrained length command from the context menu. This results in the actual size of the spring also being the unstrained size.

The following example is more complex, using three balls and three springs. (Springs_with3ball.ex)

1. Create a new example and place three balls and three springs on the table.
2. Set the mass of all three balls to 0.1kg and the unstrained length of the springs to 0.6m. Link the balls to the spring as illustrated in the screen shot to the left.



3. Start the simulation.

In this example the ball-spring system is symmetric. You can adjust the unstrained lengths and the masses to try variants of this example.

4.5 Movement along a straight line

Frequently we will want to examine problems where motion is confined to one dimension. There is a constraint in Newton that reduces the six-degree of freedom case to only one. This object is a constraint called **Slider**. It will force the object to stay on a straight line.

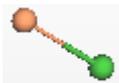
If we link two bodies using a **Slider**, they will move together except for the distance between them, which can change freely. It is as though the bodies are skewered on a shaft and can only slide along its axis.

This constraint is well suited to an examination of one-dimensional motion. In this example, a ball and spring will permit us to examine the one dimensional harmonic oscillation.

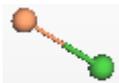
Let's get started making an example (1DSpring.ex).

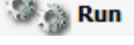


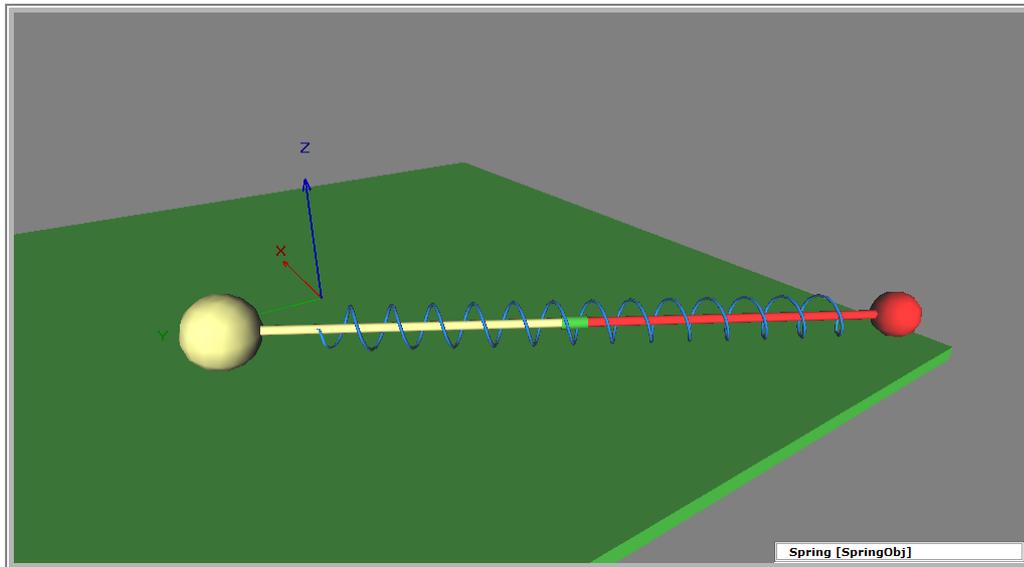
Ball



Slider

1. Place a  ball and a  slider on the scene.
2. Select the ball and change its color to red on the  (Appearance) page of the Properties window.
3. Select both the slider and the ball and click on the  (Link to...) icon, to put the ball on the constraint.
4. Place another ball on the scene and change its color to yellow.
5. Increase the mass of the yellow ball to 2 kg on the  (Inertia) page of the Properties Dialog.
6. Link the ball to the slider; select both and click on the  (Link to...) icon.

7. Place a  (Spring) on the scene and link its ends to the two bodies (Select all together and click  icon).
8. Set the friction coefficient of the bodies to zero.
9. Start the simulation ( Run).

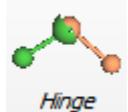


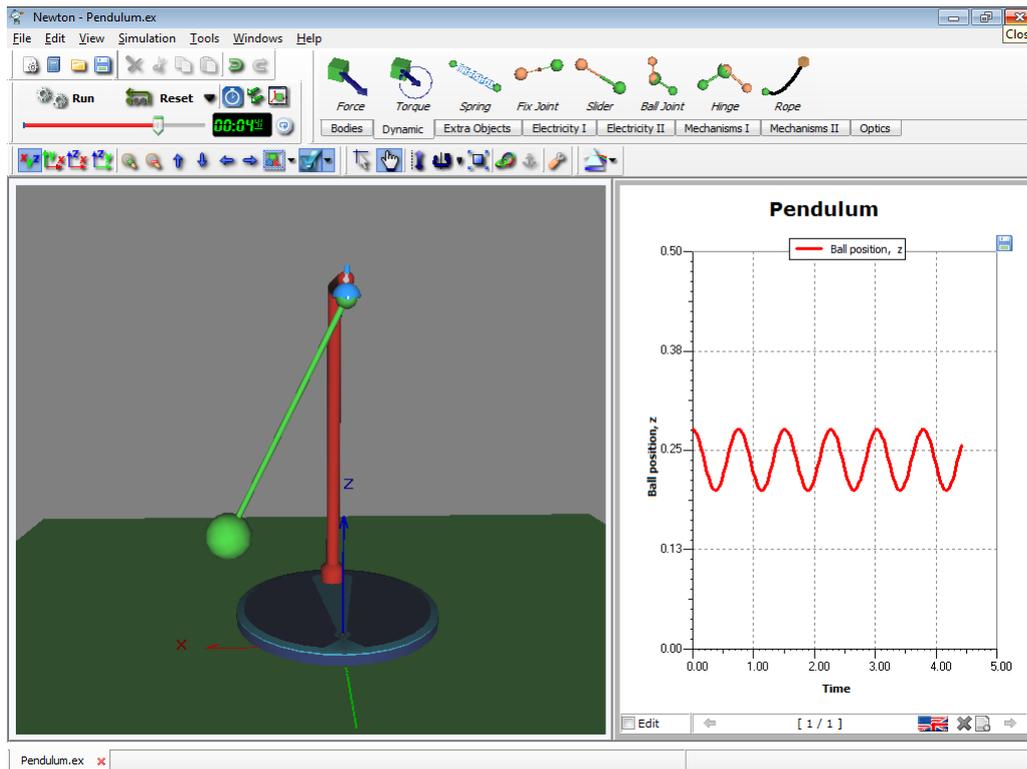
Explore this experiment by stiffening the spring (see the chapter ‘Experiments with springs’).

4.6 Circular motion

The dynamic object called Hinge constrains the body to move in a circular track. If we link two bodies to the hinge, we have modeled the linkage used for the rear wheels of cars.

Let’s build a pendulum utilizing the hinge. (Pendulum.ex).

1. Retrieve a  stand, a  ball, and a  hinge from the Objects bar.
2. Lift the hinge to the end of the stand’s horizontal shaft.
3. Anchor the hinge to the stand. Select the hinge, click on the  (Anchor to...) icon and immediately click on the stand.
4. Select the ball and the hinge and click on the  icon to link them.
5. Switch to geometric mode and adjust the length of the hinge rod by lifting the objects.
6. Return to physical mode and set the initial angle of swing.
7. Start the simulation ().

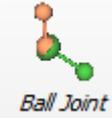


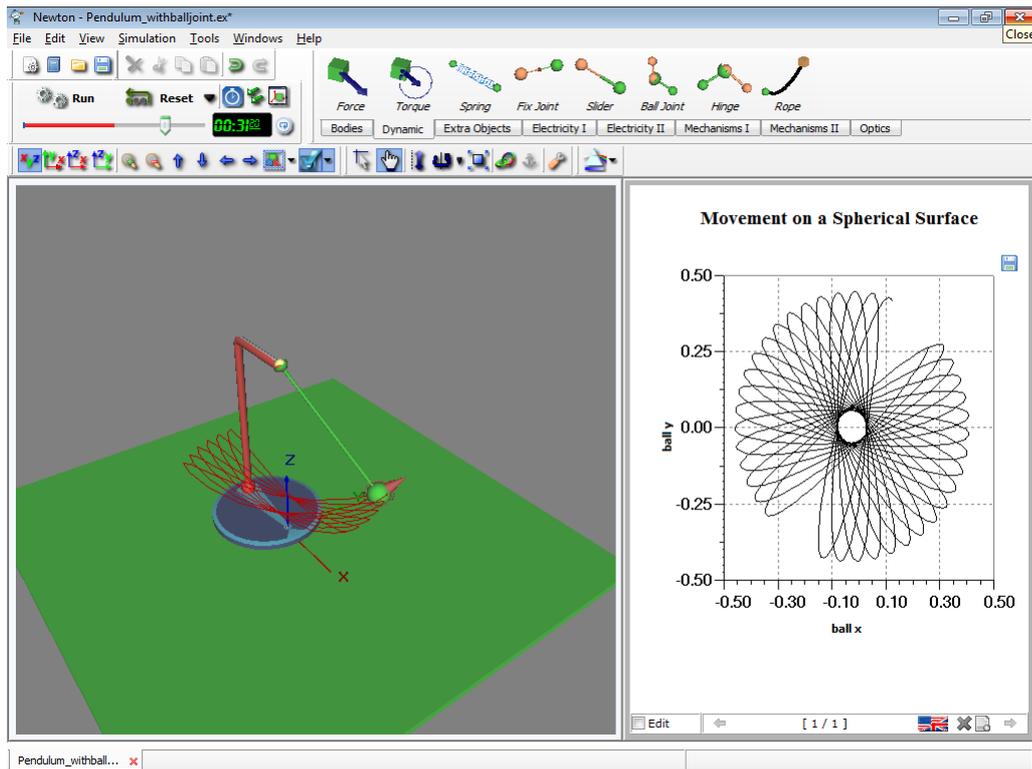
Go to the Properties window where the hinge's parameters are set. You can draw any of these parameters on a diagram, and they all can be reached from the Diagram dialog. In the diagram window above we have presented a curve showing the angle of swing of the pendulum.

4.7 Motion on spherical surface

You can constrain a body to the surface of a sphere by linking the body to a balljoint. A balljoint constrains the ball to remain at a constant distance from a point; however, the body can rotate freely around the joint.

We can make another pendulum, this time using the balljoint (Pendulum_withballjoint.ex).

1. Place a  stand, a  ball and a  balljoint from the object toolbar onto the 3D scene.
2. Select the balljoint, click on the  (Anchor to...) icon, and immediately click on the stand.
3. Select the balljoint and the ball and click on the  to link them together.
4. Switch to geometric mode to adjust the position of the ball. Place it under the balljoint.
5. Switch back to physical mode and drag the ball to its initial position.
6. Set the initial velocity of the ball. If you don't do this, the swinging ball moves in a plane. Now we want the plane of the swinging ball to rotate. To achieve this, assign a velocity to the ball perpendicular to this plane.
7. Start the simulation by clicking the  (Start) icon.



From the Properties Window, you can set all the balljoint parameters to exact values. Any of these parameters can be plotted as curves on the diagram. The picture above graphs the ball's position in the x–y plane.

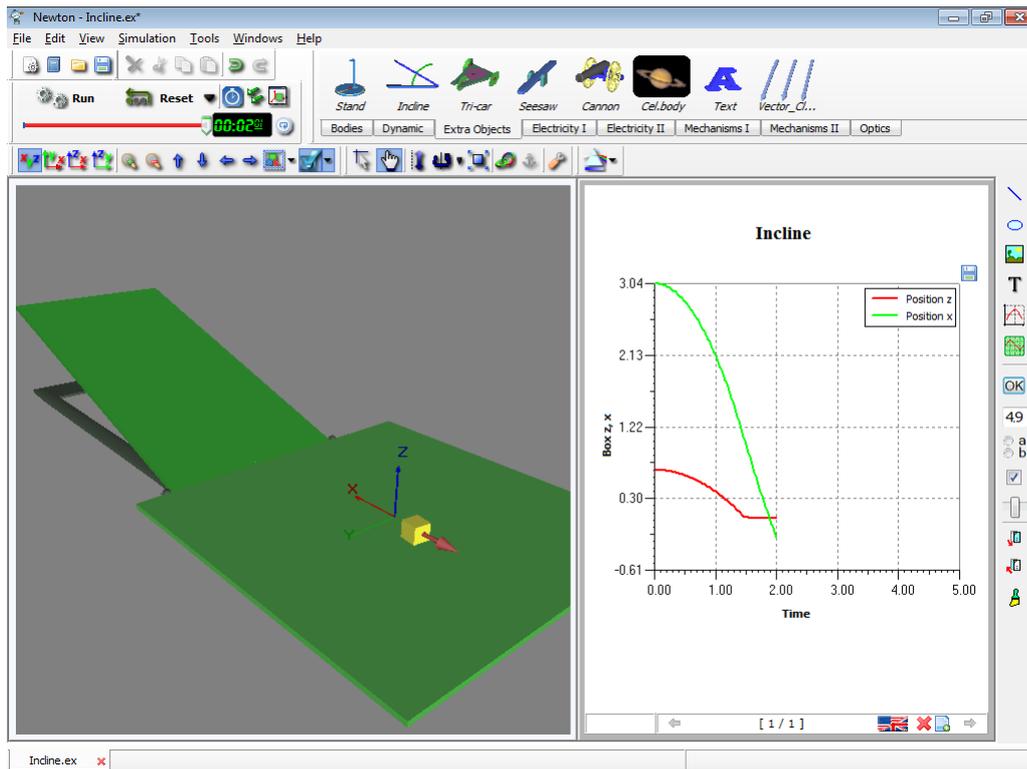
4.8 Incline

Extra objects consist of simple bodies and dynamic objects, which often appear in experiments. You will find these on the object bar. The incline is such an object. It consists of a rectangle, a hinge, and an incline-base. It has its own Object Properties window where the angle, the friction coefficient, and elasticity of the incline can be set.

Let's build an example using the simple incline (Incline.ex).



1. Click on the icon *Incline* in the Object toolbar.



2. Set the table next to the incline in such a way that objects rolling down the incline will land on the table.
3. Set the angle of the incline by moving the flat of the incline.



4. Add a brick  to the experiment.



5. Change its color from the  (*Appearance*) panel.
6. Pull the brick up the incline until its bottom surface fits onto the surface of the incline perfectly.
7. Set the friction coefficient. Click twice on the body, the incline and the Table, set the values required on the Object Properties window.
8. Start the simulation by clicking on the  (*Start*) button.

4.9 Planetary motion

Up to now we have only made experiments in the gravitational force field of Earth. Using Newton, it is possible to set the gravitational field so the bodies attract each other according to

$$F = G \frac{m_1 m_2}{r^2}$$

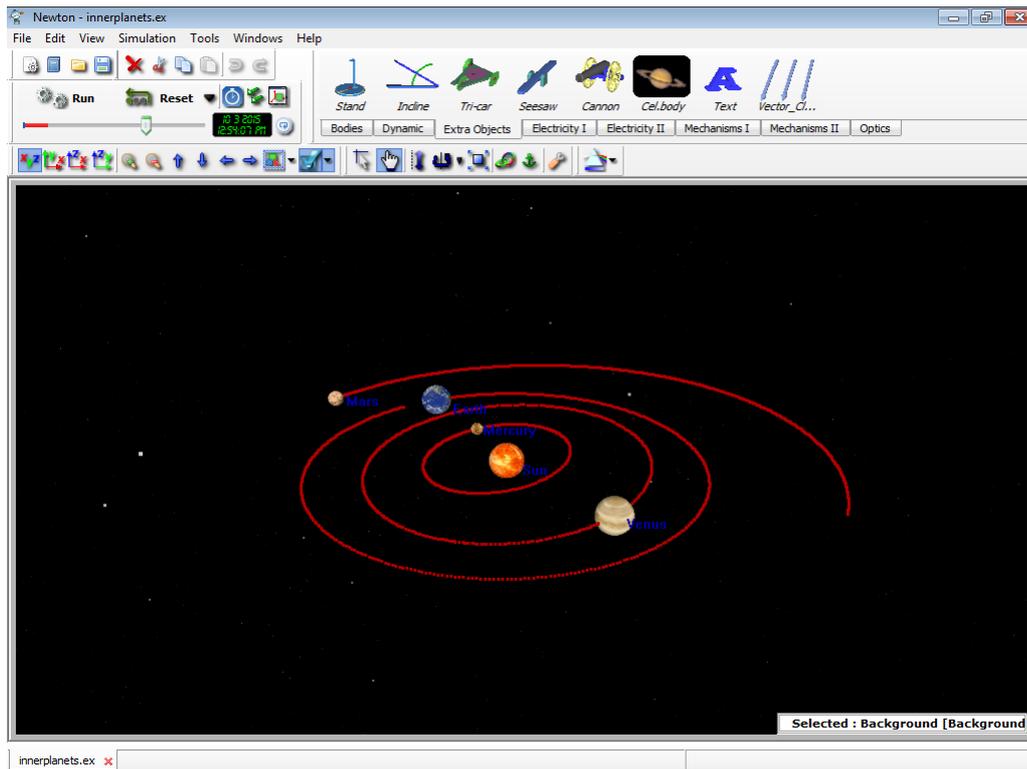
Newton's gravitational law, . This will allow us to demonstrate planetary motion. In this chapter we will show the detailed steps required to simulate our Solar system (InnerPlanets.ex). This simulation is quite different from those seen up until now, because the values of distance coordinates and time magnitudes are vastly larger. Try to imagine the huge distances that separate the planets, and the time scales of their periods. The main task in creating this experiment is to set the magnitudes of time and space parameters.

1. Create a new example and set the table visibility parameter to false.
2. Click twice the background of the 3D window, in an open area. The Properties window appears—select the starry night sky.
3. Set the Dimension value to 10^{12} (type: 1e12) in the View menu *3D window settings*  dialog. This setting affects mouse movements in the 3D window. Bigger values make the same mouse movement cover far greater distances in the virtual space. You can travel millions of virtual kilometers with a single mouse gesture.
4. Set the gravitational force to planetary in the Simulation menu *Force fields*  dialog.
5. Change the unit system to astronomical by selecting it from the combo box in the Simulation menu **Units** dialog.
6. In the Simulation menu Setting... command invoke the Settings dialog, set the virtual time to one day, and the time step to 0.01 day.



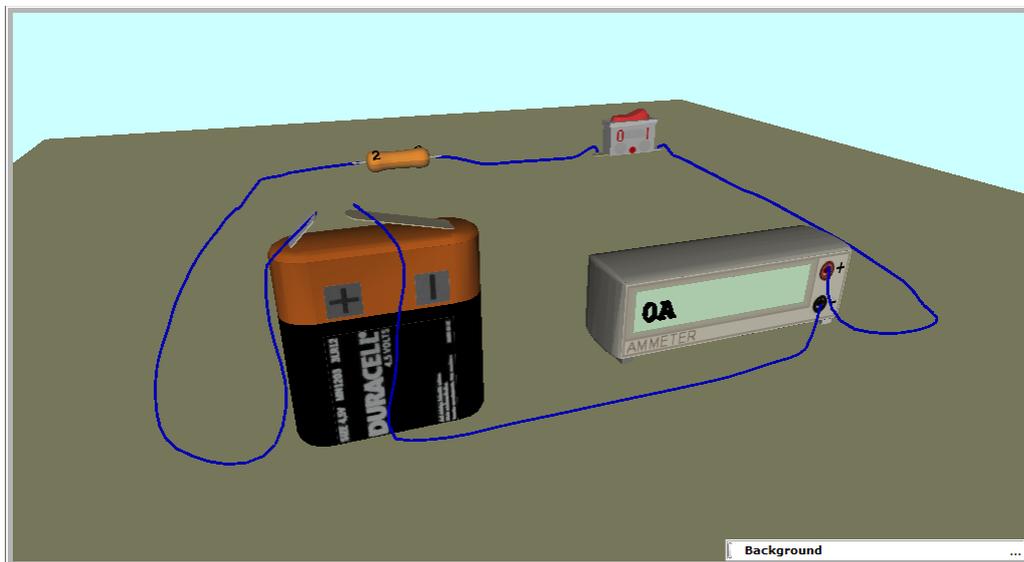
7. Click on the *Cel.body* (Planet) icon in the extra objects tab on the object bar.
8. Select the sphere object, and double click on it to bring up the Properties Window. Choose one of the planets or the sun from the *Object name* combo box. Newton automatically sets the astronomical body's real properties.
9. Insert as many objects as you want (don't forget the Sun), repeating the previous step.
10. The two trackbars on the Properties window are useful for scaling the size of the Sun and the planets. Note that this scaling doesn't alter the mass or the density parameters. It's meant only for improving the view of the solar system.
11. On the bottom of the panel you can set the Date, which will affect all of the object positions.
12. Choose a good location in the universe where you can see all the objects, and run the simulation.

Note: During editing in this experiment, it is possible to inadvertently get inside an object while moving the camera, Of course we can't find that object because from the inside it is transparent. If this happens, use the camera positioning controls or the camera properties window to get out of the object.



4.10 Examination of DC circuits

In this example a simple series circuit is made with a resistor of 2 ohms, an Ampere meter and a 4.5V battery.



To create this circuit do the following.

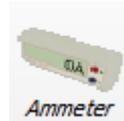
1. Click the Electricity I tab on the Objects toolbar where the basic electric parts, such as resistor, lamp and switch can be found.



Resistor



Switch



Ammeter



Battery 4.5V

2. Place a Resistor resistor, a Switch switch, an Ammeter Ampere meter and a Battery 4.5V battery in the 3D window.
3. Connect these parts with wire.

To connect the parts, move the cursor over an appropriate pin node until a small drawing pen icon appears. When this pen appears, click the left button of the mouse, draw the wire, and left click again at its endpoint. Note that you can also draw the wire by clicking and holding down the left button and then release when the cursor is over the appropriate endpoint. The color of the wire changes to white when the cursor is over the endpoint.

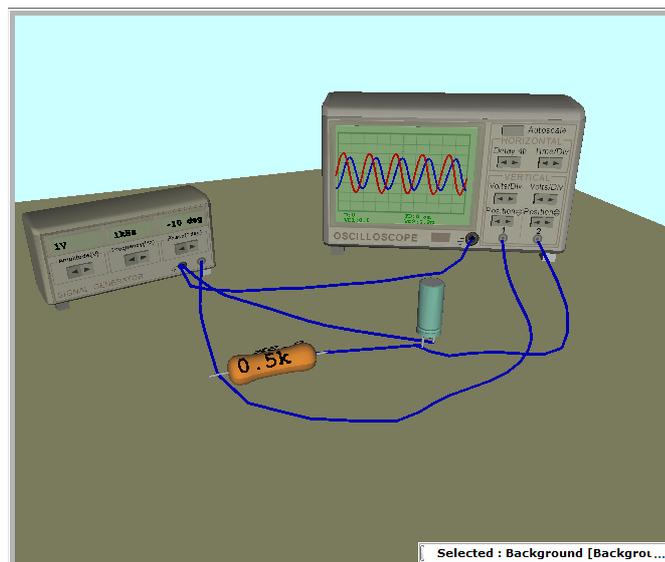
Note that while the drawing methods described above are suitable for drawing with the mouse, in the case of digital interactive boards or tablet computers usually only one of these methods can be used.
4. To set the required value of the resistor to 2 Ohms, double-click the resistor, enter 2 in the Resistance field and press OK.

Now we have completed our simple circuit. To test its operation, move the cursor over the switch and change the switch by clicking on the button. The current meter will then show $4.5/2 = 2.25A$ according to the Ohm's law.

4.11 Examination of AC circuits

With Newton you can also build and examine AC circuits.

In our example we will create and examine an RC circuit using the sinusoidal Generator and the Oscilloscope in Newton.



Resistor



Capacitor

1. Place a Resistor resistor and a Capacitor capacitor from the Electricity I toolbar, then double-click on these parts and set their values to 500 ohm and 1uF respectively. Click the

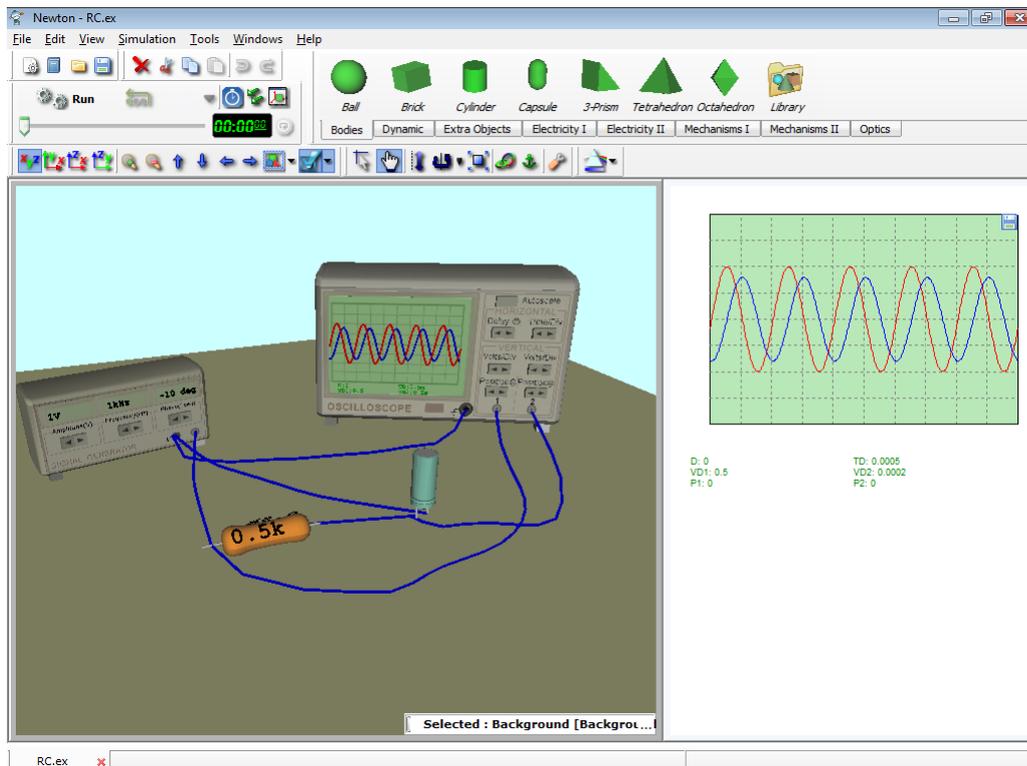


Electricity II tab, where the *SignalGen.* generator and the *Oscilloscope* oscilloscope can be found.

2. Place a Generator and an Oscilloscope in the 3D window. Double-click on these instruments and set the Generator's amplitude to 2V , the frequency to 500Hz and the Time/Div of the Oscilloscope to 0.0005s.

3. Draw the wires. Connect the ground of the Oscilloscope and the ground of the Generator. Connect one end of the resistor to the output of the Generator and the other end to the capacitor. Connect the other end of the capacitor to the ground of the oscilloscope. Now only the two channels of the oscilloscope are to be connected. Connect one of them to the common point of the resistor and the capacitor, and the other one to the end of the resistor that connects to the output of the generator. The respective waveforms will immediately appear on the Oscilloscope.

4. You can also place the waveforms in a diagram in the Description Window. Click on the edit checkbox of the Description window and then the Oscilloscope icon on the vertical toolbar of this window. The diagram will be attached to the cursor, press the left mouse button to place it. Clicking on and drag a sizing handle to resize it.



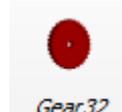
Both on the Oscilloscope and on the diagram the output voltage of the generator and the voltage of the capacitor are displayed. The differences in the amplitude and in the phase are clearly visible.

4.12 Mechanisms

Use the Mechanisms tab on the toolbar to make gear systems. Make a system consisting of a 64-cog and a 32-cog gears, driven by an electric motor.



1. Place a stand on the table, by clicking *GearStand* on the Mechanisms toolbar.



Place a *Motor* motor, a *Gear64* 64 and a 32-cog *Gear32* gear from the Mechanisms toolbar.



2. Insert an axle into the stand. Click the *Axle* icon on the toolbar. The axle will be placed onto the table. Move the axle towards the stand. It is placed automatically when it is close enough to the middle of the stand



3. In a similar way place the 64-cog *Gear64* gear in the middle of the axle. If the gear is moved close to the middle of the axle, it will be attached automatically.

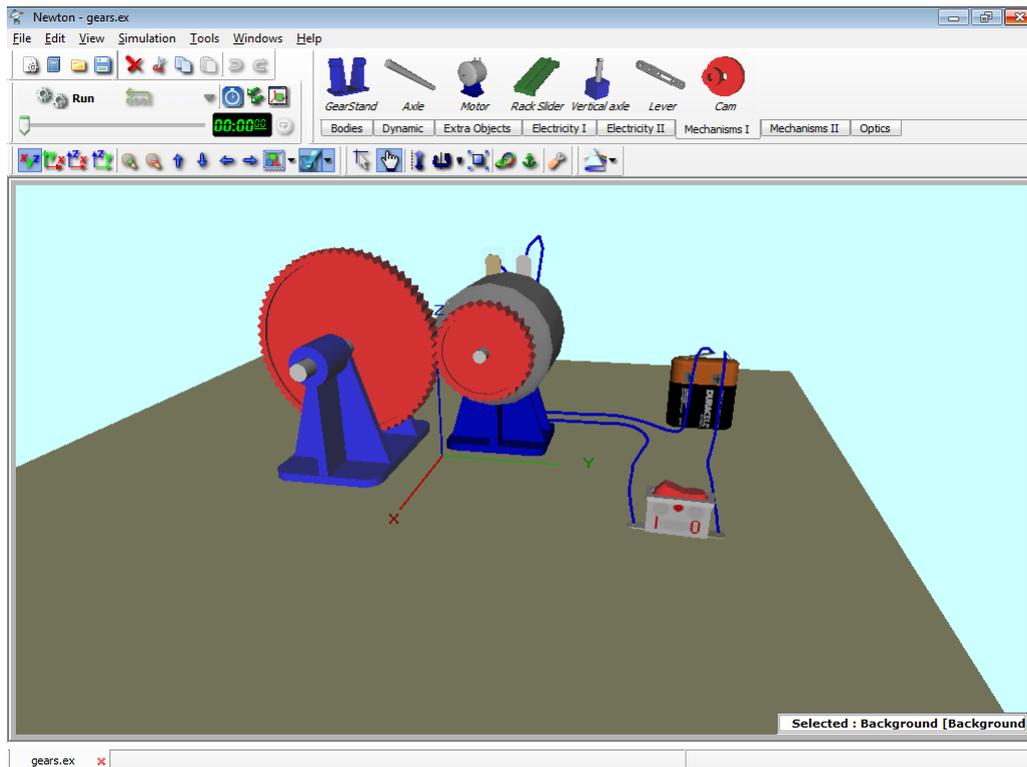


4. Connect the other 32-cog *Gear32* gear to the motor.

5. Join the two gears. If the cogs do not fit, you can turn the gears a bit with the help using the mouse. Move the gears by dragging the stand. It is easier to join the gears if you switch to planar view (e.g XY).

6. In order to drive the gears with the motor, connect a switch and the battery of 4.5V to the motor.

7. Start the simulation clicking on the switch.



4.13 Optics

Another interesting part of physics is optics. With Newton it is possible to set up different optical systems, and show a realistic view with Newton's raytrace engine. The optical elements are under the Optics tab on the Object bar. The building blocks are: different lenses, mirrors, prism, ray emitter, canvas



In this example we will create and examine an optics system with converging lens and canvas.

1. Place an **optical bench** on the scene, by clicking to the *Optical Be...* icon.

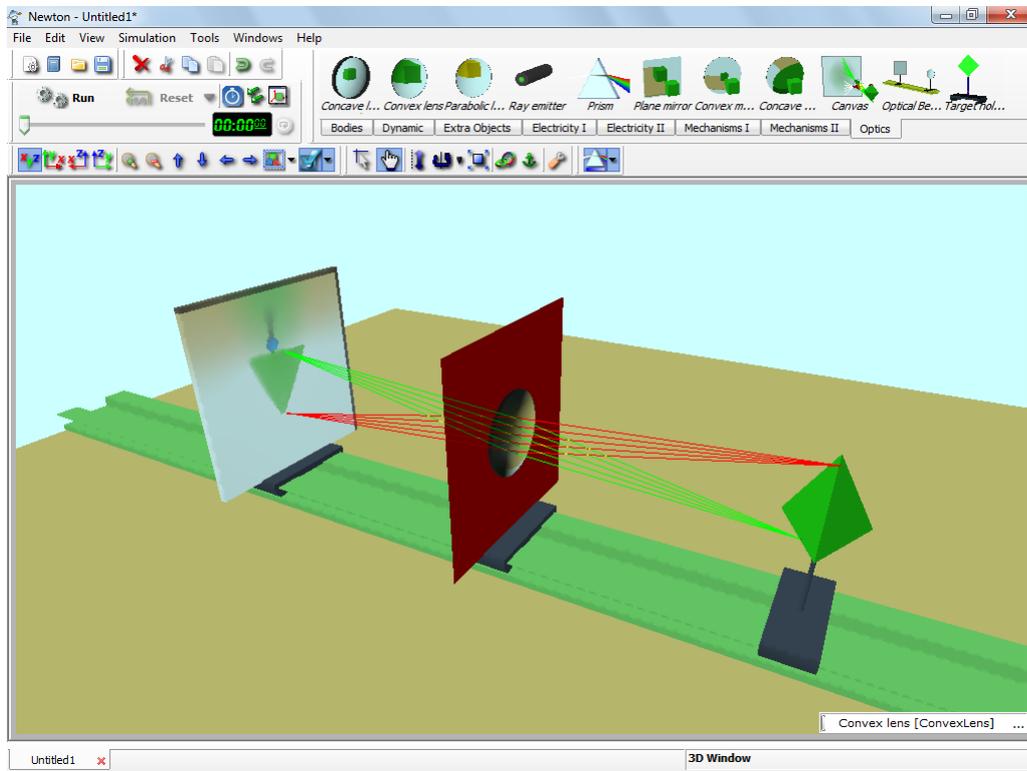


2. Retrieve a **Convex lens** *Convex lens*, a **canvas** *Canvas* and a **target holder** *Target hol...* from the Optics toolbar.
3. Put the lens, the canvas and the target holder to the optical bench, by moving the lens etc. towards the optical bench, it is placed automatically when it is close enough to the bench.
4. Place a body (for instance tetrahedron) on the scene from the bodies toolbar. Put the body on it, by moving close to the target holder. The body will be automatically attached, when it is close enough.



You can still move the objects on the bench, with the mouse.

5. Click on the **Ray trace icon**  to observe the optical example.



There are three types of ray tracing method.

- Ray trace after changing camera view (fast) 
- Ray trace optics element only (medium) 
- Ray trace always (slow) 

4.14 Problems

This chapter shows how to start with an existing example file and transform it into a new problem file.

Just as with example files, problem files contain 3D window(s) in which the problem is illustrated, and description windows. Problems can be presented using both types of windows. You may also use the description window to present some hints or even a solution to help the problem-solver.

We will now alter the free fall example into a problem. The task for the student will be to answer a few questions. Follow the steps below:

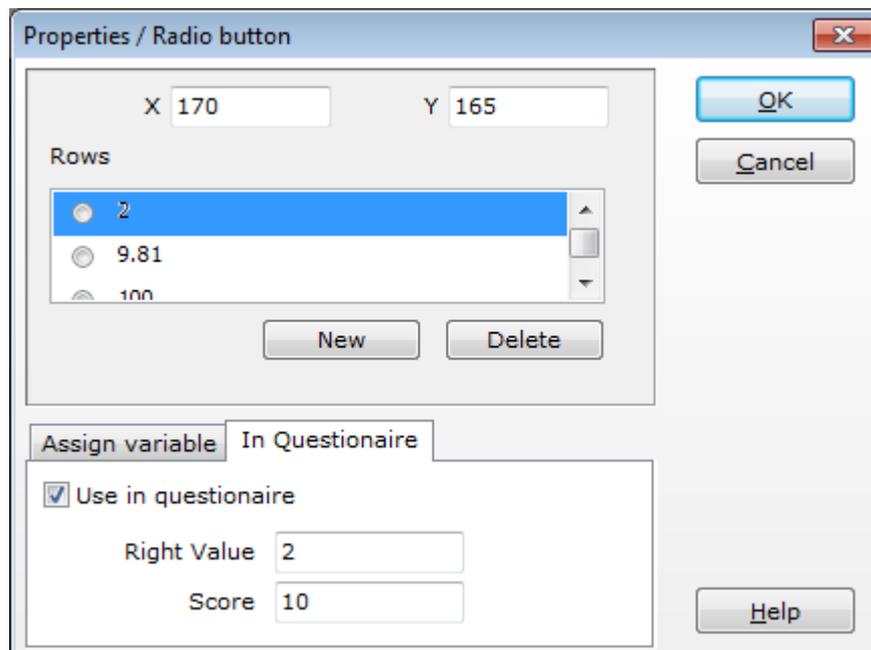
1. Open the Freefall.ex file.
2. Delete all the text except the title.
3. Place this text below the title :

'A body is dropped from a height of 2 meters.'

In the first question (problem a) the student has to choose the right value from the possible answers. The text of the question is:

Find the acceleration of gravity on the earth!

We'll use  (*radio buttons*) to make this a multiple-choice problem. You will find radio buttons on the description toolbar. Place one on the description window and double click on it. The radio button properties dialog appears with which all the settings can be adjusted. Enter three answers into the row list: 2, 9.81, 100. One of these has to be the right answer. You must tell the program which answer is correct. Select the Right value field and write the line number holding the **right value**. Newton permits you to calculate scores—an important feature when you create a set of problems.



4. The second question (problem b) will be the calculation of the time the ball takes falling to the floor. The problem text is:

Find the time when the ball reaches the floor!

Use the  (*editfield*) element for this kind of problem. Click on the icon in the toolbar, put it into the description window, and click twice on it. In the properties window, chose the **Use in questionnaire** option to enter the right value (0.64 second in this problem), and assign a tolerance of 0.03. (This means that the acceptable error is $0.03/0.64 = 5\%$). Finally, enter the point value for scoring this problem.

5. The third task (problem c) is to solve a yes-no question.

The problem text is:

If the answer is right, check the box!

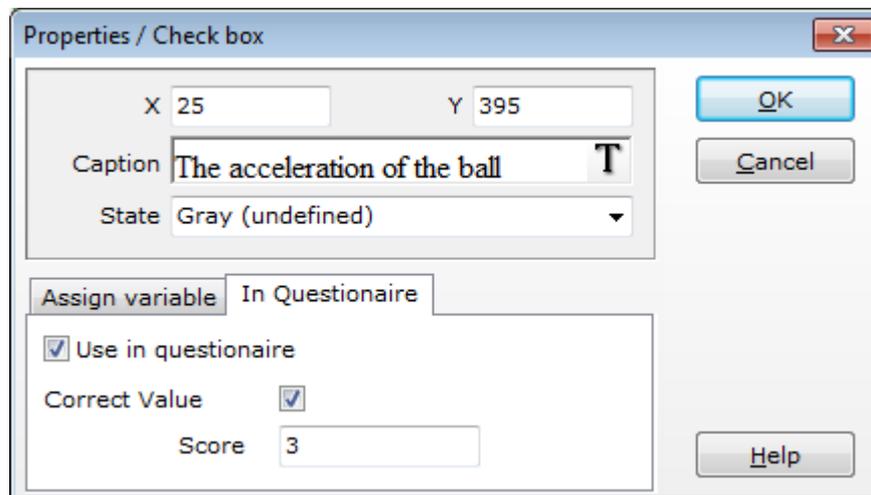
For this multiple choice test, the best descriptive element is the checkbox component.

Click on the  icon on the toolbar and place it onto the description window. Let's give this a caption that asserts a questionable truth. Click twice on the checkbox and its

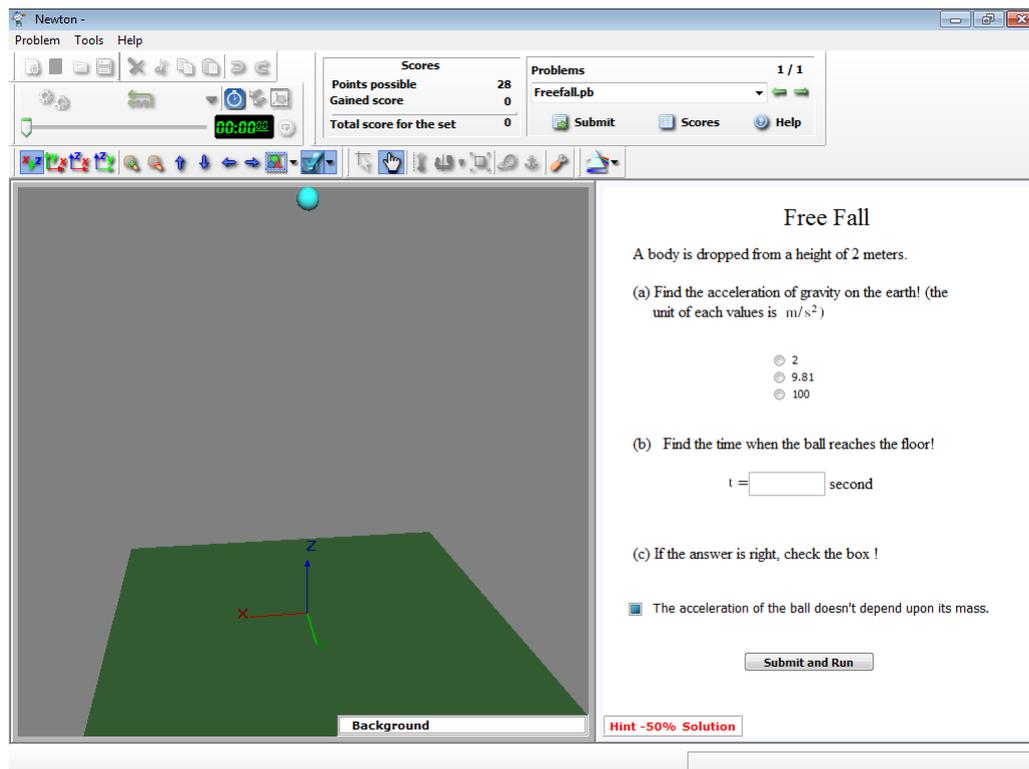
properties window will appear. Enter the caption:

The acceleration of the ball doesn't depend upon its mass.

Check the right value of this statement to true, and enter the point value for scoring this problem.



6. To check the results, place a button by clicking on the  icon. Click twice on the button and its properties window will appear. Here we can set the caption, and size, position, and what is important for us now: We can set actions what should happen when the button clicked. Select "Check problem" from the combo box on the bottom of the page, click add, then "Run simulation" and click add again.
7. It is possible to give hints to help the student solve the problem. Click on the  (*Create new Page*) icon at the bottom of the description window. Each time you click on this icon, a new page is created. It is possible to delete the page currently on-screen with the  (*Delete Actual Page*) icon. You can move among the pages with the  icon. To tell Newton that the page contains a hint, you have to change the type of the newly created page. Click on the description window with the right mouse button and in the context menu choose *Set page as/Hint* command. Newton's scoring system allows you to define a penalty when a student needs a hint. His/her score will be reduced by a given percentage. To set this number, click on the description window with the right mouse button, and choose the *Hint Score Reduction...* command in the context menu.
8. It is also possible to provide the full solution. However, if the student looks at it, her score on this problem is set to zero. Create a new page , write the solution, and right-click on the description window. In the context menu choose *Set page as/Solution* command.



9. When you have completed the problem file, you can save it. In the Save dialog, change the filter of the file type to 'Newton problem file *.pb'.

When you next reload the file, Newton will determine automatically that it is a problem file and switch to problem solving mode. All editing operation will be prohibited and in place of the Object bar, Newton will present the Problem control. The student's answer can be entered for the interactive elements, and hints and solutions can be fetched using the two buttons of the status bar of the description window. To test a value entered by the student, click on the Submit button on the problem tool bar.

To switch back to editing mode, click on the Problem menu Edit command. Entry to the Edit mode is password protected so that students will be prohibited from checking their answers or otherwise manipulating the test. For all problems there is only one password. Its default value is 'Newton', and, of course, you can change it. If you forget your password, reinstall Newton (be careful not to overwrite your own experiment and problem files) to set the password again to the default.

If you have a number of problem files covering the same material, you can bind them into a set of problems. The resulting problem set can be used for student testing. You can do this clicking on the *File/Problem Set Manager...* command, which will invoke a dialog where you can set up the details for the problem set. The extension of a problem set file is '*.pbs'.

Part



V



5 Usage of Newton in detail

In this chapter we will introduce and explain Newton's tools and their use. We will guide you through the objects that can be used to build your experiments and explain their functionality and properties. We will show you how to easily and quickly use objects to create accurate, stable and fast simulations.

You will also learn how to create powerful description windows using diagrams, explanatory texts, and interactive elements. We will demonstrate making output files formatted as a vrmf model file or as an avi video file.

To create a new experiment click on the New  icon on the Standard toolbar or on the New command in the File menu. You can save the current file with the Save  icon or the Save command in the File menu.

5.1 Objects : Newton's virtual building blocks

We will typically use several elements to realize our experiments; these elements are called **Objects**.

The Objects can be classified into the following groups:

- Simple body (e.g., ball, brick, octoeder)
- Dynamic objects (e.g., force, spring, joints)
- Extra objects (e.g., incline, seesaw, matchbox)
- Environmental objects (e.g., table, background, camera)
- Supplementary element (e.g., track, velocity vectors, points)

The first three groups can be found on the Objects toolbar. This bar has three pages, one for each group. You can switch among them by clicking on the tabs. Click on an icon to add a new object to the scene. Newton will place it temporarily in the middle of the window.

The supplementary elements cannot exist unless incorporated into one of the simple bodies or extra objects. The track (which displays the trajectory of its body) is an example of this kind of object. Its properties can be manipulated by the properties window or by the context menu of its 'parental' objects.

The environmental objects generally play a passive role in the experiment. They make the scene attractive and aid in editing operations. When you create an experiment from scratch, Newton automatically provides these (environmental) objects.

All objects—except the supplementary ones—have their own **identifier** and **name**. Extra objects may contain several simple bodies and dynamic objects, so each part has its own name and identifier. The identifier and the name are not the same! Each object has a unique identifier, which is not used by the others. The identifier is a combination of a short character string, (generally a short English word or abbreviation), and a number. The identifier is used to define a curve for the diagrams, where we have to identify an object and their parameters unambiguously. Because these identifiers are often placed in mathematical formulas, we should confine ourselves to using only the letters [a..b] and [A..B] and the numbers [0..9]. The first character of the identifier cannot be a number. Object Identifiers in Newton are not case sensitive—redball22 and RedBall22 are interpreted as the same. The name of an object, on the other hand, can be anything. It may contain several words and more than one object can

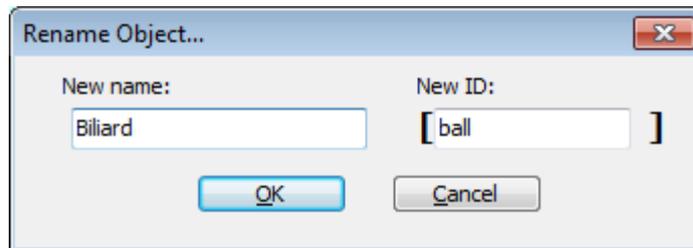
have the same name. In the program, the name and the identifier generally appear beside each other, as:

name[identifier]

e.g.

Biliard Ball [ball]

When creating a new object, Newton will automatically assign it a default name and identifier. If you move the mouse over the object, the default name and identifier will appear in the status bar. To alter the strings, use the Edit menu/ Rename... command.



Now let's go through the objects according to their category.

5.1.1 Simple bodies

The most common building shapes can be found on the Bodies page of the Object Bar. In Newton, we use the term body for any object that has material. This kind of object has mass, density, and inertia properties; the bodies can collide and slide with each other; may have charge; and are affected by gravitation. Simply put, these are the commonly known bodies of our ordinary, real world. Newton offers the following basic shapes:



There are still more body models in Newton's '**models**' folder. These files have a '.o'



extension. To browse these models, click on the library icon on the bodies page to invoke the model dialogs. Select a body model and click the OK button to create an instance of that model in the 3D window.

If Newton doesn't have the body shape model you need, you can use 3D modeling software (available from other vendors) to create the model. The program you choose must be able to export models to the prevalent standard, the so-called VRML 2.0 (Virtual Reality Modeling Language 2.0).

Pay attention to these aspects of model creation:

The body should be a one piece, continuous, closed-surfaced shape. It doesn't matter that the vrmf file may contain several shape elements, but the elements together must comprise a polygon with a one piece, continuous, closed-surfaced shape. In addition, the following requirements must be respected:

- The normal vectors of each polygon face must point outward.
- There must not be any duplicate faces.
- All face sides must connect to another face.

If these requirements aren't met, the volume and mass calculations cannot be executed or will be wrong. There is no way for a program to convert an unclosed surface to a continuous, closed-surface body.

The imported body automatically gets default material properties, which can be changed later.

In some simulations, bodies collide with each other, which in general requires a great deal of processor resources and can significantly slow down the simulation. The special shapes—ball, brick, cylinder, capsule, etc.— are computed differently, and their collision calculations execute faster and with greater accuracy. Collisions involving the other bodies are calculated on the basis of the location of the polygons, and the required calculation time is proportional to the square of the number of faces. When using these bodies it's best to reduce the number of faces. Wherever possible, we can use passive elements in the simulation, which don't collide. For passive bodies, reducing the number of faces is not so important because only 3D drawing slows down, and drawing is generally so fast (aided by the PC's graphics card), that the slowdown isn't noticeable.

5.1.2 Dynamic Object

In Newton the constraints and forces acting on a body can be defined by dynamic elements placed in the 3D window and linked to the bodies. These objects, although appearing in the 3D window, don't have material properties and cannot collide with other bodies. Their shape only illustrates their functionality and helps to understand the configuration of the experiment.

These dynamic objects can be used in our demonstrations:

- force, torque
- spring
- constraints: ball joint, hinge, slider
- fix joint

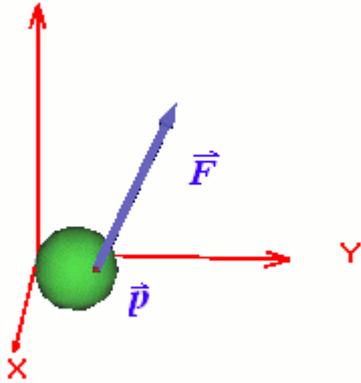
Every dynamic object must be attached to one or more bodies to have an effect. The constant force or a torque can be assigned to only one body, whereas the springs and joints can control the motion of two bodies simultaneously. These objects have two connectors, but they also work with one connected body; in this case, the free connector will be fixed to its current position. The fixjoint, which clamps bodies together, requires a minimum of two, and can accommodate an unlimited number. The glued bodies will behave as one during the simulation.

By default all of the dynamic connections are visible and appear in the 3D window. You will notice “symbolic rods” between the centers of mass of the body and the dynamic object. It must be emphasized that this is a virtual rod, so, for example, it has no mass property and is unable to collide. The rod only shows the relation between the two objects to make the scene more understandable. You can hide a symbolic rod by right clicking on it and unchecking the **visible** command in the context menu.

In the next section, we will examine the functions of these elements and get a better feeling for their use.

5.1.2.1 Constant force

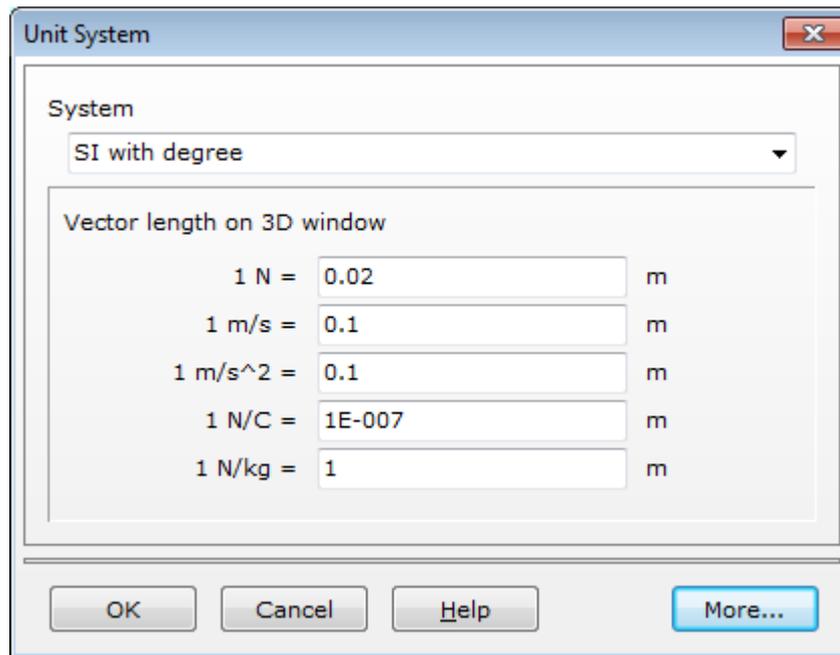
According to Newton's second law, a constant force will accelerate a body. To create and attach a new constant force, select the body and click on the force button on the object toolbar (dynamic tab) . A blue vector, starting from the center of mass of the body, appears in the 3D window.



You can alter its direction and magnitude using the mouse (see Vector editing chapter), or by adjusting the related parameters on the properties window's **force panel**. To place this property, click twice on the blue force vector in the 3D window.

You can assign more than one force vector to a body. The program computes the resulting net force according to the parallelogram law.

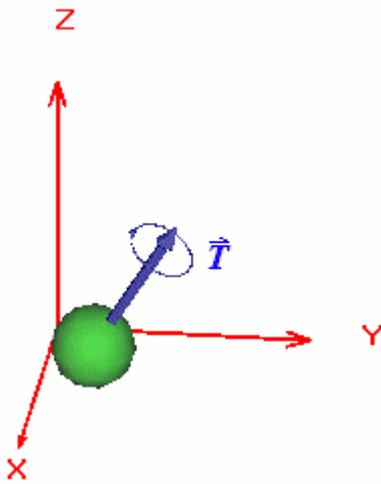
By default, the point at which the force acts is the center of mass, but this isn't a requirement. It can be attached to any **point object** (from the supplementary object group) that was assigned previously to the body, and can be placed anywhere inside or outside of the body or on its surface. To place the acting point of the force outside the center of mass, you should first create and reposition a point object, then select it and click on the force object in the object bar. Note that you can also change the position of the acting point on the force panel. Using this method, Newton will automatically create the acting point and make it the currently selected object. You can read more about point objects in the Supplementary objects chapter.



There is one vector visualization issue left to discuss. How big (or little) should the force appear on the screen? This question arises because the size of the force is expressed in [N] (using the SI system), while the representation of the force vector should have a length measured in [m]. We need a rate number with which to multiply the size of the force to get the length for screen presentation. On screen, the force vector will be represented by a blue arrow in the scene alongside the body upon which it bears. Multiplying all the vectors with the same rate number makes sense, because the force vectors will maintain correct proportion to each other, their size can be compared on the scene, and vector addition can easily be visualized. But the rate number cannot be arbitrary: use too big a rate and the screen will be overgrown by the vectors; or use too small a rate and the vectors will be hardly noticeable or hidden by the bodies. You can change the rate number of forces and other kinds of vectors—as long as the vector units are not length type. Velocity and acceleration, for example, can be used with a rate number.

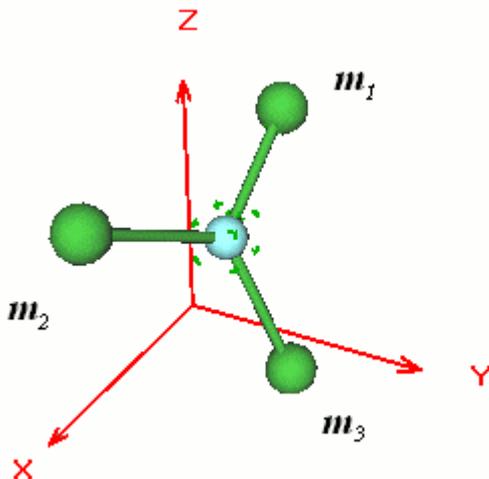
On the **Unit dialog** (Simulation/Unit command), besides setting the unit used in Newton dialogs, you can set the rate number of three parameter fields related to the vectors: force, velocity, acceleration. These incorporate the rate number, which can be altered here. If you enter a value two times bigger into the force editfield, the force vectors on the scene will double in size.

5.1.2.2 Torque



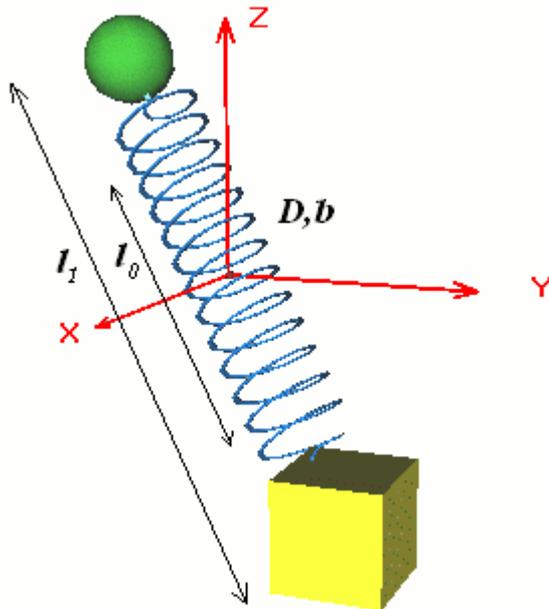
Torque is a force that acts upon the body and produces angular acceleration inversely related to its inertia moment. Visually, the torque object is very similar to the force vector, except for a rotation indicator around the head. The direction and the size of the torque vector can be adjusted with the mouse or by the torque panel on the Properties window (double click on the torque). The length of the torque vector in the scene is scaled by the rate number of the force (see Unit dialog).

5.1.2.3 Fixjoint



The fixjoint joins two or more bodies together. After you attach two or more bodies to each other, Newton inserts a fixjoint at the center of mass of the aggregated bodies. The bodies connected by the Fixjoint move and rotate together as though they were a simple rigid body with the total inertia. When you link two or more bodies, the resultant initial velocity and angular velocity are automatically computed. If you want to adjust the velocity, you will have to set the velocities of the Fixjoint. Newton makes the velocity properties of objects read only, so you cannot give initial velocity or angular velocity to composite bodies. Of course, you can modify the material properties of the individual components separately.

5.1.2.4 Spring



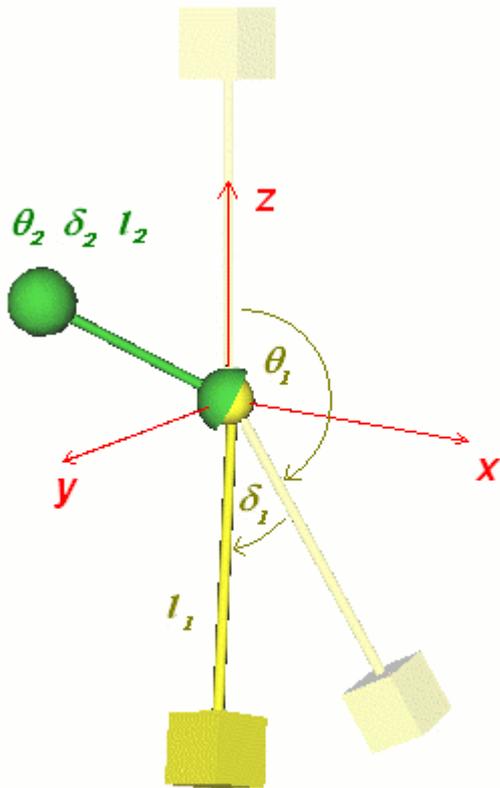
The spring object acts upon one or two bodies with a force directly proportional to the difference between its unstrained and current length. Both bodies can rotate freely because they maintain their inherent degrees of freedom. The physical spring model contains a friction component, which is proportional to the velocity.

$$F_s = -D \cdot \Delta x - b \cdot v$$

where D is stiffness, Δx is elongation between the current and unstrained lengths, b is the friction coefficient, and v is the difference of the velocity of the two bodies. The stiffness, unstrained length, and friction parameters can be controlled on the spring panel. Setting the friction coefficient to zero gives you an ideal spring, which can be used, in creating an ideal harmonic oscillator.

You can link the spring not only at the center of mass, but to any other Point (supplementary objects) assigned to the body. The spring acts upon the selected body through this acting point (See the Point chapter).

5.1.2.5 Balljoint



If you attach a body to a point in space by a fixed length rod and let it rotate freely around the point, you constrain the body to the surface of a sphere. The balljoint acting upon its linked bodies realizes this constraint.

When two bodies are linked to the balljoint, both are able to rotate around the balljoint. In addition, the three linked objects can translate and rotate together freely.

In addition to Cartesian coordinates, the position of a linked body can be given in spherical coordinates relative to the joint location:

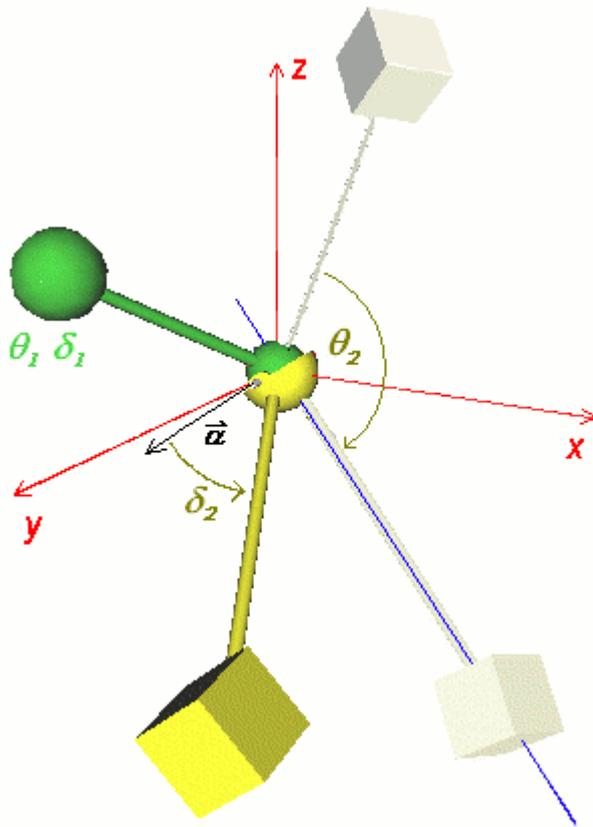
l distance : distance between a body and the joint (length of the rod)

Θ vertical angle : angle between (0,0,1) and a rod to the body

δ horizontal angle : if you project the rod into the xy plane, this is the angle between the (1,0,0) axis and the projected rod

While a simulation is running, the length of the rod remains constant, but the two angles change as the simulation progresses. These coordinates can be plotted on a diagram as functions of time. You can alter these parameters numerically on the balljoint panel of the properties window.

5.1.2.6 Hinge



If you link a body to a hinge, it can freely rotate around the axis of the hinge (\underline{a}) at a constant distance; namely, on a circle.

In the case of two linked bodies, the bodies can rotate around the hinge axis, and together the three objects can move and rotate freely.

The position of a body, in addition to its usual Cartesian coordinates, can be described relative to the hinge by three new coordinate values.

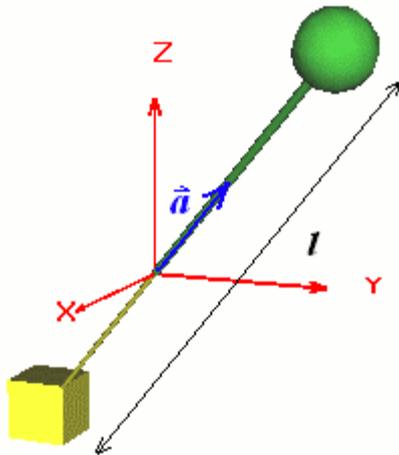
l **distance**: distance between the body and the hinge (length of the rod)

δ **angle** : angle between the axis \underline{a} and the rod

Θ **rotation**: If you rotate the body around the \underline{a} axis, you will find a location where the z component of the body position is the biggest. This is the zero rotation point, and this rotation parameter is measured from that point.

During simulation time, only the rotation will change—the distance and angle remain fixed. However, these parameters can be plotted on diagrams and can be changed on the properties panel of the hinge.

5.1.2.7 Slider



A body has six degrees of freedom in 3D space; three belong to translation and three to rotation. Sometimes, in the interest of simplicity, you may want to examine the movement in only one dimension. Perhaps you'd even dispense with the three rotational degrees of freedom in the interest of simplicity. The slider dynamic object will handle this requirement.

The slider keeps the linked bodies on a line (\underline{a} direction vector). The body can slide upward or backward along the straight path, but it's unable to leave it.

If you attach two bodies to the object, they can also slide along the line freely, but the three objects must stay together as they move and rotate.

The center of the slider object is always at the midpoint of the distance of the bodies (\underline{a}). All parameters (\underline{a} , l) can be adjusted on the slider panel of the properties window.

5.1.3 Extra objects

Several special or frequently used objects can be found on the Extra object tab of the object bar. Most of these objects were created using the dynamic objects and bodies. As they are often used in demonstrations and make the development of demonstrations easier and faster, we made them before we made the demonstrations. Some of these extra objects have unique capabilities that can be controlled on their properties window (see Properties window chapter). Let's walk through these objects one at a time.



5.1.3.1 Cannon

You can easily demonstrate projectile motion with the cannon object. It has four parts: a bullet, a stand, a cannon barrel, and a hinge, which connects the stand and the cannon barrel. The cannon can shoot a ball into the scene with defined initial velocity and with the barrel at a user-defined angle. In physical mode, the angle of the cannon barrel and the initial velocity of the bullet can be adjusted by mouse. Start the simulation and the ball will fly from the cannon.

5.1.3.2 Incline

The incline has three parts: a stand, a top surface, and a hinge, which connects the two bodies. The angle of the top surface can be adjusted by mouse.

5.1.3.3 Matchbox

The matchbox object behaves like a three-wheeled car. It consists of three cylinders (wheels), three hinges and a simple frame. If we set its initial velocity, it will roll on the surface (table, etc.).

5.1.3.4 Stand

The stand is a stationary body upon which objects can be placed.

5.1.3.5 Celestial body (Cel. body)

This object is a big sphere that has its own special properties window with which you can assign the attributes of the members of our solar system. Choose your planet and place it at a given time with the right mass and rotation velocities. It's easy and fast to simulate our Solar system using the Celestial body.

5.1.4 Environment objects

This group includes three objects: background, table, and camera. When you open a new experiment, Newton automatically places one each of the background, table, and camera on the scene. A scene accepts only one background and one table, so you can't add them. You can, however, add more cameras; in addition, you can have more 3D windows using additional cameras.

5.1.4.1 Background

The background is a polygon-approximation of a big sphere that surrounds our virtual laboratory and us. You can set its color, assign a texture to it, or draw stars on it. You must go to the background properties panel to make these settings.

5.1.4.2 Table

The table object is placed at the origin of the 3D space, with its top surface coinciding with the $z=0$ plane. Its width and height are freely adjustable and you can put bodies on it. It has friction and elasticity properties and reacts appropriately when a body collides with it. These important parameters can be altered on the table panel of the Properties window (clicking twice on the table).

The table can't be deleted. If you don't want to use it, you can set its visibility to off.

5.1.4.3 Camera

The camera object provides a view of the 3D space. Every 3D window has an assigned camera, which shows the scene from its point of view. You can add more camera objects with the Edit/New camera command. You can switch among the current cameras in the View/Camera menu.

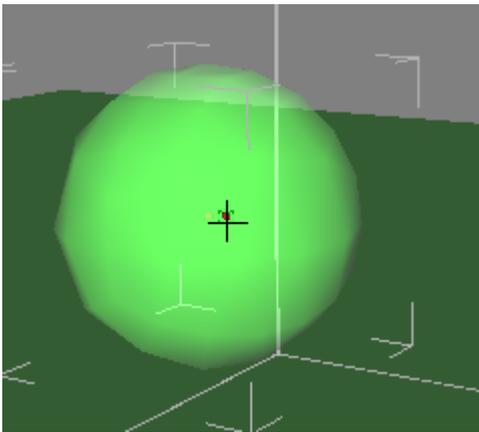
You can adjust the position and aiming of a camera with the mouse (see the Changing point of view chapter). The camera bar button makes it easy to place the camera in alignment with the X-Y, Y-Z, X-Z planes. Newton provides predefined camera movements, which take place automatically during a simulation run. The camera can rotate around a specific object, rotate as it follows its object, and can follow it. See the Properties Window / Camera chapter.

5.1.5 Supplementary element

The supplementary elements cannot exist unless incorporated into one of the simple bodies or extra objects. Its properties can be manipulated by the properties window or by the context menu of its 'parental' objects.

5.1.5.1 Point

This special object can be assigned to bodies and defines a particular point of the body. By default, every body has a point object at the body's center of mass. If you set the body color to transparent, a little red sphere mostly inside the body appears. Generally, we want forces and springs to act on the center of mass. Sometimes, though, you may want to use some other location for the acting point of the force or spring.



To add a point to a body, select the body and click on the surface where you want to place the point. With the right mouse button, open the context menu and choose the **Add point** command. Newton will now place a little red point on the surface. To select the point, move the cursor to hover over the point (you will see the cursor change shape), click and drag it to anywhere on the scene. Learn more about points in the Point relocation chapter.

5.1.5.2 Velocity vectors

The values of velocity and angular velocity, at time $t=0$ are part of the initial conditions of the simulation. Once the simulation is running, these velocities may be changing continuously. If you want to see the changing velocities of objects, you must represent these quantities in the 3D scene. Velocity vectors appear similar to force vectors, but they are red and more rounded. You can set their initial values by mouse (see Vector editing chapter), and more precisely by the **velocity panel** of the bodies.

We face the same problem here as we did with the force vector: it's complicated dealing with the plotted size of the velocities, because the unit of velocity doesn't match the unit of length. As with the force vector, we need a rate number with which to scale it. The rate number can be found on the Simulation / Units dialog.

5.1.5.3 Acceleration vectors

During the simulation, bodies accelerate or slow down and rotate with changing speed. Newton provides acceleration vectors so these can be made visible. The acceleration (and angular acceleration) vectors appear yellow on the 3D scene. By default they are programmed to not be displayed (visibility set to off), but you can change this on the appearance panel of the selected body if you set the related check boxes (acceleration, angular acceleration).

As with the force vector, we need a rate number with which to scale it. The rate number can be found on the Simulation/ Units dialog.

5.1.5.4 Track - the path of movement

If you want the user to get a good sense of the trajectory of bodies, turn on movement tracking. At regular intervals during the simulation, a point will be drawn at the current position of the body. The path of these points is a trail or track of points. It is also possible to attach points to a line.

By default, the number of track points is limited, but this can be changed. The track length is measured in seconds, the amount of time taken by the track to complete. If Newton runs out of points before the track is completed, it will begin to delete the earliest points. Alternatively, you can set how many points are to be drawn in one second. These settings can be found on the Simulation / Settings dialog.

Right click on the background to bring up the context menu. From this window you can turn tracking on or off globally.

5.2 Editing in the 3D window

Newton comes with a number of features that can help you create an accurate and attractive model. In this chapter we will show how to manage a camera, how to move, rotate and join objects, and will introduce other useful tools.

5.2.1 Changing the point of view

The view you see in the 3D window comes from a virtual camera. When you change the point of view, you are actually modifying the position and direction of the current (active) camera. Newton allows you to work simultaneously with more than one camera. By switching to another camera, you can jump to a new point of view immediately.

Here's how we adjust the camera using the mouse.

You can rotate around the scene by pressing down the left mouse button over an empty place on the background, where the mouse cursor shape changes to an arrow . Holding down the button, move the cursor left, right, up, down, and see the camera rotate left, right, up, and down. Repeating the same operation using the right mouse button will shift the camera forward, backward or side-to-side. Pressing both buttons down you can raise or lower the camera.

Keyboard shortcuts can also carry out some of the point of view operations. Use the Arrow keys for turning the camera and the +/- keys of the numeric keypad to shift the camera forward or backward.

Icons on the Camera toolbar provide yet another way to call these commands. If the camera bar isn't visible, you can turn it on using the command View/Toolbars/Camera bar.

The arrow icons  rotate the camera, while the magnifying glass buttons  shift the camera forward and back. Still more interesting are the other buttons on the camera toolbar . The four buttons take you directly to normal, front, side or top view.

The camera will be fixed perpendicular to the plane of the selected view. These planes are spanned by the main axis of the 3D space, for example,

- Front view: by the X and Z axes
- Top view: by the X and Y axes

- Side view: by the Y and Z axes

One advantage of using these views is that in each view objects can only be moved parallel to the selected plane. This is very useful when you are editing an example and you need to adjust an object's position fast and accurately using the mouse.

There are shortcut keys (hotkeys) for the four View/Camera commands:

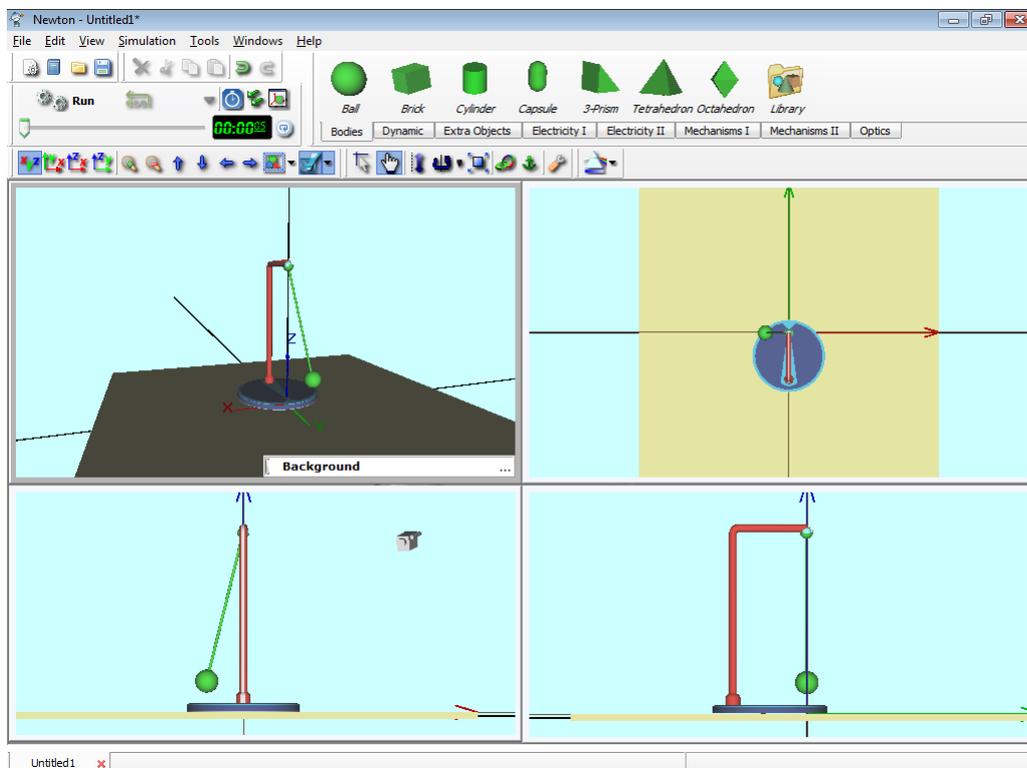
SHIFT-F1, top view (X-Y)

SHIFT-F2, front view (X-Z)

SHIFT-F3, side view (Y-Z)

SHIFT-F4, normal view

After switching views, Newton centers the view on the selected object. If no object is selected, Newton will center the camera on the origin of the space. You can return from a fixed view by clicking on the normal view button or on the icon of the selected view again.



We've mentioned that more than one 3D window can exist at the same time. You can create a new 3D window using the **Edit/New 3D window** command. In the screenshot to the right, four views are open, each with its own camera, each with its own camera view.

In physics, sizes and distances vary over a wide range depending on the phenomena we're examining. For example, if we compare the distances among the planets of our Solar system and among the balls on a snooker table, they differ by many orders of magnitude. This is true also in our laboratory's virtual space.

With Newton's default values, you can move only a few meters forward or backward with one pull of the mouse. Clearly, this won't be enough in planetary simulations, where there can be millions of kilometres between two objects. In Newton there is a global parameter which is responsible for camera speed. This can be adjusted on the **3D Window Setting** dialogs in the **Zoom sensibility** field.

5.2.2 Object manipulation

In this section, we will take a more detailed look at how we edit and move objects.

5.2.2.1 Adding, selecting and deleting objects

Most of the important, instantly usable objects are on the tabs of the Object bar. Simply click on an icon and Newton will add one instance of the object to the scene. All objects can be placed in this way except for two objects on the dynamic tab: the force and torque objects. Because force and torque make no sense without reference to a body to act upon, you must select an object on the screen first; then you can click on the icon of force or torque.

For the most part, an object must be selected before you can modify its parameters. There are several ways to select objects. The most common way to select something is to click on it with the left mouse button. When an object has been selected, the corners of the gray bounding box appear. If the object has different colored parts, another bounding box (green) appears. This green bounding box marks the component of the body that can be recolored (commands on the appearance panel). When you select a supplementary object (such as a point or vector), the body to which they are related will be transparent. This lets you see this object in its entirety.

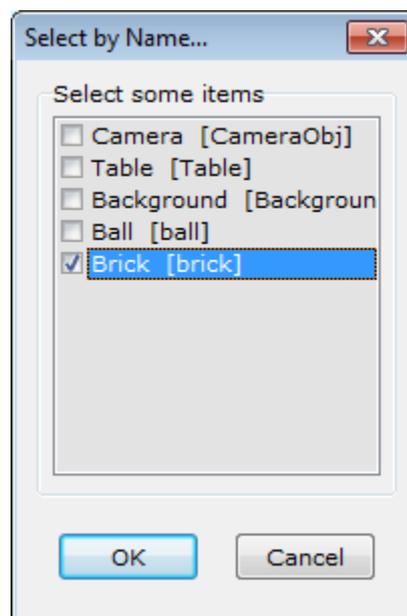
You can unselect a body by clicking on an empty area of the 3D window.

You can also select a part using the Objects combo box on the properties window.

You can select multiple objects in several ways. The first way is to select them one at a time until all are included. Press and hold down the CONTROL key on the keyboard, and click on the objects one by one. If you select an object by mistake, click on it again (all the time holding the CONTROL key down).

Another way to select multiple objects is useful when the objects are near each other in a specific area. To select these objects, press and hold the right mouse button for two seconds. After the cursor changes to the shape of a rectangle, define the selection area by moving the cursor with the mouse. The objects inside the rectangle, as well as those only partially inside the rectangle, are now selected.

The ultimate way of making multiple selections is to use the check boxes on the **Edit/Select by name** dialog. There you can select objects by their names.



The selected objects can be **deleted** by pushing the **DEL** button on the keyboard. If the object you're attempting to delete has related objects, the program asks you if the related (connected) parts are also to be deleted. On the properties window the selected object can be deleted with the **CTRL+DEL** hotkey.

5.2.2.2 Editing modes

There are two editing modes,  **geometric** and  **physical**. In the geometric mode, you can move every object freely, ignoring any logical or dynamic relationship among them. The bodies cannot collide, but they can penetrate each other. In addition, the objects' constraints don't apply. The geometric mode could also be called the "raw editing mode," because you can edit the scene without considering the rules of physics.

In **physical mode**, bodies can collide, and constraints upon them do apply. For example, in physical mode, a brick connected to a ball joint is constrained by the joint and can be moved only around the joint, with the distance between them fixed (in geometric mode, the body would be placed anywhere, with Newton adjusting the length of the rod). The Physical mode is usually a more natural way to edit demonstrations, and it is the default mode.

5.2.2.3 Positioning, rotating and scaling

Use the left mouse button to move objects. By default, objects are constrained to remain on the X-Y plane, the horizontal plane. Position the cursor over the object, click and hold the left mouse key, and drag the object with the mouse. The selected body follows the position of the mouse cursor projected on the plane. During the move, the object's coordinates are displayed in the quick info field at the bottom right corner of the 3D window. When the object is at its destination, release the button.

To move an object vertically, first click on the  (Move up-down) button on the 3D bar, and then click on the object. A black line appears on the screen, running through the object's center. This is the domain of possible movement of the object. After you have placed the object vertically, you should deselect the object by clicking on the background or on another object. The axis disappears, and the mouse reverts to horizontal mode. If you want to raise or lower another object, click the  button again.

Note: Newton generally deactivates tools (and changes their icon back to normal) when the target object is deselected or when you click again on the tool button.

The SHIFT key on the keyboard also enters Move up-down mode, just press the key during the operation.

Don't forget that in front, top and side views (see Changing the point of view chapter) objects can be relocated parallel to the selected plane of the view.

Any object can be rotated on the scene by the  (Rotation) tool. You can spin the object around the three main axes: x, y and z. A black line shows the current axis of the operation. You can switch among the three axes by pressing the SPACE bar on the keyboard. To rotate an object, click and hold the left mouse button, and move the mouse perpendicularly to the axis. Let the object spin until it's aligned properly, then click on the background to deselect the object.

You can resize an object with the  (Scale) tool. First click on the icon, and next on the

object. Drag the mouse until the object is the proper size. Note that changing the size of the body will change its inertia because Newton does not alter the object's density but, rather, keeps it constant.

In physical mode at resizing, the position of an object can change due to collisions with other objects. For example: if you place a ball on the table and inflate it, the ball would grow so large that it would penetrate into the table. Newton prevents this by raising the ball.

5.2.2.4 Linking, anchoring and fixing

Dynamic objects (springs, joints) need to be acted upon by a body if we want to change their motion. In Newton, the term **linking** is used to describe the act of attaching a dynamic object to a body. For example, when you link a body to a spring, you determine that the spring should act upon that body.

You can link an object(s) to a dynamic object if you select the body (bodies) and the dynamic object at the same time, and push the



(Link to...) button. Only body type objects can be linked with springs or joints. You can't link two springs together, for example. However, one body can be linked to multiple dynamic objects.

Joints and springs have two (or more) connectors. These are shown as little sticks coming out from the basic shape of constraints and springs. If you link a body to a joint, a symbolic rod stretches out between the body and the object. If you click on a rod or on one of the little sticks with the right mouse button, the selected link's context menu appears. From this menu you can make the rod invisible or unlink its connection.

If you select a linked body, you will find the  (Unlink) icon. If you select an unlinked body, you will find instead the  (Link to...) icon.

Another way to link a dynamic to an object, to click and hold down the left mouse button at the dynamic object, then move the cursor to the object to be linked. When the left button of the mouse is released, the two objects are linked.

Anchoring works differently from linking. It defines an asymmetric relationship between two objects, and it acts only when you are editing the demonstration. It has no effect upon the objects during simulation time. Anchoring allows you to select objects and group them so that they can be moved or rotated as a cohesive group. Let's imagine that there is a ball and it is anchored to a brick. If you move the brick, the ball will follow it and maintains its position relative to the brick. We say that anchoring is asymmetric because the linkage works only in one direction. Referring to our brick and ball example, when you move the ball, the brick remains where it was; move the brick, however, and see the ball follow. Anchoring is useful when you need to move some objects as a group while maintaining their relationships to other objects in the group. To recap: select a central object, and anchor the others to it. Now, whenever you are in the editing mode, you need only move the central object and the rest will follow.

To anchor an object to another follow these steps:

1. Select the first object, the object to which the others will be anchored..
2. Click on the  anchor icon.
3. Select the second object, one of the objects that you want to that you want to anchor to the first.

To cancel an anchoring relationship, do steps one and two again, but instead of step three, position the cursor over an empty place (background) on the scene, and click.

As an interesting variation on anchoring, you can anchor two or more objects to each other. Simply anchor the first object to the second and the second to the first. Now all anchored objects will move as a group whenever a member of the group is moved

Using the **fix** command, you can establish an object's position both at edit and at simulation times. Fixing an object while editing prevents inadvertent repositioning. Fixing an object at run timer ends the object inactive. Newton won't calculate its motion, and it remains at rest; however, it can still collide at simulation times. You can turn fixing on/off, either on the properties window location panel, or on the object's context menu.

5.2.2.5 Vector and point editing

The velocity, angular velocity, force and torque objects are represented in the scene by vector-like shapes. Manipulation of these objects calls for special techniques.

If you move the mouse cursor over the vector, the cursor changes to a thin arrow shape. To change the vector's direction, grab its head and adjust. If you grab the vector's tail, you can alter its length (the magnitude of the force, for example). In both cases, the body belonging to the vector becomes transparent during the operation. The position and direction of the vector is numerically displayed on the Quick info field (bottom-right corner of the 3D window).

Sometimes an attached vector is smaller than the body, so it remains hidden—you can neither see it nor adjust it. There are two ways to handle this. You can globally change the scale of the vectors on the Simulation/Units dialog. Although the size of vector type objects are based on their magnitude values, they are multiplied with a rate number. This not only scales them, but it sets their units to a length unit. Every vector type (force/torque, velocity/angular velocity, and acceleration) owns a parameter field on the dialog, where the sizes belonging to one magnitude unit can be set. These scaling parameters can be altered intuitively by mouse:

select a vector and push the  scale tool. Resize the vectors; this time all other vectors of the same type will change size together.

The second technique is useful when vectors and bodies overlap. You simply set all bodies to transparent. Click with right mouse button on the background and choose the Transparent mode command from the context menu. Now you can see, select, and change all vectors.

Point objects can be moved similarly. Float the cursor over the object, and the cursor becomes a cross. By default, you are confined to locations on the surface of the body, but this constraint can be turned off on the point panel of the properties window. Switch to transparent mode (see above) if you want to move the point inside the body. You can relocate the point of the body's center of mass if you wish, but be aware that this will alter the movement of the body.

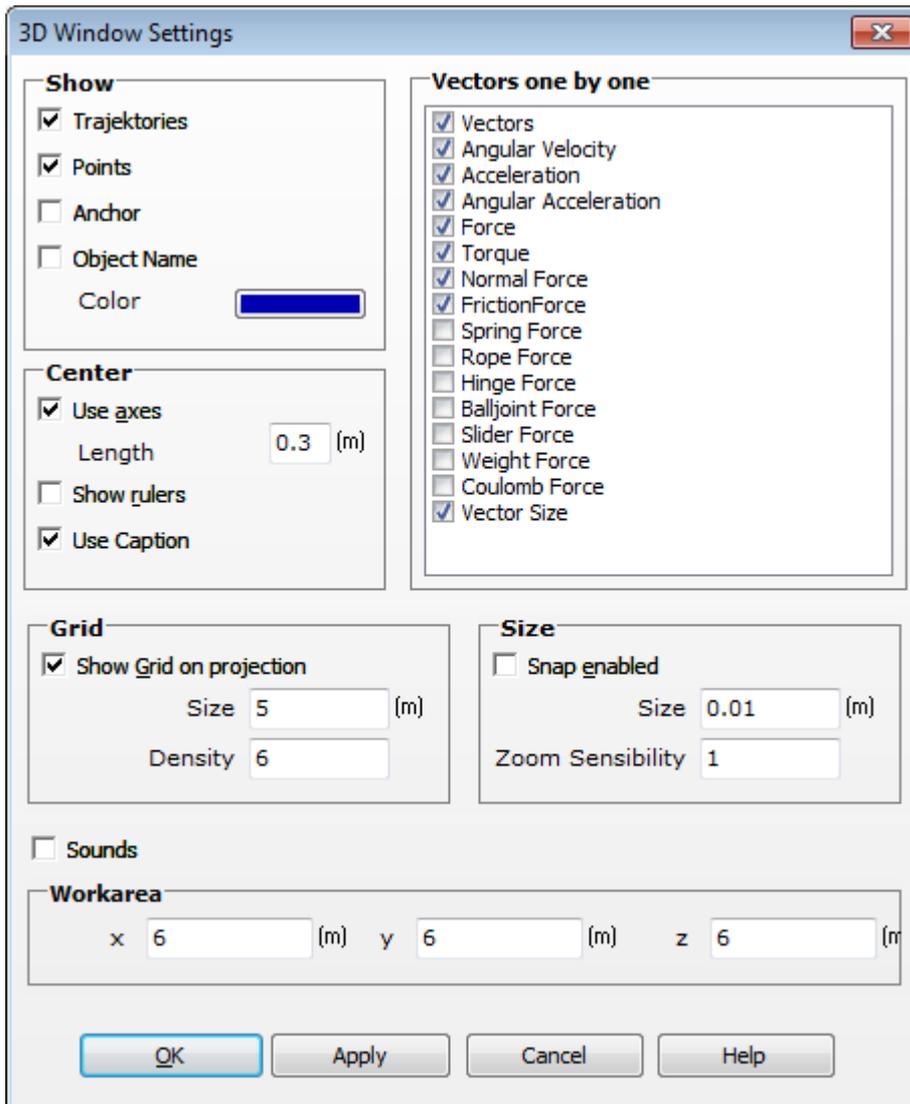
5.2.2.6 Cut, copy, insert, undo functions

You can use the general edit functions (Edit menu)—such as cut, copy, or insert—to manipulate objects. The clipboard is available and functions as in other Windows applications.

Newton preserves the object's parameter values, and many other things, such as forces acting on the object, etc. If you attempt to copy an object along with other objects related to it, you're warned by a question dialog that appears. You must decide if you want to include the other objects. If you answer Yes, all objects, linked or anchored to the selected object will be included in the action.

If you aren't content with the result of an edit or if you make a mistake and want to step back to the earlier state of the scene, use the undo function (Edit menu or CTRL-Z hotkey). If you change your mind, you can also reverse undo actions using redo.

5.2.3 3D Window settings dialog



The 3D window settings dialog allows you to control the appearance and the editing properties in the 3D windows. Click on the 3D button  or select the View/3D Window settings command. Since you can use more than one 3D window simultaneously, you can adjust each separately. The dialog always shows the settings of the 3D window currently in focus.

Next, we'll explore the controllers:

Show|Trajektorias: show the trajektorias of the objects, if it set at the objects properties also.

Show|Points: show all points in the 3D if enabled.

Show|Anchor: show an anchor sign next to every object, which is anchored to somewhere, if enabled.

Show|Object name and Color: Gives access to object name and color.

Center|Use axes: The coordinate system appears in the origin of the scene, if enabled.

Center|Length: The length of the axes of the coordinate system can be adjusted here.

Center|Show rulers: To enable rulers (they help with accurate placement), turn this on.

Center|Use caption: The captions and the rulers will be shown, if enabled.

Grid|Show grid at projection: If enabled, a grid helps the editing operations in special views.

Grid|Size and Density: The size and density of the grid used in special views are adjustable parameters.

Size|Snap enabled: If enabled, the objects snap in place according to the value of the Controller field (see below).

Size|Controller: Use this field to set the origin.

Size|Zoom sensibility: This influences the camera speed (the distance that will be covered with one mouse pull when navigating in space), and acts upon the default size of some objects. If this parameter is set correctly, you will be able to comfortably navigate in the virtual space. For example, if your demonstration fits on a table, set it to approximately one (m); but if you simulate the Solar system, 1.00E+011 (au) is a better choice.

5.2.4 Units dialog

This dialog can be used to globally change the unit system used in the dialogs of Newton. If a number on a dialog has units you will see the unit symbol between round brackets to the right of the editfield.

Unit System

System: SI with degree

Vector length on 3D window

1 N =	0.02	m
1 m/s =	0.1	m
1 m/s ² =	0.1	m
1 N/C =	1E-007	m
1 N/kg =	1	m

	Units	Sign
Time	second	s
Distance	meter	m
Mass	kilogram	kg
Force	newton	N
Angle	degree	°
Energy	joule	J
Frequency	hertz	Hz
Charge	coulomb	C
Power	watt	W

Use Date Format

OK Cancel Help Less...

At the top of the dialog, the System combo box indicates the current unit system. You can change it to another unit system by selecting another item from the list. You can use one of the these systems:

- SI with degrees
- SI with radians
- Astro
- CGS
- Custom

The custom system lets you to individually change the units of the different quantities. Click on the More button, and when the next part of the dialog appears you will find more combo boxes. You can set the units individually for each parameter.

The sizes of vectors (force, velocity, and acceleration) can be scaled globally on the Unit dialog. The first field is related to force, the second to velocity, and the third to the acceleration vectors. For each vector, you can set the vector size corresponding to a unit of

magnitude. If you work with values of very big or small magnitude, which can result in oversized or almost invisible vectors, you should alter these values. To apply changes, press OK.

You can change the unit of an edit field individually also:

- Right click on the caption of the unit to be changed.
- Select another unit from the context menu.

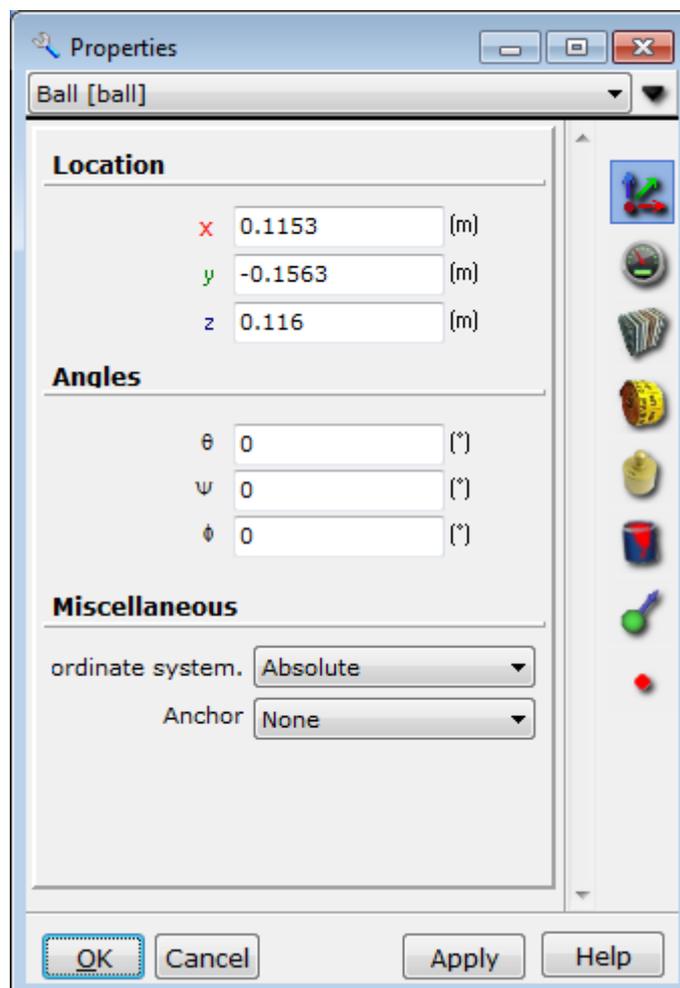
Here is a method of converting physical values such as position from one system of units to another,

- Right click on the caption of the unit to be changed. It is m/s as we begin.
- Select another unit from the context menu; e.g., km/hr.
- Enter the new value in the new units; e.g., 10 km/hr.
- Reset the units to m/s and see the numerical result in m/s.

5.3 Properties window

You will find that you use the properties window more than any other. You will use it to read and modify object parameters.

To open this dialog window, double click on the background or on one of the objects in the 3D window.



The list of the combo box at the top of the form contains the names with the identifiers of the existing objects of the scene. Beside the name and identifier you can see a small icon in the combo box. It shows the type of the element. The selected item of the combo box is the same object, which is selected in the 3D window. Change it at either place and the selection will be applied at the other place also.

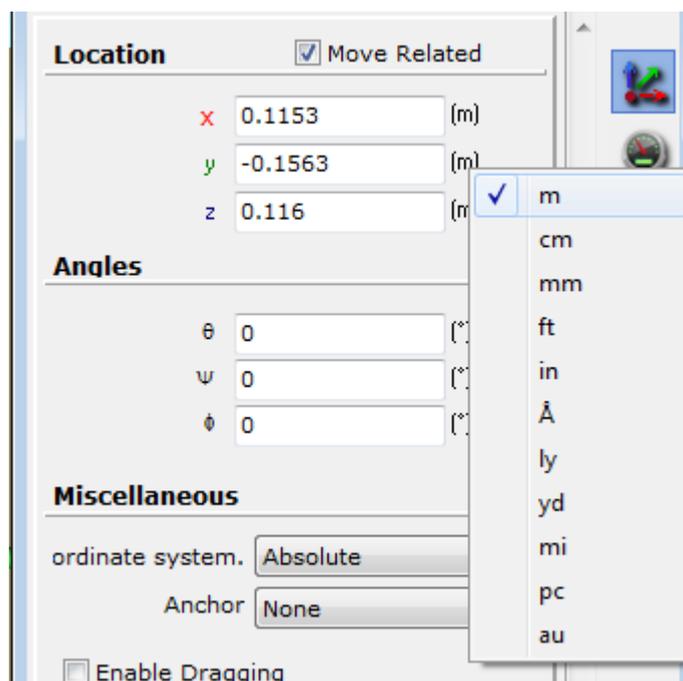
You can change the properties here only for the selected object. The various properties are arranged into different groups, such as location, appearance properties, etc. Each group of properties has its own panel. You can jump to another properties group by clicking on the icons on the right side. In our figure the location information of the ball can be seen, which includes the location, angle, coordinate system, etc. properties.

Different elements have different properties panels, so Newton presents only the appropriate panels. Furthermore, some objects like astronomy objects, have special panels,. To see the special properties of the selected object, click on the



(*Special properties*) icon.

On the panels we can find many controls—edit boxes, buttons, Trackbars, combo boxes, as well as more ordinary windows controls.

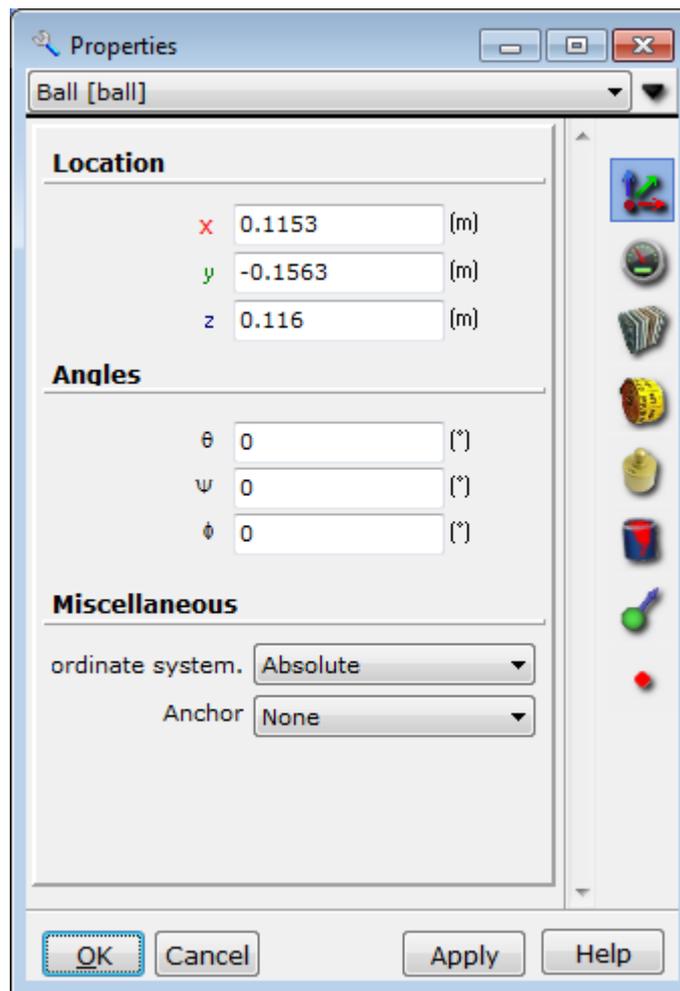


The input boxes usually display the value of a physical quantity, with its unit to the right of the box. You can change the unit at any time by right clicking on the sign of the unit and choosing another from the pop up menu.

To set the changed values into place, click on the **Apply** button or press **Enter**. Clicking on the **OK** button has the same effect as the Apply button, but in addition the window closes. The **Cancel** button closes the window and doesn't validate the changes.

Let's continue with the full description of the different panels. We'll start with the most general groups, which are accessible for most of the objects, then go on with the special property groups.

5.3.1 Location



For starters, this group of properties shows the position and the direction of the selected object, but more properties—like coordinate system—are to be found here.

The **position** edit boxes (x,y,z) give the Cartesian coordinates of the center of mass of the selected object. These values are coordinate system dependent. By default, the values are in an absolute coordinate system (at the center of the table, right handed, z -axis points up), but with the Coordinate System combo box, it can be easily changed. Every object can be selected as the origin of the Coordinate System. The center of the Coordinate System will be at the center of mass of the body (or at the geometric center in the case of joints). Furthermore, the Coordinate System axes are rotated with the object. This is a useful tool to reposition objects relative to others.

The **Angle** edit boxes (Θ,Ψ,Φ) give the Euler angles of the selected object. This set of three angles defines how much rotation is needed around the three axes to get to the desired position. Don't forget, these values are also coordinate system dependent. The Newton software uses the so-called “**xyz-convention.**” In this convention the first rotation is with angle Θ around the x -axis, the second is with an angle Ψ around the rotated y -axis, and the third is with an angle Φ around the doubly rotated z -axis.

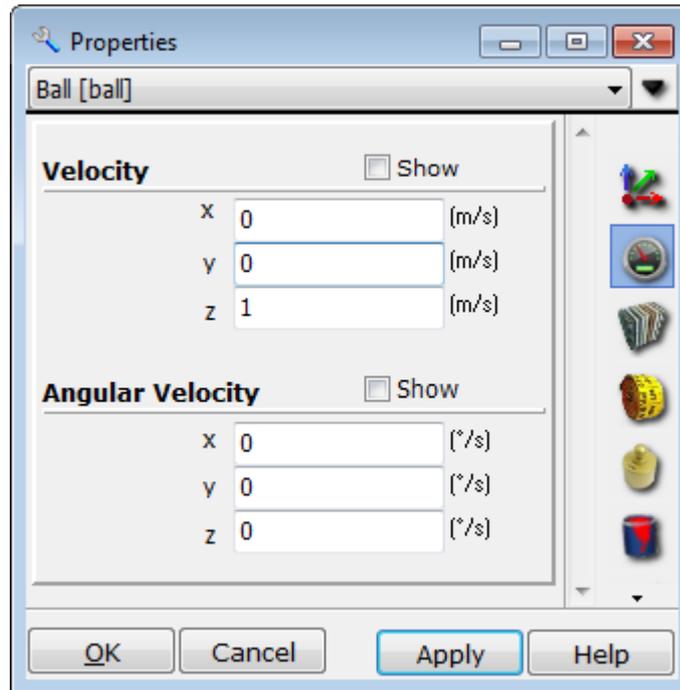
If the **Move Related** box is checked, after you change the selected object's position or angle, the position and angle of any related objects (related means: the objects are anchored to the selected object or linked to the selected objects) will also be changed to maintain a constant

distance between them.

With the **Anchor** combo box, the object can be anchored to another object. So at design time, when moving or rotating any selected objects, each object which is anchored to the selected object will move together.

With the **Fix at editing / Fix at Running** check boxes you can lock the objects at design time or running time. Locking a body at design time is helpful when you don't want to move the selected object by mistake. A body locked at running time becomes static (position and angle are constant), but it will collide with the other bodies.

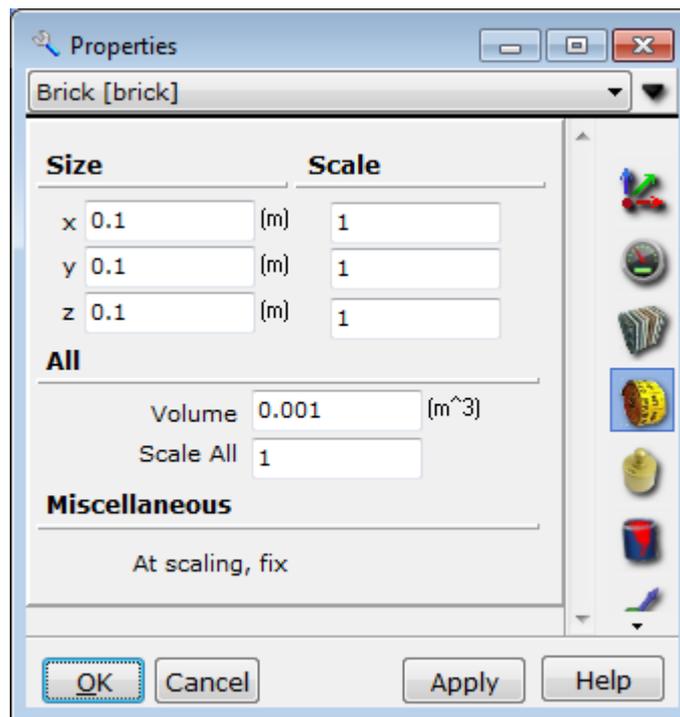
5.3.2 Velocity



On this panel, you can check the actual values of the velocity and the angular velocity and of course you can enter a different initial value. Using the Show check boxes below the edit boxes, you can display or hide the velocity and the angular velocity vectors in the 3D windows. Around the angular velocity vector, you can see a little circular vector, which shows the direction of rotation.

Note that the '**show vectors**' checkbox on the **3D Window Settings** dialog may overwrite the settings of these checkboxes, because this switch hides all the vectors. If you believe that vectors should be visible but you can not see them, check the setting of this dialog.

5.3.3 Size



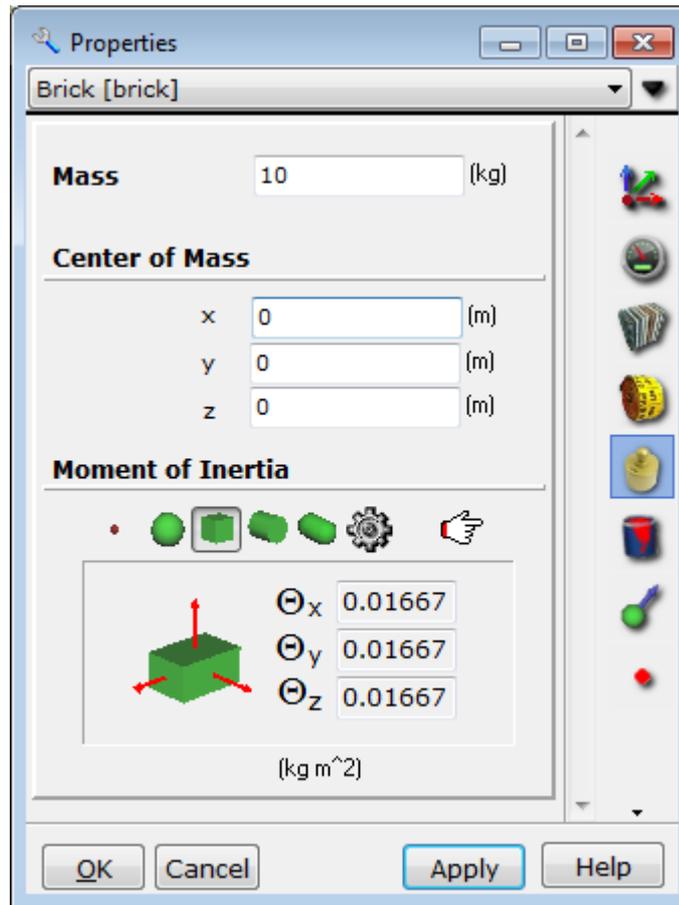
With this dialog, the size and volume of the selected object can be modified in many ways. The simplest way is to enter the **Size** values. The **scale** values allow you to stretch or squash the object in each direction. The values of the Scale edit boxes are multiplied by the Size values to compute the new size. When you enter a **scale all** value not equal to one, you can scale the object the same amount in each direction.

Instead of 'Size All', for some objects you will find the **Volume** field more useful. In this edit field you can read and modify the volume of the body. Setting the Volume value causes Newton to change the size of the object in every direction.

When you modify the volume of an object, either the mass or the density has to be changed too. Use the two radio buttons (**At scaling, fix**) in the bottom of this panel where you can choose whether the mass or the density will be held constant.

Note that the size panels of the ball and cylinder differ a little bit. For the ball, only the radius may be scaled, while for the cylinder, both the radius and the length can be scaled.

5.3.4 Inertia



This panel contains all the possible settings for the inertia of a body. At the top of the panel the **mass** can be modified, and just below the center of mass can be repositioned. The values of the **center of mass** are referenced to the geometrical center of the bounding box of the body.

At the bottom of the panel the components of the inertia moments are shown. Click on one of these  icons and assign various inertia values of ideal shapes, such as

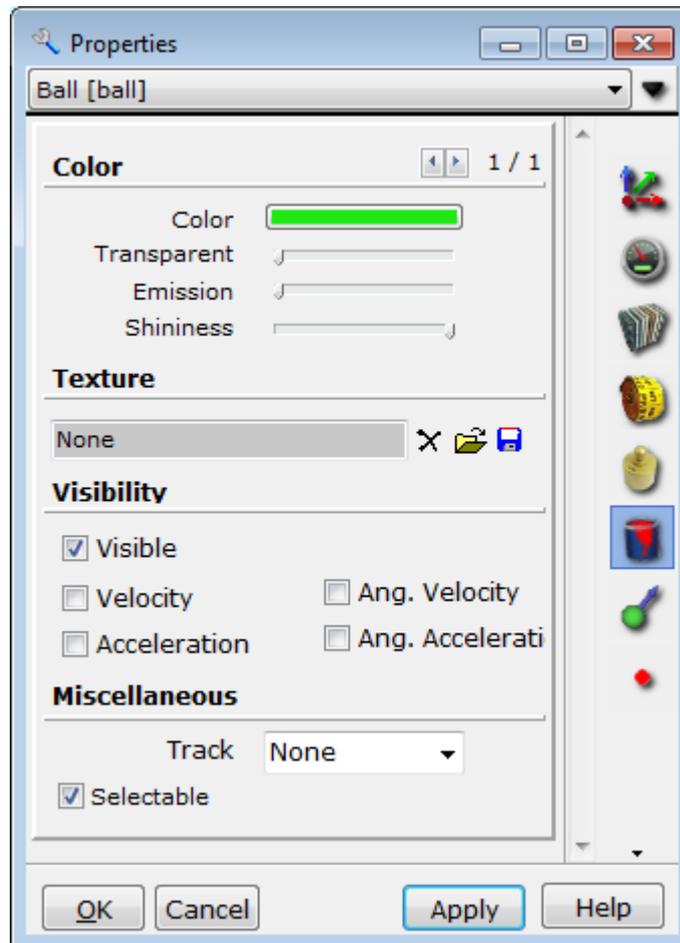
point, sphere, box, or cylinder. With the  (*Inertia Calculator*) button you can calculate the values of the inertia tensor for any shape.

Select any icon and you will notice that the number of active editfields changes as the inertia moments changes. This is because the geometric shapes have symmetries, which reduce the number of the parameters of the inertia moment. For the point, which is an abstraction and doesn't exist in the real world, there are no inertia moments to assign. At the opposite extreme, the most general case is when the inertia is calculated from a triangle face of the polyhedral; you will need six parameters to determine the inertia moment properly.

Note that the inertia values of ideal shapes—sphere, box, and cylinder—can differ slightly from the calculated values that are embedded in a loaded model file, despite their nominally being the same shape. For example, place a sphere on the scene and click on it to get to this panel. Assign the ideal inertia values for a sphere, then click on the Inertia Calculator (the icon is a gear symbol). You will find some small difference between the results. This comes about because the model isn't perfect—the sphere is actually built up from a finite number of triangle faces. Compared to a real ball, the model is very angular. But the more triangle faces used in

modeling the sphere, the closer the numerical results will be to the ideal case.

5.3.5 Appearance



Working with this panel, you can control the appearance of the selected object. With the **visibility** check boxes you can specify whether or not an object is visible, and whether or not its velocity, angular velocity, acceleration, and angular acceleration vectors are visible. The **track** combo box determines if the object's path will be visible and, if so, if it appears as a dotted or solid line. Below the visibility panel there is the **selectable** check box, which determines whether you can select the object by clicking on its shape.

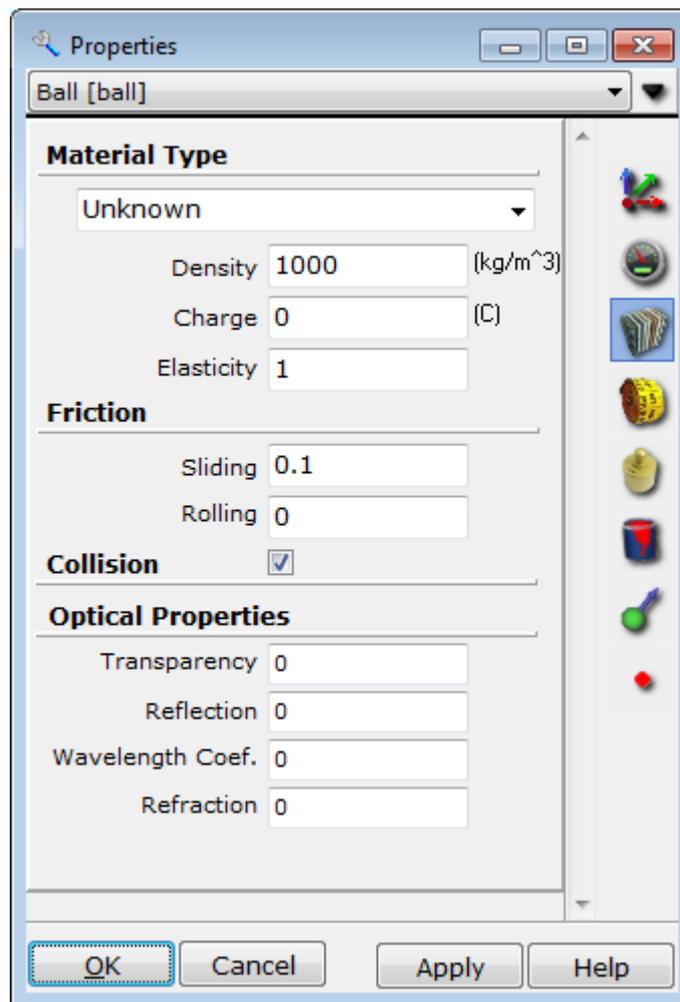
A Newton object can contain many parts, and each part can have different **texture**, **color**, **transparent** and **emission** properties.

For each part of the object, a texture file name is shown in the box below the texture text. The texture file (JPEG, or BMP picture files) can be erased (✕), changed (📁) and saved (💾). When creating or modifying a texture file, the values of width and height must be a power of two.

The color can be changed with the color dialog, which appears when you click on the color button. The transparent and emission properties can be changed with the Trackbars.

You can move among the parts using the ⏪⏩ buttons. In the 3D window a light green box can be seen around the part (if nothing is overlapping).

5.3.6 Material



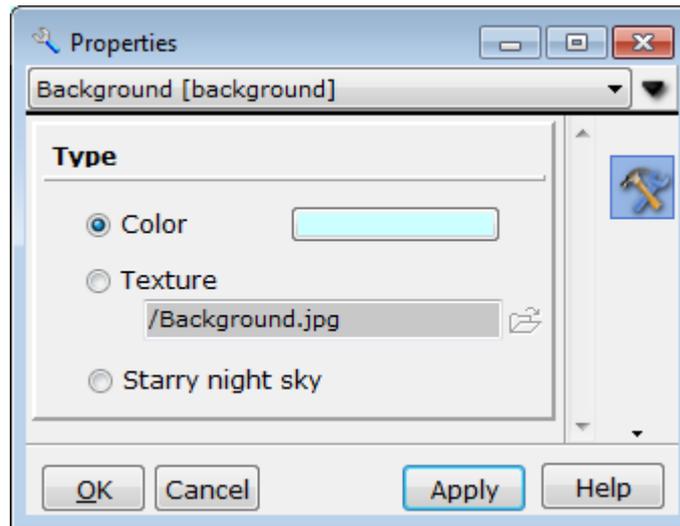
On the material panel, you can manage density, elasticity, charge, and the various friction parameters. With the **material type** combo box you can choose from many predefined materials and set the properties of the selected object to the values of a “known” material. In this list you will find predefined material, e.g.; steel, wood, plastic, etc.

When two objects collide, the relative rate of the change of velocity is usually given by the collision number. In Newton, this is the mean of the two **elasticity** parameters of the two colliding objects. This number is between 0 and 1, where 0 is the perfect inelastic case and 1 is the perfect elastic case. With the **collision** check box on the bottom, you can set whether the objects collide or not.

When two objects slide against each other, a friction force acts on the objects. This force is proportional to the sliding frictional coefficient. In Newton this coefficient assumes the value of the smallest of the friction parameters of the chafing bodies. This value is between 0 and positive infinity, where 0 is the case of no friction, and positive infinity is perfect stiction. In practice, 10e9 is big enough to stand in for infinity.

You can set another friction coefficient—rolling friction—which is a resistance force that slows down the motion of a rolling ball or wheel.

5.3.7 Background

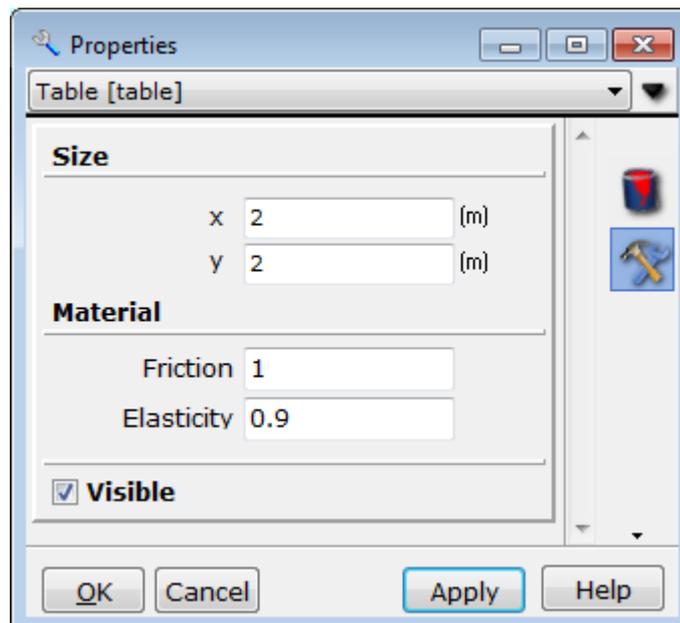


The background object is actually a very big sphere within which we and all the objects have been placed. You can select the color and the texture, or you can set them to a starry night sky.

Choosing the texture radio button, with the  (*Load*) button, you can load BMP and JPEG picture files. Note that the texture file height and width should be the power of two.

In astronomical demonstrations Newton provides an attractive starry night background, which gives a nicer view. In addition, you can discover different constellations.

5.3.8 Table

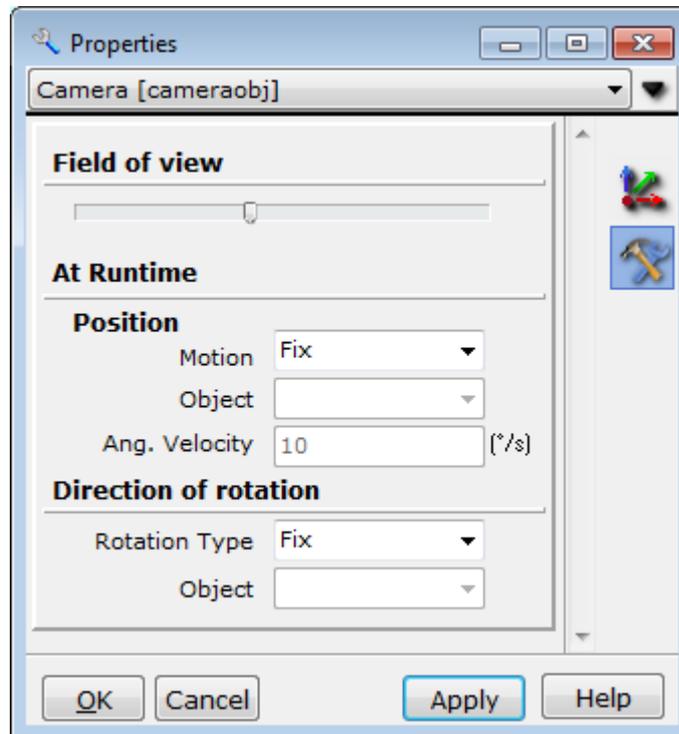


The table object is very simple, but since it is used frequently it has its own properties window, where all the important settings can be adjusted. The first setting is the checkbox for object visibility.

The next two editfields determine the x and y dimensions of the table.

Because other bodies bounce and slide on the table top, it is convenient to be able to set the friction and elasticity material properties directly.

5.3.9 Camera



On this panel, you can adjust camera navigation at runtime and the camera field of view (in degrees).

You cannot select the active camera (the camera that is providing the scene in the 3D window) by simply clicking on it; however, you can select it at any time using the object combo box (on the properties window). Other cameras that may be inactive can be adjusted by finding them on the scene and clicking on them.

At runtime one or more bodies of interest may move out of the camera's view, so you may want the camera to automatically follow one of the objects. Set the combo boxes and edit fields accordingly.

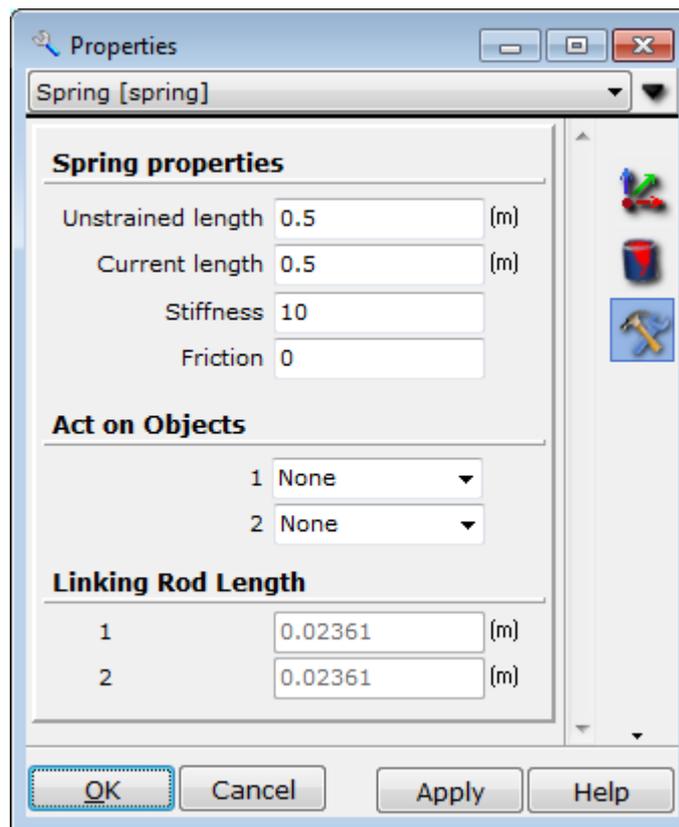
For camera position you can specify the type of **motion**:

- **Fix**: The camera is fixed. (This is the default camera motion.)
- **Locked to Object**: The camera moves together with the selected object.
- **Go around object**: The camera moves around the object. The angular velocity of rotation and the object can be set in the edit box. It is usually used together with the Rotation Type / Point to object option .

With the **Rotation type** combo box you can set the automatic rotation:

- **Fix (default)**: Camera does not rotate.
- **Rotate with object**: Camera will rotate with the object selected in the combo box .
- **Point to object**: The camera will always point to the object selected.

5.3.10 Spring



Use this panel to see and modify the selected spring's properties. In Newton the spring force is linearly proportional to the elongation, while spring friction is proportional to the speed.

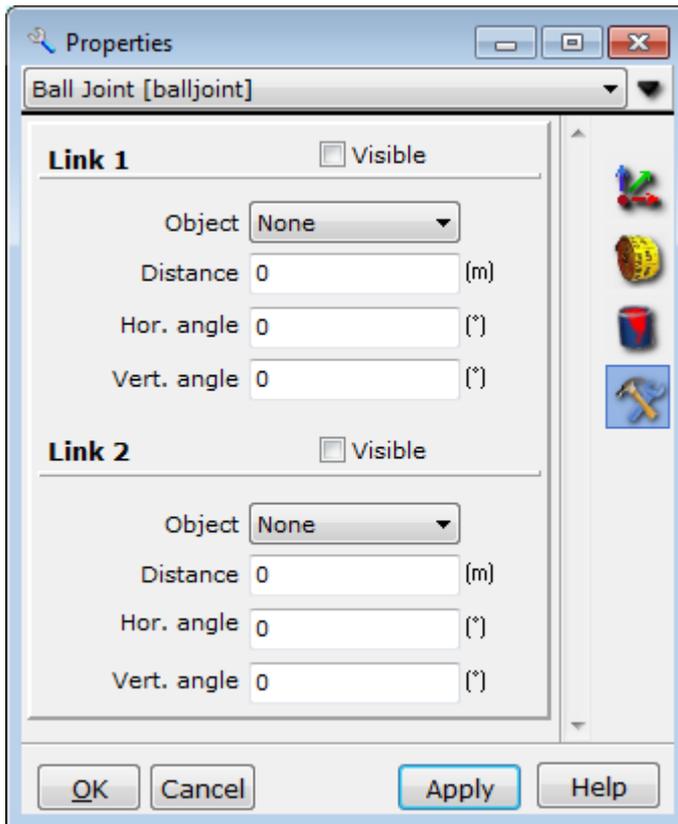
Here you can set the value of the Unstrained length (the spring length when no force is acting on it).

If called for, set the stiffness, friction (damping), and current length (distance between the two bodies) in the editfields.

You can see two comboboxes to select the bodies upon which the spring will act. Selecting the item 'None' will unlink the original body.

At the bottom of the dialog you can change the Linking Rod Length. Every spring contains two small connectors, similar to joints, that are part of the symbolic representation of the spring. Their size can be estimated easily, as it is the same as the radius of the bounding sphere of the body it is linked to. If you prefer to use a different value, it can be set here.

5.3.11 Balljoint



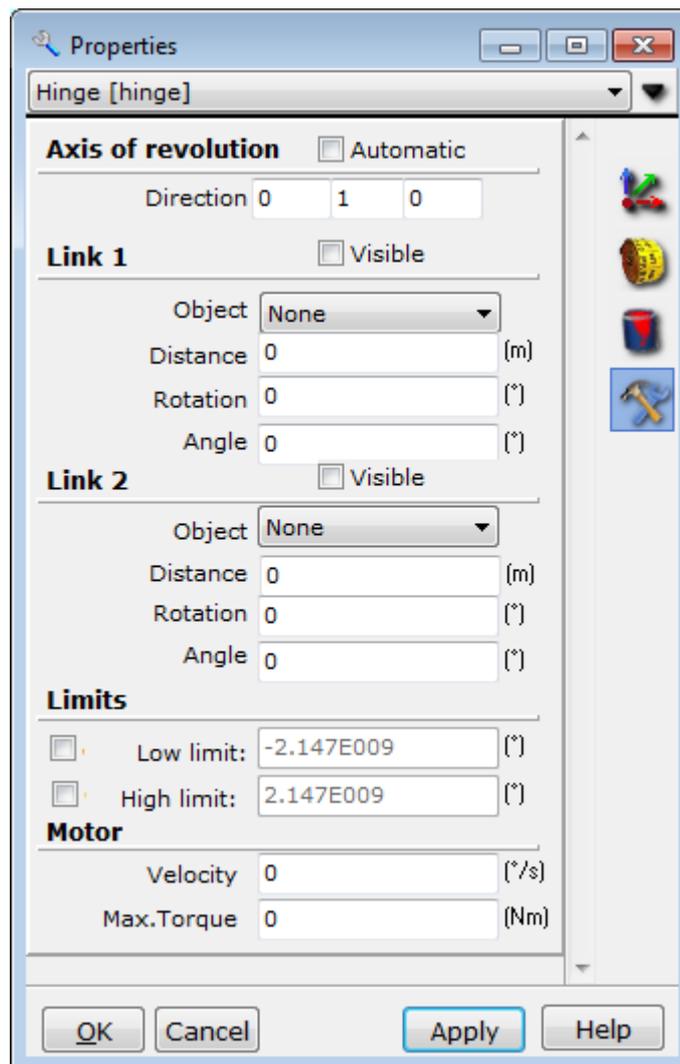
Select balljoint from the Properties Panel and make the settings needed to set up the balljoint (see chapter balljoint). Establish the two linked objects and their relative position from the joint. You can set the same options for each link.

With the **visible** check box, the visibility of the joint's stick can be set.

The object combo box selects the object you want to link to the joint.

The next three parameters—the distance, horizontal angle and vertical angle—specify the relative position of the object.

5.3.12 HingeJoint



Select the hinge joint from the Properties Object combo box. From here you can choose the two linked objects and their relative position. For more information on the parameters of the object position, see chapter HingeJoint.

Determine the visibility of the joint's stick with the **visible** check box. With the **object** combo box you can select the object you want to link.

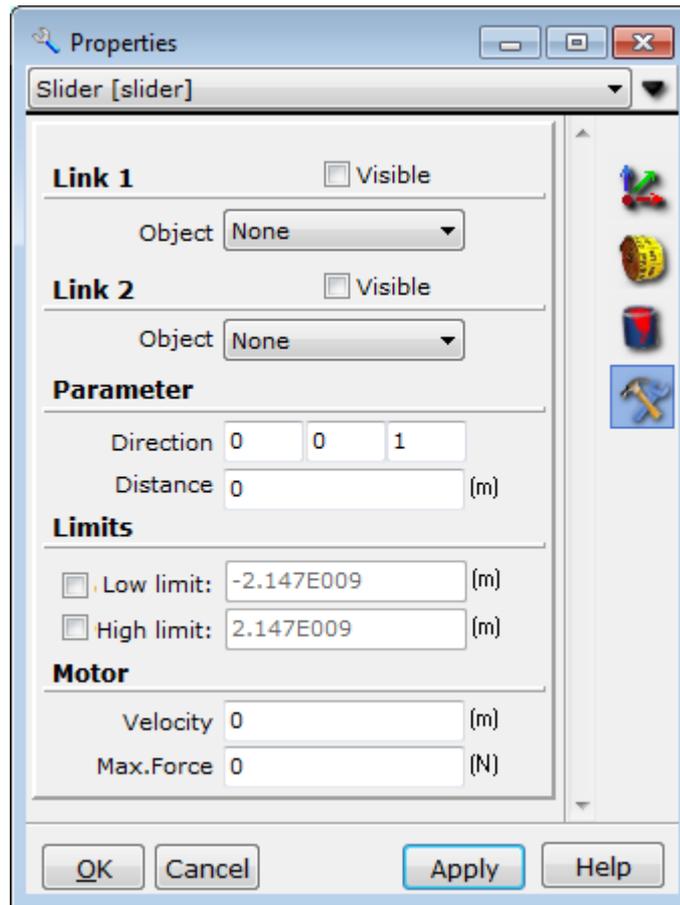
With the **distance** edit box you can specify the distance from the joint (the length of the stick).

The angle edit box shows the **angle** between the rotation axis and the axis along the stick (which is constant at running time). It is zero if the two axes are parallel and 90 if they are perpendicular to each other.

The **rotation** angle gives the current angle of rotation.

The direction of the rotational axis can be set with the edit boxes in the bottom of the panel. In many cases you may want the angle between the sticks and the rotational axis to be 90 degrees: enter a check in the **automatic** check box. Now when any linked object is rotated, the rotation angle will automatically rotate in that direction, while the angle remains 90 degree.

5.3.13 Slider



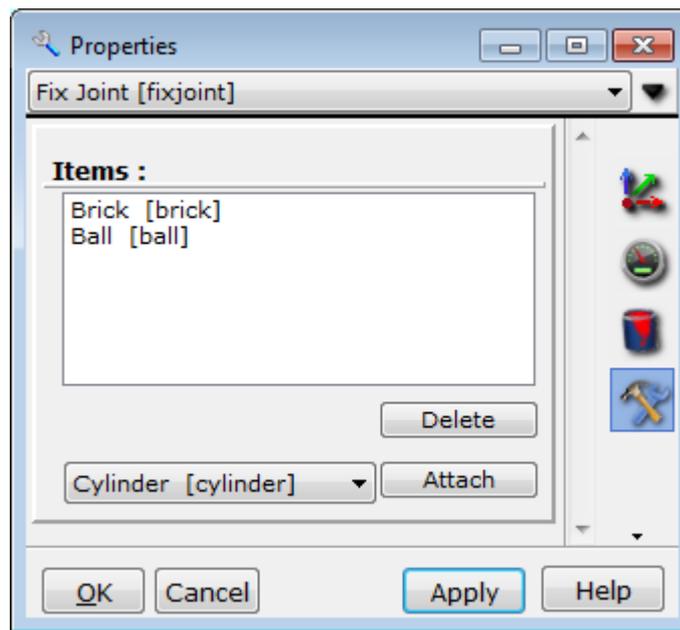
The slider object links two bodies. The **object** combo box shows these two bodies, and permits you to select another object from the list. Select 'none' to break the original link to the object.

The **visible** check box can be used to set the visibility of the stick.

The **direction** vector of the slider, which sets the line of motion the bodies can move along, can easily be modified in the three edit field, which you use to set its unit vector.

The **distance** edit box shows the distance from the currently linked objects to the center of the slider.

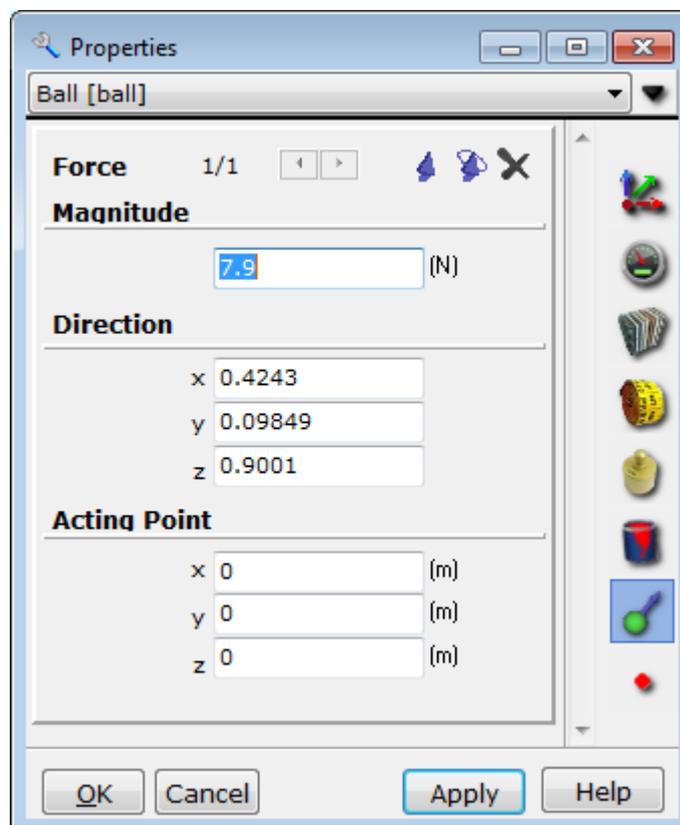
5.3.14 Fixjoint



The Items list displays the linked objects. Additional objects can be linked to the fixjoint by selecting the object from the combo box below the list, and clicking on the Attach button.

If you want to remove an object from this list, select it in the items list and click delete.

5.3.15 Constant force, Torque



The selected **force** or **torque** object properties can be seen on this panel. The only difference

between the force and the torque on this panel is that the **acting point** is disabled for the torque.

In the editfields of the force (torque) the **size** and **direction** are displayed and can be modified.

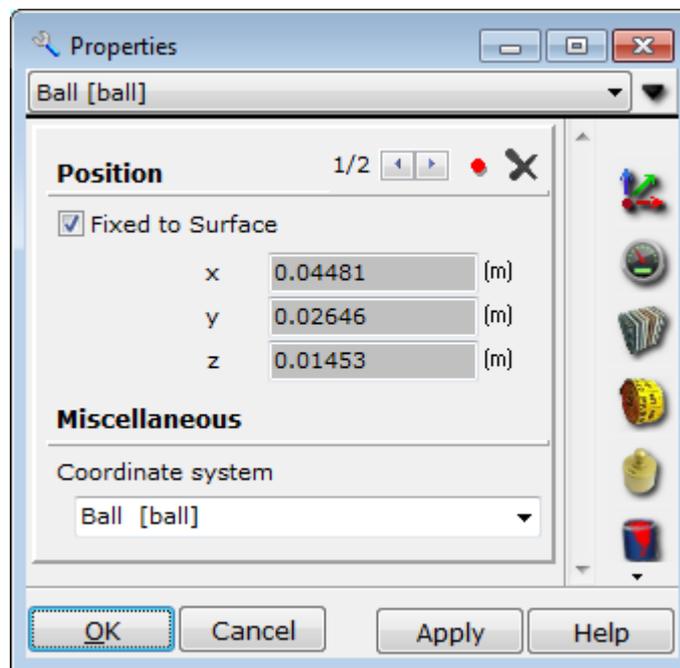
The size is the norm of this physical quantity, while the direction determines its unit vector.

You can specify the acting point of the force on an object. This point is to be referenced to the object's Cartesian coordinate system. Generally, it is in the center of mass. If you reposition the acting point, a new point object (supplementary objects) appears attached to the object, and the force will point from that point.

With the **show** check box you can control the visibility of the selected force, or torque vector on the scene.

In Newton you can set more than one force or torque vectors to an object. Use the  buttons in the bottom of the panel to cycle through the force or torque objects acting on a given object

5.3.16 Point



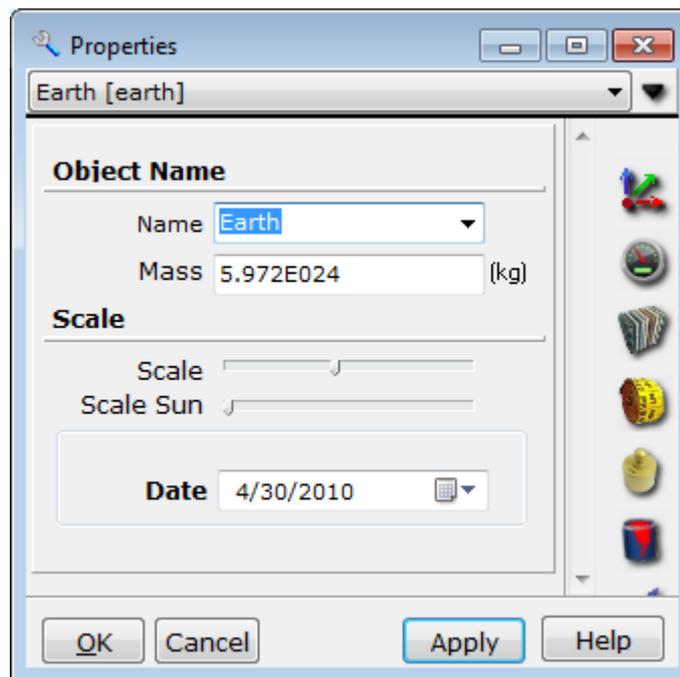
With this panel you can modify point properties.

In the **position** edit boxes the coordinates of the point can be seen and set. The position is given with respect to the object's coordinate system. The system type can be modified with the **coordinate system** combo box.

If the **Fixed to surface** checkbox is checked, then the point is constrained to be on the surface of its parent body. When this check box is unchecked, the point can be placed anywhere in space.

As in the case of the force and torque, many points can belong to an object. To jump to the next or the previous point, use the  buttons at the bottom of the panel.

5.3.17 Celestial object



This is a special object for use in astronomical simulations.

Use the combo box below the Object name to select among many predefined schemes. In the list you can find the sun and all of the planets. When you select one of these, Newton sets the properties of the selected object to those of the celestial object (**mass, density, size, texture, etc.**).

Furthermore, the initial position and velocity values are automatically set according to the date specified by the **date** dialog.

Try it now—place some celestial object in the scene (don't forget the Sun!) and start the simulation. You can see how the planets orbit around the Sun.

If you modify the date, Newton will change the initial values of all the planets' position and velocity.

The sizes of the planets are in correct proportion, but you can change their size by adjusting the **Scale** Trackbar. Similarly, you can change the size of the Sun with the **scale Sun** Trackbar.

5.4 Understanding the simulation environment - running simulations

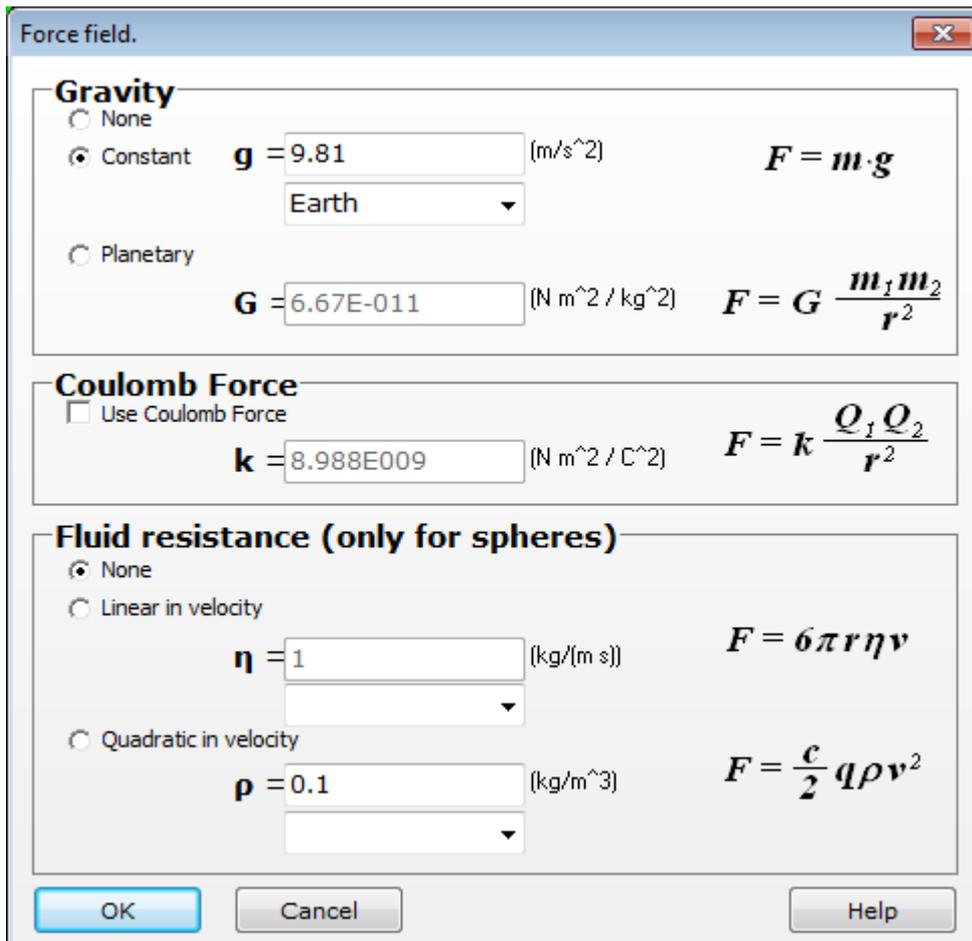
After building the experiment you can start the numerical calculation of the simulated motion by pressing the Run  **Run** button. This single button toggles between the Run and Stop commands. To terminate a run, press the Stop  **Stop** button. These commands are also in the simulation menu.

You can view the simulation again by pressing the replay button . This time, though, Newton doesn't have to do the calculations because the resulting data are stored in computer memory. In this way, the complex calculations of a simulation, (which need the computing power of big computers and cannot be carried out in real time on desktop PCs), can be replayed as fast as you wish. Before replaying the simulation, you can freely change the point of view.

To return to the initial state, click on the reset  **Reset** button. This sets every object back to its initial position, assigns its initial velocity, etc....

The simulation has many parameters, which the user may adjust. There are parameters related to the simulation time, the external force field, the length of the tracks or the length of the records which can be replayed, etc.... These parameter are classified into two groups, one of them being the external forces, and the other being “all the rest.” The dialog with the parameters of the first group is reached by clicking on the command Force Field in the Simulation menu.

5.4.1 Force Field



Force field.

Gravity

None

Constant $g = 9.81$ (m/s²) $F = m \cdot g$

Earth

Planetary

$G = 6.67E-011$ (N m² / kg²) $F = G \frac{m_1 m_2}{r^2}$

Coulomb Force

Use Coulomb Force

$k = 8.988E009$ (N m² / C²) $F = k \frac{Q_1 Q_2}{r^2}$

Fluid resistance (only for spheres)

None

Linear in velocity

$\eta = 1$ (kg/(m s)) $F = 6\pi r \eta v$

Quadratic in velocity

$\rho = 0.1$ (kg/m³) $F = \frac{c}{2} \rho v^2$

OK Cancel Help

In this panel, you can set the external force(s) acting on the bodies. These are the Gravitational field, the Coulomb field, and fluid friction.

On the Gravity panel you may choose from three possibilities:

- The choice 'none' means that the simulation take place far away from any stars and planet, in empty space, where no gravitational forces accelerate the bodies.
- The second, 'constant' means that the gravitational field is the same anywhere in the virtual space, and points in the direction (0,0,-1). If you place a body in this field, it will accelerate downwards just as we experience gravity on the surface of the Earth or on any other planet. The acceleration can be changed to any value; moreover, there is a combo box with which you can select the gravitational acceleration of any planet of our solar system.
- The third choice is 'planetary'. If you want to use Sir Isaac Newton's law of gravitation,

$F = G \frac{m_1 m_2}{r^2}$, select this choice. Here m_1 and m_2 are the mass of two bodies, r is the distance

between them, and G is the gravitational constant. You can change G , which, of course is a constant and doesn't vary in the real world. Still, it can be interesting to change G and see what would happen (for example, in our solar system).

The Coulomb force between the bodies can be switched on/off on the second panel. Here you can explore the effects of changing the Coulomb constant just as we did with the gravitational

constant. The force is expressed as $F = k \frac{Q_1 Q_2}{r^2}$ in the equation, where Q_1 and Q_2 are the charges of the two bodies, r is the distance between them, and k is the Coulomb coefficient.

To change the charge of the bodies, go to the properties window material page . The default value of the charges is zero, so the Coulomb force also will be zero until we change the charge of at least two bodies.

On the last panel, you can choose from two different fluid resistance models. With either model, the friction approximations are only valid for spheres: Newton ignores friction on all other shapes. The friction models are the following:

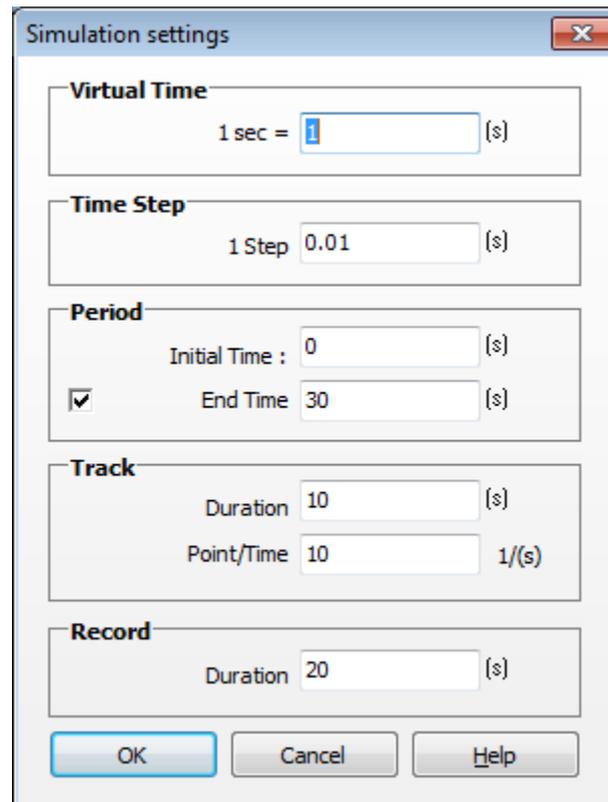
- Linear in velocity: The Force acting on the body is linearly proportional to the velocity, formulated : $F = 6\pi r \eta v$. Here r is the radius of the moving sphere, v is the velocity, and η is the viscosity of the fluid. This kind of approximation is typically good for bodies moving in liquids if the velocity doesn't exceed a certain velocity limit.
- Quadratic in velocity: The $F = 1/2 c q \rho v^2$ force slows down the body, proportional here to the square of the velocity. c is the numerical drag coefficient (for a sphere $c=0.45$), q is the cross-sectional area, ρ is the air density. This model is used typically for air resistance.

In both cases, you can use measured values from the combo boxes under the constant edit fields.

5.4.2 Setting Simulation Parameters

This dialog will come up if you click on the Settings... command in the Simulation menu. Here you can find attributes of the execution of the simulation.

Virtual Time: The inner clock of the simulation can progress faster or slower than our clock. Here you can adjust how many virtual seconds elapse in one real second. Because the program cannot calculate arbitrarily fast (due to CPU limitations), Newton may, in spite of the settings, use a slower virtual time. In this situation, you first make a simulation run. When finished you can replay the simulation, and now it will run according to the selected virtual time.



Time Step : the computer cannot make calculations in continuous time, only in discrete time. The interval between two time moments is called the time step. When you adjust the time step here, you change the density of the discrete time moment and at the same time the accuracy of the simulation. For example, a 0.01s time step means that in 1 virtual second the program takes 100 steps. Thus the position of a body will be calculated 100 times a second. Decreasing the time step makes the simulation more accurate, but slower. The optimal value of the time step is achieved when further decreases of the time step will not significantly change the result. Estimating this value is a very difficult problem and cannot be solved automatically. But generally we can say that a virtual time of 1% percent makes the simulation fast and inaccurate, 0.1% is moderately fast and accurate, 0.01% is slow but very accurate.

Period: Here you can change the time moment when the simulation starts and – if you wish – the final time when the simulation stops.

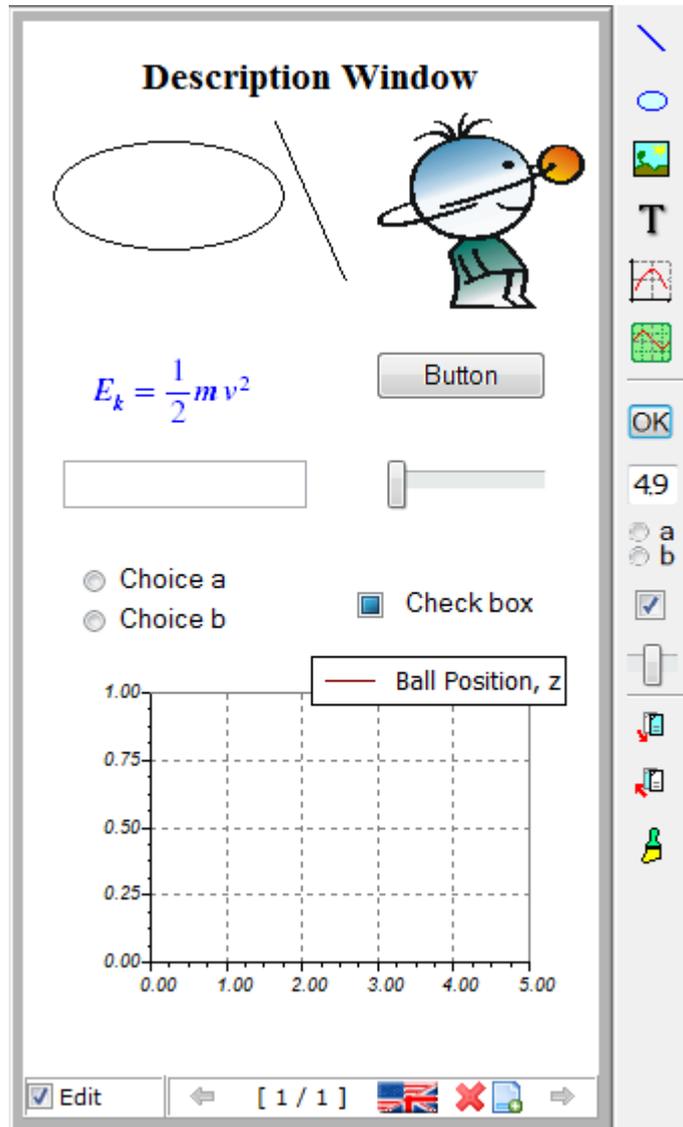
Track: For each of the bodies you can have Newton draw a track to show the trajectory of the body's center of mass in the 3D window. You can adjust how long the track will be in time units and thereby extend the time the body takes to complete its motion. Keep this length on the shorter side. If the simulation extends over too long a time, the scene may become confusing and cluttered by the accumulation of earlier points. You can set the density of the track at the point/time editfield.

Record: Newton automatically starts recording the results of the simulation. This record can be replayed repeatedly after the simulation completes. It can also be exported into a *.avi video file. The recording stops automatically after “Length” seconds.

5.5 Description Window

Even though an experiment may be visually attractive and sophisticated, it will be enhanced by the inclusion of explanations, descriptions, calculations, or test problems. This will help

the user understand physical phenomena more deeply and broadly, and improve the learning experience.



You may use Newton's description window to get and check test problem results, and to insert auxiliary illustrations, graphs, equations, explanations—even the interface unit for the simulation's important parameters. In the paragraphs, which follow, we will introduce you to the tools used with the Description Window.

The command New Description Window is available in the Window menu, this puts an empty description window on screen. Because only one description window can be used in Newton in an example, you cannot create a new description window if there already is one.

This window has two modes. In one mode you can edit the contents, while in the other you can enter values in the text fields, press buttons, etc.; that is, you can make it work. To switch between the two modes, simply click on the Edit check box in the left bottom corner of the window. If the box is checked, the Description toolbar will appear beside the window. The toolbar icons can help you insert elements on the window. These commands and tools are also available in the Edit/New Item submenu.

5.5.1 General Usage

The description window can have more than one page. This facilitates longer, structured explanations for the experiment. On the first page, for example, you could place diagrams, and on the second page you could explain the theoretical calculation of the motion.

At the bottom of the window beside the check box you will see two other icons; these are to manage the window page. The left icon  creates a new page, and the right icon  deletes the currently selected page. Right beside the right icon a caption displays the currently selected page number and the total number of pages. The third part of the caption says what type page is currently selected and is only of interest when you edit the description window of a problem file. In this example, you may need to change the page type from *normal* to *hint* or *solution* depending upon the contents of the page. We will present the page type in more detail later on. You can use the type-switching command (which can be found in the context menu of the window) to set the type of the current page.

In the right side of the status bar, there are two arrow buttons   that you can cycle through the pages. The PageUp/PageDown keys of the keyboard do the same thing.

If you have placed elements in the description window that extend beyond the window, Newton enables the vertical and horizontal scroll bars.

Each element inserted in the description window has its own properties window from which you can change the element's position and size numerically. The appropriate dialog will appear if you click twice on an element. We will present the details of these dialogs later when we present the corresponding element.

To replace or resize the element, do the following. Place the cursor over the item (the cursor shape will change to ) , press and hold down the left mouse button, and drag the element into a new position. When an element is selected, you will see small boxes in the corners of its drawing area. These boxes are for resizing elements, but only when doing so makes sense; for example, pictures or diagrams. If you try dragging a line's selection rectangles, you can move the end point of the line.

You can select and move several elements at once. Click near one of the elements, hold down the mouse button, and extend the selection rectangle until it encloses the elements you wish to move. When you release the button, the items within this rectangle will be selected. Now click on one of the selected elements, hold down the mouse button, drag the elements to their new location, and release the mouse button. Another way to move a group of elements is to select them one by one. Hold down the Ctrl key and click on the elements one at a time. When the selections have all been made, move them as explained above.

After you have placed a few elements onto the Window, you may find some element(s) overlapping. To change which element will be visible and which will be covered, press the

icons   . One of them places the selected element behind the other, the other sends it to the front.

In the settings submenu of the context menu of the description window you will find the Settings/Snap... and Settings/ Papercolor commands. Snap is a helpful tool to force repositioned items onto a grid. On the 'snap' dialog you can switch snap-to-grid on and off and adjust the size of the grid. The papercolor (background color) setting changes the background color of the description window.

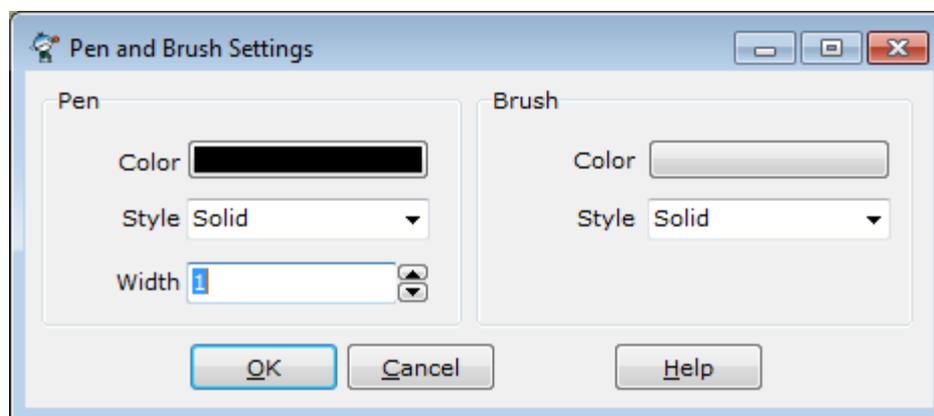
Now let's go through the tools used for editing. In the followings, we will always suggest that you insert the elements from the description tool bar, but all of them are available from the description menu or from the description window context menu.

5.5.2 Insert line, ellipses, pictures

The first icon  enables line drawing. Move the mouse cursor where you want the line to begin, click with the left mouse button, extend the line to the end point, and click again. You can draw additional lines in the same way. When you are through drawing lines, press the right mouse button or the ESC key.

Use this tool  to draw ellipses or circles. Select the ellipse icon, and move the cursor to a corner of the boxed ellipse and click to establish the starting point. Now move the mouse to extend the ellipse to the desired shape and click a second time.

You can change the line style, the color, or the fill style of the ellipse if you select the item(s) and press the last icon , named 'Pen and Brush Format'. A dialog will appear as shown below.



The three pen properties—color, style, and width—determine the appearance of lines or ellipse contours that you draw. To change the color, click on the button and select the desired color. If you have selected a Pen style that is continuous (doesn't include dots or dashes), then the Brush color will be used to fill ellipses.

If you haven't selected any items before clicking on this icon, the pen and brush settings will be changed, and will be in effect the next time you draw a line or ellipse.

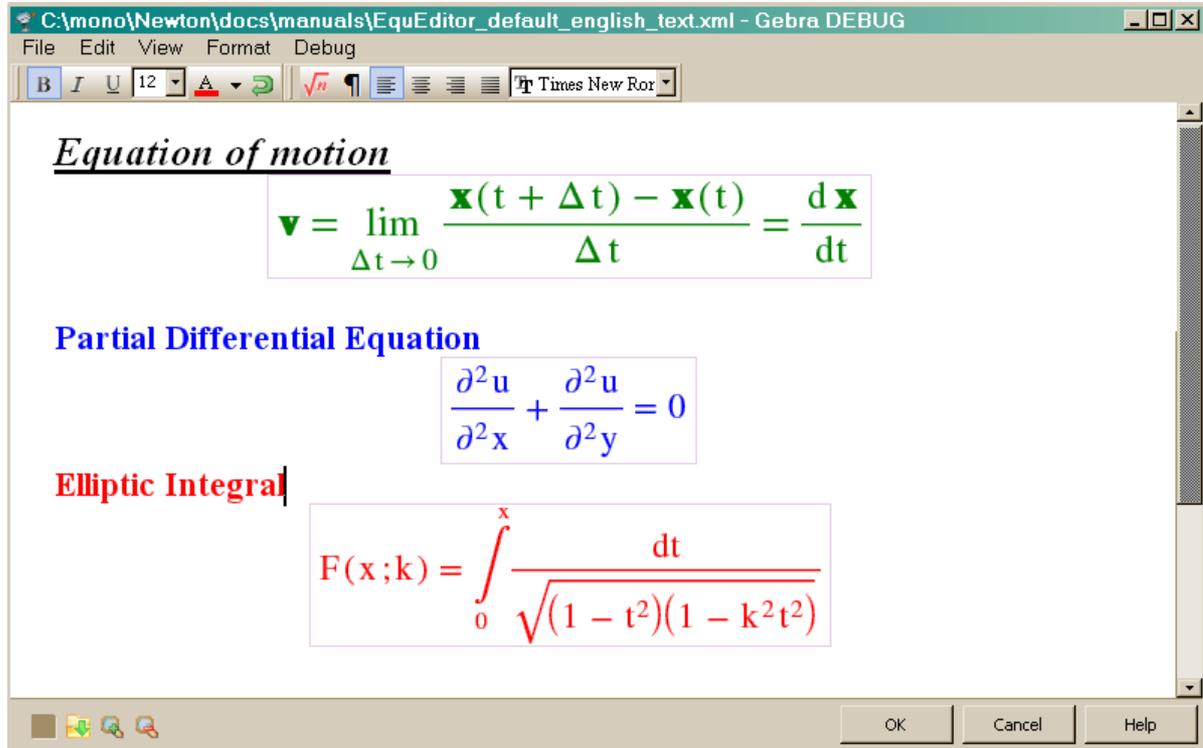
To place an image from a Windows bitmap file onto the Description Window, click on the

bitmap icon . A dialog will open with which you can select a file from one of your disc drives (format bmp and jpg can be imported). Click the OK button and place the image onto the window. If you want to resize the image, select the bitmap and move the cursor over any of the small rectangles that indicate the selection handles (the cursor shape will change to ) , and resize it by dragging and moving the handle.

5.5.3 Edit Text and Equations

T, the next icon on the Description Toolbar, is the Text tool. It allows you to create and place captions, words, and equations in the Description Window. Clicking on the Text icon brings up the Text dialog window where you can compose your text. This dialog window and the composing rules are explained in this chapter. When you have completed your text and set all the attributes, click OK to place the text on the Description Window. Later, if you want to

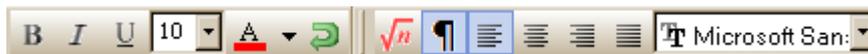
edit the text, click on it twice and use the dialog again. To reposition the text, use the usual drag and move method.



5.5.3.1 Icons of Text dialog box

This dialog box operates in two distinct modes. In 'Text Edit' mode, you can enter, modify, delete texts, adjust paragraphs, change fonts, etc...this is how the common Editors usually work. When you insert a Formula Box or you step in with the cursor the Editor will switch to 'Formula Edit' mode, now you can build mathematical formulas using the appearing toolbars. You will find it strongly intuitive in use.

The buttons on the text dialog box's toolbar in 'Text Edit' mode are:



From left to right it represents the following operations:

Bold

The font of the text(selected or will be typed later) will be boldfaced.

Italic

The font of the text will be italicized.

Underline

The font is underlined.

Font size

Specifies the height of the font in points.

Font Color

Specifies the color of the text.

Undo

Undo the last operation.

Insert Formula

Math formulas should be written into "Formula Box".

Show Special Characters

Show/Hide special characters.

Align Left / Center / Right / Justify

Align the text in the paragraph to Left/Center/Right side of the Editor, or Justify text on both sides.

Font Type

Identifies the typeface of the font. This font setting is applied only to normal expressions. All the texts within a 'Formula Box' will use a special font set.

One of toolbars on the text dialog box's toolbar in 'Formula Edit' mode are:



Clicking on one of these icons will insert at the cursor an expression; for example clicking on the **fraction** inserts two square characters above each other. This presents you with sort of a template that will become a proper expression after you substitute your parameter names for the denominator and the numerator characters. The expressions can be nested freely into each other.

Tip: You can find hints for most of the icons. Generally in the hint you can find some short word or abbreviation, for example for symbol square root you will find 'root'. Try to type it into a Formula Box, you will see it will change to the greek symbol at once.

Let's go through from left to right:

Brackets, norms

It is a collection of round, square, curly brackets, and norms.

Fraction

Different shaped fraction can be inserted by clicking here.

Indexes

You can find lot of kind of indexes here.

Square root, n-th root

To insert roots into the formula click here.

Embellishments

Collection of different kind of Embellishments.

Vector, matrix

Insert different shaped and sized matrixes into the formula.

Text Box

If you want to cancel shaping inside an equation use Text Box.

On the picture you can see below you can find lot of additional symbols to build proper and good-looking expressions.



For the easier editing you can magnify the text using the *zoom in/out* icons below on the  toolbar.

5.5.3.2 Text dialog box | Menu

The menu in the text dialog box enables you to save and load your text or to set its properties. Most Important Commands on the menu are:

Open

Loads existing text from a file into the text editor.

Save

Saves the contents of the text dialog box to a file with its current name. For web you can use html file format,

HTML Export

You can export the content into HTML format. There is possibility to change the formula format embedded in html, it may be Mathml format, or simple GIF image.

5.5.4 Creating Diagrams

The motion of objects in the experiment not only can be watched in virtual 3D, but also can be easily plotted on diagrams placed in the Description Window. Many other physical quantities can be plotted, not just motion; for example, the components of velocity, moment, acceleration, the energies, etc..

Several curves can be plotted on one diagram simultaneously. A curve is defined by two expressions. These expressions are mathematical functions containing the variables of the bodies and objects of the experiment, and they are evaluated at every simulation time step. As result we get a pair of real numbers at every time step. The series of these points define a curve, and the curve is plotted on the plane extending through the horizontal and vertical axis of the diagram.



Press the diagram icon  on the description tool bar to create a new diagram. This brings up the diagram properties dialog, where you can add one or more curves to the diagram or change the settings of the axis, scroll, curves, and appearance. Even if you're not prepared to define curves now, you can place an "empty diagram" in the description window. Click on the OK button and place the diagram in the description window, first the top left corner, then the bottom right corner. If at a later time you want to change the size of the diagram, select the

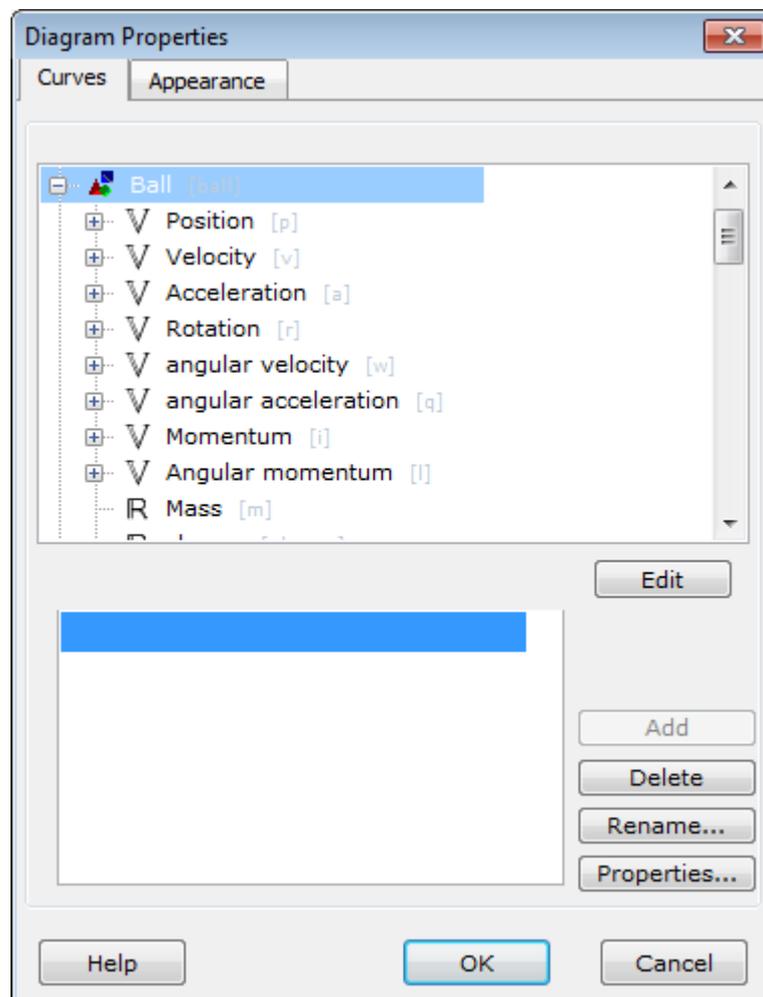
diagram by clicking on any point of the diagram area. In the corners of the diagram you can see small rectangles, place the mouse over any one of them, press and keep down the left button and move the mouse to reposition it. To move the diagram to another place of the description window, click anywhere in the diagram and drag it to the desired position.

Double-clicking anywhere within the diagram will pop up the diagram properties window again. In the next chapter we will explain it in more detail.

5.5.4.1 Diagram properties window

The Diagram Properties Window is presented on two pages, **Curves** and **Appearance**. To switch pages, click on the tab with the appropriate caption. The Curves page is for creating and adjusting curves, while the Appearance page is for changing the appearance of the diagrams and setting the axis.

5.5.4.1.1 The curve page



When this dialog first appears, you can see the name of the object in a list at the upper part of the window. Of course, if no object has yet been placed in the scene, this list will be empty. Next to the object name, you can see the folder outline character, \oplus . If you click on it, the object's variable list will be displayed.

If an object has vector type variables, it cannot be plotted on the diagram. Newton vector variable names are preceded by this symbol \oplus . Clicking on them will bring up the vector components, X, Y, Z. To draw a curve for this variable, select the variable and click on the

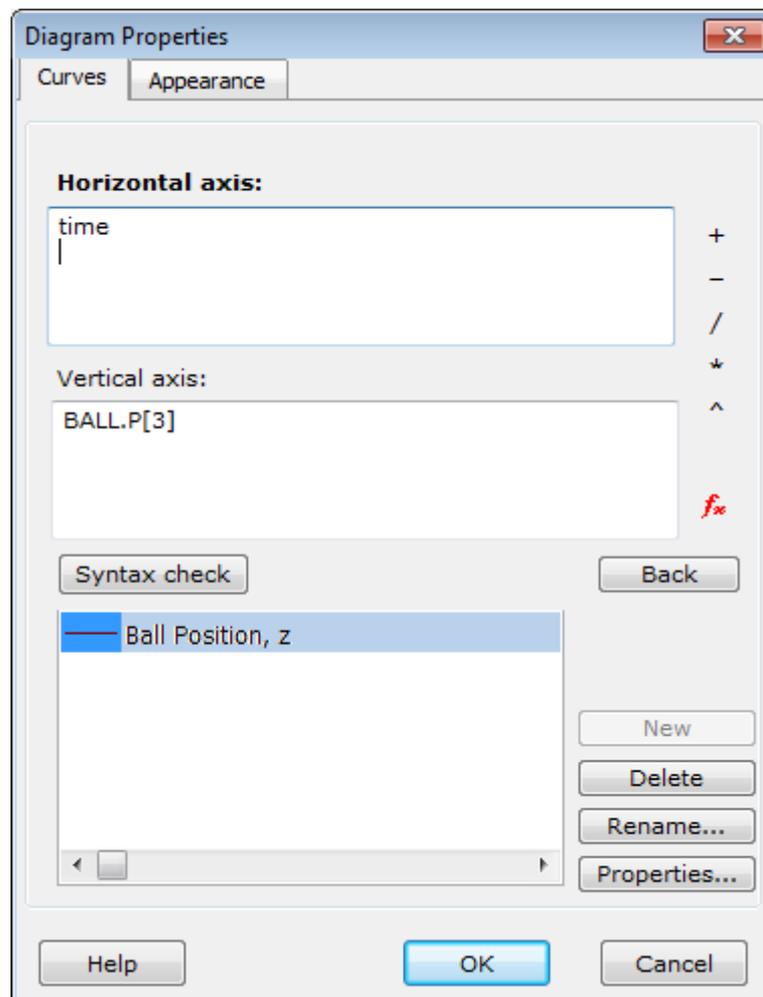
add button. You have now defined a curve, the curve of the variable versus time.

The icons to the left of the name indicate the variable type. The \mathbf{V} is the vector type variable, the \mathbf{R} is the real type, and \mathbf{Z} is the integer type. Only the last two types can be plotted directly on the diagram. If you select the vector type, Newton grays out the **add** button. An expanded list can be collapsed by clicking on the \square symbol.

If you followed the operation described above, and pressed down the add button, the name of the new curve will now appear in the Curves list. Next to the list, you will see buttons with which to manage the selected curves. To select another curve, simply click on it. The functions of the buttons are the following: the familiar **add** to create a new curve, **delete** to delete the selected curve (you can also use the delete keyboard key), and the **properties** button to set the selected curve's appearance. The color and the width of the curve can be set. A check box determines if the curve points will be tied together with a simple line.

To rename the selected curve, click the **rename...** button. The name of the curve will be shown in the legend, so it is important to use names that suggest their function.

Despite its simplicity, there are some disadvantages to defining curves as demonstrated above. Only the time dependent functions of the predefined variables can be plotted.



We need a more powerful way to define the plotting of functions if, for example, we want to plot the projection of the motion onto a plane (which is not a time dependent function). Another case arises when we wish to plot a function of more than one variable. As mentioned previously, the definition of the curve requires two expressions related to the axes of the

diagram. The formulas can be entered directly. Click on the Edit button and note that the upper part of the dialog alters.

There are two new edit fields—horizontal axis and vertical axis. You must enter the two mathematical expressions defining the curves. The rules are simple: you compose the expression from a variable name, mathematical operation (+, -, *, /, ^) and functions (e.g. trigonometry functions, coordinate transformation functions, etc) . The function syntax is: name of the function, followed by the parameters inside parenthesis. You don't have to memorize the names of the variables and functions—simply click the  icon. The Variables Window opens, allowing you to browse the variable and function lists. At the lower part of this window you will find a short description of the selected item. To insert it into the expression, click on the **insert** button. You can read more about this dialog in the chapter 'Variable Window' .

To the right of the two edit fields are icons for addition (+), subtraction (-), multiplication (*), division (/), and raising to a power. Clicking on an operation symbol inserts it into the expression at the cursor position. The selected edit field is denoted by its caption., which is displayed in bold characters.

After entering the expression you should verify that it is acceptable for the program. Click on the **Syntax Check** button. If an error is found, Newton will present an error message and the edit field of the wrong expression will turn to red. A syntax check will be carried out automatically after you click the OK button of the dialog. You cannot close the dialogs as long as the program reports an error.

To modify a curve, simply select that curve, and the two axis edit fields will open revealing its expression. You may edit freely.

If you have created a curve using the simpler method presented earlier, you can still use this editing dialog. For example, let's say you have chosen the z component of the body named ball. If you select the curve from the list in the edit fields, you will find the following expressions:

Horizontal axis

time

Vertical axis

ball.p[3]

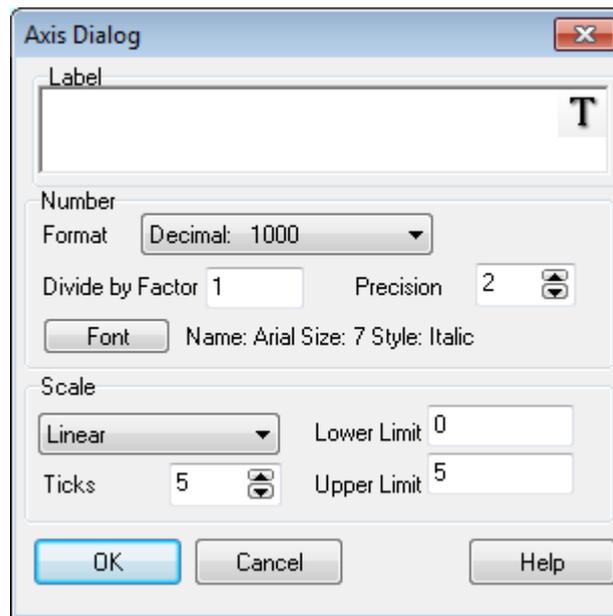
Here the expression time is a variable that shows the actual simulation time. The ball.p[3] is the z component ([3] = z) of the position (.p) the body ball (ball is the identifier). The diagram gets a value at every time step, and adds a point on the plane and adds the point to the curve.

5.5.4.1.2 Appearance page

The appearance of the diagram can be altered using tools on the appearance page. Let's go through the possible settings.

On the Axis panel you can change the settings of the axis. If the Scrolling box is checked at drawing time, the program will scroll the axis if necessary; i.e., if the maximum or minimum value of the curve is bigger or smaller than the Upper or Lower limit. There are two ways to treat this. The first is to 'change axis limits', which means that the limits will be pushed out. The second way is to 'shift interval', which shifts the limits together.

Clicking on one of the two buttons—X-axis and Y-axis—will bring up another dialog. Another way to reach this dialog is to move the mouse over the axis of the diagram drawn in the description window and double click on it. The dialog contains the following:



Label Text	This is the name of the axis. The name will appear under the horizontal axis or to the left of the vertical axis respectively.
Label Font	Sets the text font.
Number Format	Allows you to set the format of numbers. The options are decimal, engineering, or scientific.
Number Divide by Factor	The axis numbers will be divided by this number. This will also be reflected in the written numbers.
Number Precision	Defines the number of digits to the right of the decimal point.
Number Font	Sets the Font of numbers.
Scale Lin/Log	Selects a linear or logarithmic axis.
Scale Ticks	Determines the number of intervals into which the axis will be divided.
Scale Lower Limit	The Lower limit of the axis.
Scale Upper Limit	The Upper limit of the axis.

Finally, there is a “Legend” check box on the Appearance page of the Diagram Window. If it is checked, a legend will be drawn, using the data from the curve’s name. The legend presents a short line drawn with the current curve settings (color, weight, etc.) next to the curve name. You can freely reposition the legend, and by double clicking on it you can change the curves’ names. Newton will also refresh the curve names in the diagram properties curve list. To delete the legend, uncheck the Legend check box on the diagram properties window.

5.5.5 Interactive controls

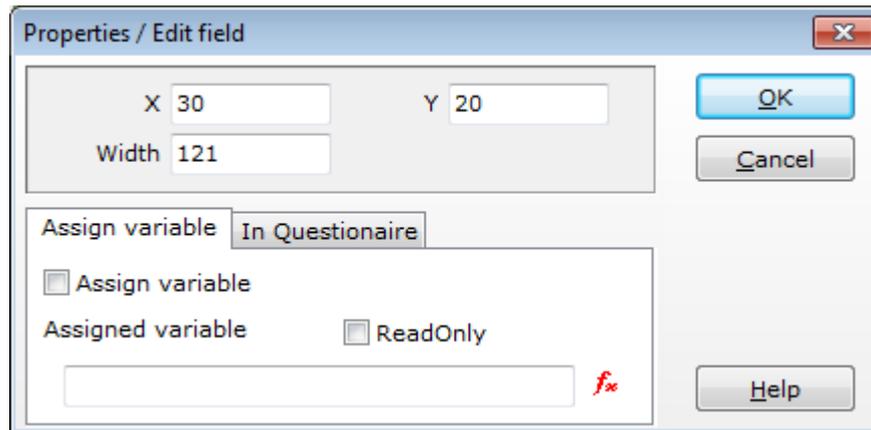
Newton provides interactive controls. These allow you to place controls for a few key parameters or physical quantities in the description window where they are ready for immediate, interactive use. For example, imagine that we have a ball bouncing on the table and we would like to examine how the maximum height of the rebound correlates with the

ball's elasticity. By providing an edit field for the elasticity coefficient on the description window, we can both read and change its value—and we can see vividly the effect of the elasticity coefficient.

Interactive controls are also used in problem solving and tests. Use interactive controls to accept user answers, check them for correctness, and assign a score for the problem.

Some controls are appropriate for interactivity during simulations, some are useful in problem handling, and some are useful in both situations. We'll present these controls in the next section.

5.5.5.1 Editfield



Click on the editfield icon and place it on the description window. Although the height of the editfield cannot be altered, its width is adjustable. Drag the small rectangles of the selected editfield and set the width to a new value, and move the editfield to a new position. If the edit mode is set to off you can click on the editfield and enter the desired text or numbers.

In Edit mode, double-clicking on the editfield will bring up the editfields properties window. From here you can set the position and the width of this item on the upper panel. Next, choose the editfield's function on the lower panel. A variable can be assigned to this editfield or it can be an input field to receive the answer to a question in a problem file.

If you use the control to input the student's answer, then you must provide Newton with the correct answer. This is the number that the student should calculate and enter into this editfield. For two reasons we must allow for an acceptable tolerance for the student's answer. For one thing, real world solutions may have answers that can't be given exactly. It is also possible that Newton's solver may yield slightly different results from one run to another. Enter the acceptable difference between the nominally correct answer and the student's answer in the tolerance field. If the student answers correctly, he/she will be credited with a certain number of points. The next editfield tells Newton the number of points the student will get.

If you choose to 'assign variable to the control', then you must enter the variable name into the editfield. However, you don't need to know the variables by heart, Newton does that for you.

Click on the  icon and browse the variable from the list. Select a variable and click on the insert button. This places the variable name into the assigned variable edit field. Click on the OK button on the editfield properties window and observe that the control now displays the value of the assigned variable. If the edit mode is switched off, you can navigate into the control and type in a new value for the variable.

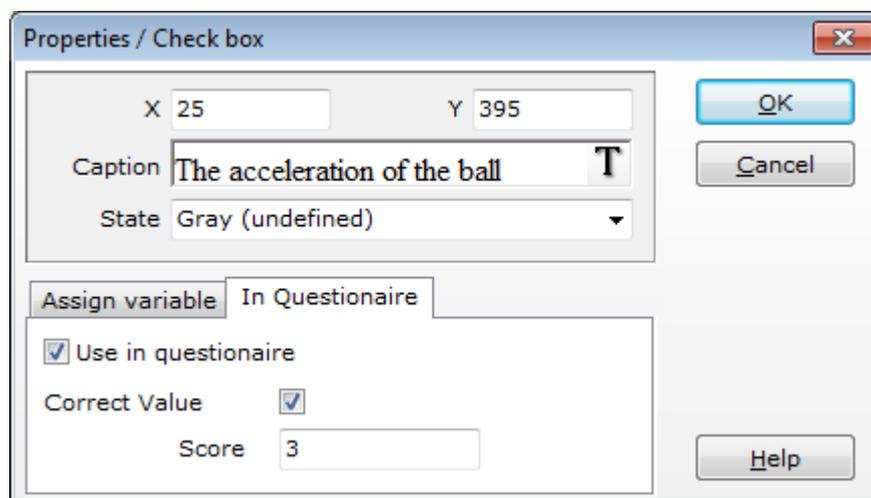
Assigned variable

 ReadOnly
 f_x

5.5.5.2 Checkbox

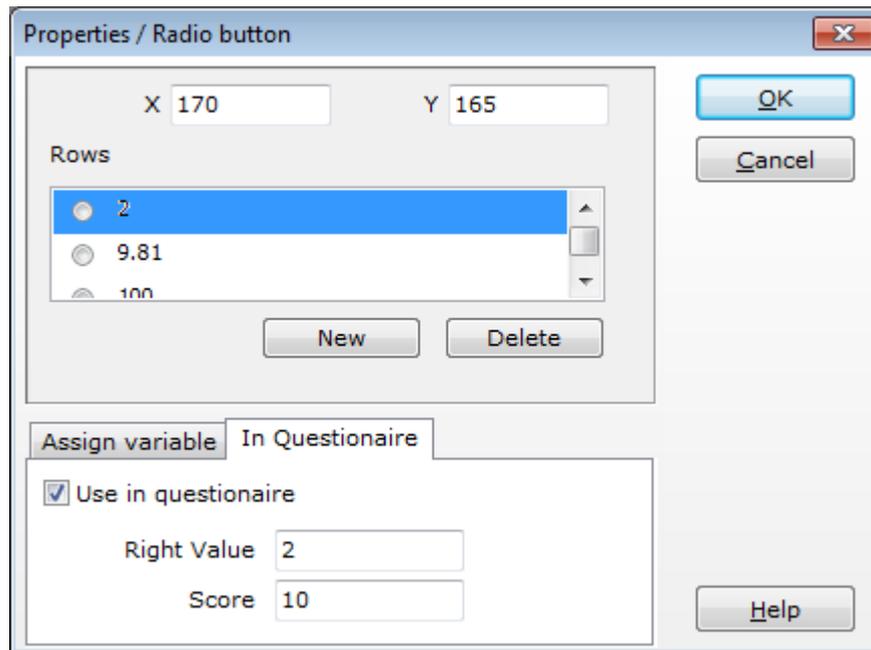
This control can be used for yes-no questions in problems, or to assign Boolean variables to the object. For example, you can assign the visibility of the bodies with a checkbox.

To place a checkbox on the description window, click on the checkbox icon on the description bar and then on the description window. Double-click on the checkbox and its properties window appears. Here you can set the position of the checkbox or change the caption (the text written after the small rectangles). The State combo box can assume three different values—checked, unchecked and grayed. The grayed choice indicates that the checkbox does not have a defined answer. You will encounter it in some of the problem files. The box will also be gray when you have not yet answered a yes-no question.



Before you can set up a checkbox, you must choose a function to use with this interactive control. If you choose “use in questionnaire,” you must enter the correct value in the “Right Value” checkbox and the score (points) that the student will get for the right solution in the Score window. If you choose the “assign variable to the control” option you can browse for the variable by clicking on the *f_x* icon. Newton filters the variable list, presenting only variables of acceptable type. For this function Newton filters out all but the variables that have two states. Choose the correct variable and click on the insert button. The window closes and the variable name is placed into the assign variable editfield. All settings are complete, so click on the OK button. If the edit mode is switched off at the description window, you can change the state of the checkbox.

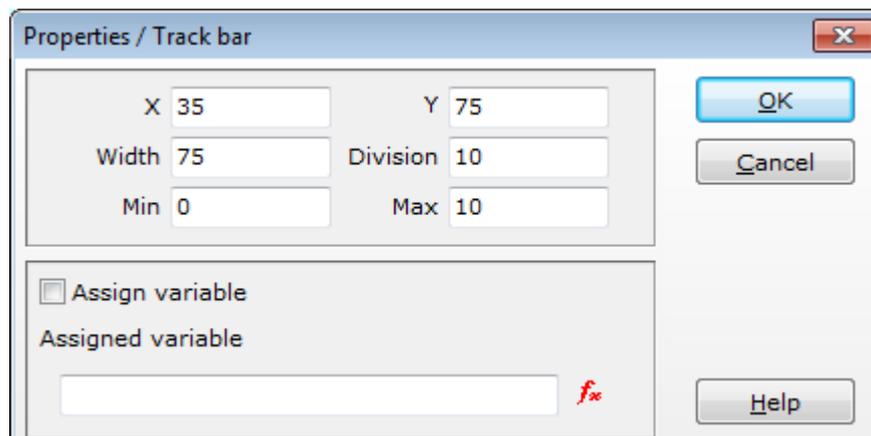
5.5.5.3 Radiobutton



The Radiobutton is only used in multiple choice problem files, where the student must select the correct answer from a list of two or more possible answers. To place this item on the description window, click on its icon on the description bar. Double-clicking on the Radiobutton brings up its properties window, displaying all its settings. You can change its position via the X and Y coordinates in the “Checked” box you may (optionally) select one answer that is initially, by default, given a checkmark. In the Rows editfield the possible answers are listed. Each line is ended by pressing the ENTER key. Next, enter the number of the right answer and the score that the student will earn for the right answer. Click on the OK button to close the window. If the edit mode is switched off, you can select any of the radio buttons by clicking over it.

5.5.5.4 Trackbar

The trackbar can be assigned to variables of real type. Use the trackbar for variables (e.g., certain physical quantities) that have maximum and minimum limits; that is, they are defined in a given interval. Elasticity, for example, is defined over the interval $[0..1]$. Any variable can be limited to an interval. If for any reason you want to constrain a coordinate component of a body between limits, use this interactive control.



Click on the trackbar icon on the description bar and place the control on the description window. Double-click on the item to invoke the properties window with which you can set the properties of the trackbar.

On the upper panel of this dialog you can reposition the trackbar or change its width.

Set the Min and Max values to establish the upper and lower limits.

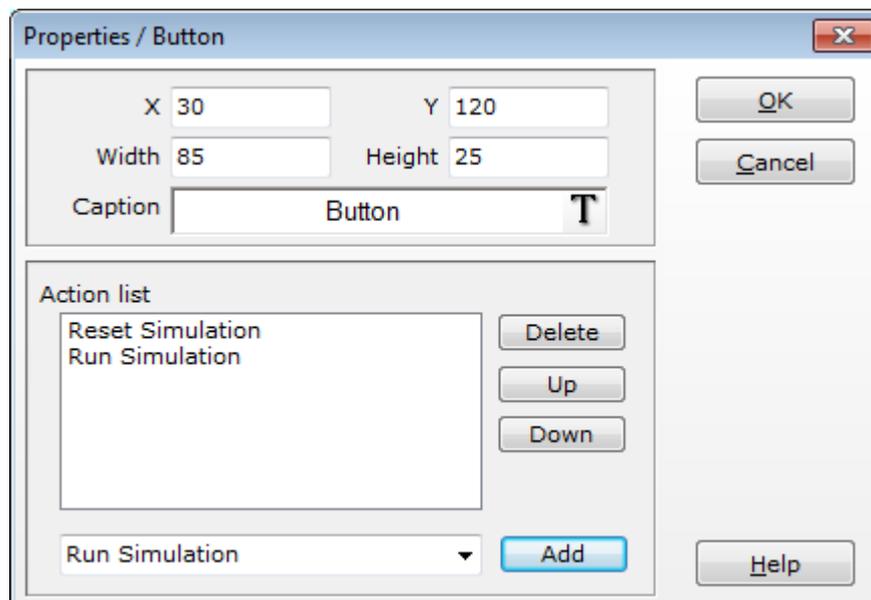
The division parameter determines the value with which the given interval must be divided to achieve the desired step size between two adjacent values. For example, the settings shown on the screen shot to the left indicate that all the integer numbers from 0 to 10 can be assigned to the variable.

You assign a variable to the control in the same way as seen earlier for the other interactive elements. If you know the name of the variable you can enter it in the variable field. If you don't remember its name, you can browse for it in the list that comes up when you click on the  icon. You accept any parameter changes by clicking on the OK button. If the description window is not set to Edit mode, you can drag the trackbar with the mouse, Newton will update the value of the assigned variable when you release the mouse button.

5.5.5.5 Button

This special button differs from the other interactive controls. We don't assign a variable name to a button, but rather one or more "actions." When the student presses this button, Newton will execute the actions in the Action list in sequence, one time, and then stop. There is an action to run the simulation and another to reset the simulation.

Place the button on the description window using the by now familiar steps: click on the icon, move the object with the mouse, and click on any point to invoke the description window where you can position it. Double-click on the item to open the button's properties window.



By setting parameters in the upper panel you can set the button's position, and adjust its height and width. Remember that you can also adjust the height and width using the mouse. Change the button Caption in the caption editfield.

In the lower panel you can create and edit the Action list. Click on the triangle at the right side

of the combo box and select an action. Next, click on the 'add' button to place the action into the action list. To delete an action or to change the order of the actions, use the buttons next to the action list. To accept the changes, click on the OK button. To test the Action list, switch out of edit mode and press down the button to begin execution of the actions.

5.6 Creating Problems and Problem Sets

Newton provides tools to make problem sets. Problems help students improve their problem solving skills and tests their knowledge of physics. The 3D scene can illustrate the exercise before the student submits the answer, and/or it can provide information after the student submits his answer. Newton is also able to solve the problem numerically and check the student's answer.

Newton offers the ability to give the student one or more hints—an instruction, a detailed calculation, or step by step hints. Step by step hints enable the student to stop requesting hints after one, two, or more hints. Using multiple step hints that become progressively more complex suits the student who needs only minor help as well as the student who needs complete support.

Students can measure their knowledge using Newton's scoring feature—correct answers win points toward a higher score, while the use of hints leads to a lower score. In a problem set, each problem is scored and a total score is derived.

We will now show how to make a questionnaire containing hint and solution pages using the interactive tools. The chapter 'making a problem set' will describe how to bundle the problems into a problem set. The chapter 'solving a problem set' will illustrate the process of answering the test questions.

5.6.1 Creating a problem

These are the typical steps taken to create a problem:

- Frame the question.
Create the text description object and compose the question in a few sentences.
- Placement and adjustment of interactive element
Generally, there is enough space left after placing the question on the Description window to place one or more interactive elements. These elements will be used to gather the answers. Three different elements can be used according to the type of question and answer.
 - If asking for a value, use the editfield.
 - If offering multiple choice answers, use the radiobutton.
 - If posing a yes-no question, use the checkbox.You can have more than one question in a problem. For each question, you must place an interactive element on the description window. For each interactive element, you are required to provide the right answer and score.
- Accompanying simulation
You may use any of the objects and bodies to make an experiment. If your experiment incorporates motion, it is a good idea to place a button on the description window with an action list Reset, Run. The student will be able to run the animation more than once. See the chapter Interactive elements for details.
- Writing hints
Instructions or hints should begin on a new page. This will hide them from the student so that they can only be seen in exchange for a reduction in score. If the student asks for hints, her possible score will be reduced by ten, twenty, or any percentage, as set by the creator of the problem. After creating a new page, change the type of the page to hint. This command

can be found in the context menu: Set page as hint. Now place the pictures, help text, and equation(s) on the window. Finally, in the context menu (right click on the description window) click on the item 'Hint Score Reduction....' A small dialog appears with which you give the percentage that will be used to decrease the score.

- Writing a solution

It is a good idea to provide a “solutions page” for each problem because if the student really has difficulty solving the problem, he can at least step through the solution and learn from it. However, even if the student solves the problem correctly, it can be useful having an official solution because there often are multiple ways to solve a problem. If the student asks for the solution before submitting his answers, he will lose the opportunity to earn credit points for this problem.

Just as with the hint page, the solution page should start on a new, separate page that can be kept hidden until the student asks to see it. To set the page’s type to solution, click on the context menu (right button, click anywhere on the description window) and select the 'Set page as solution' command.

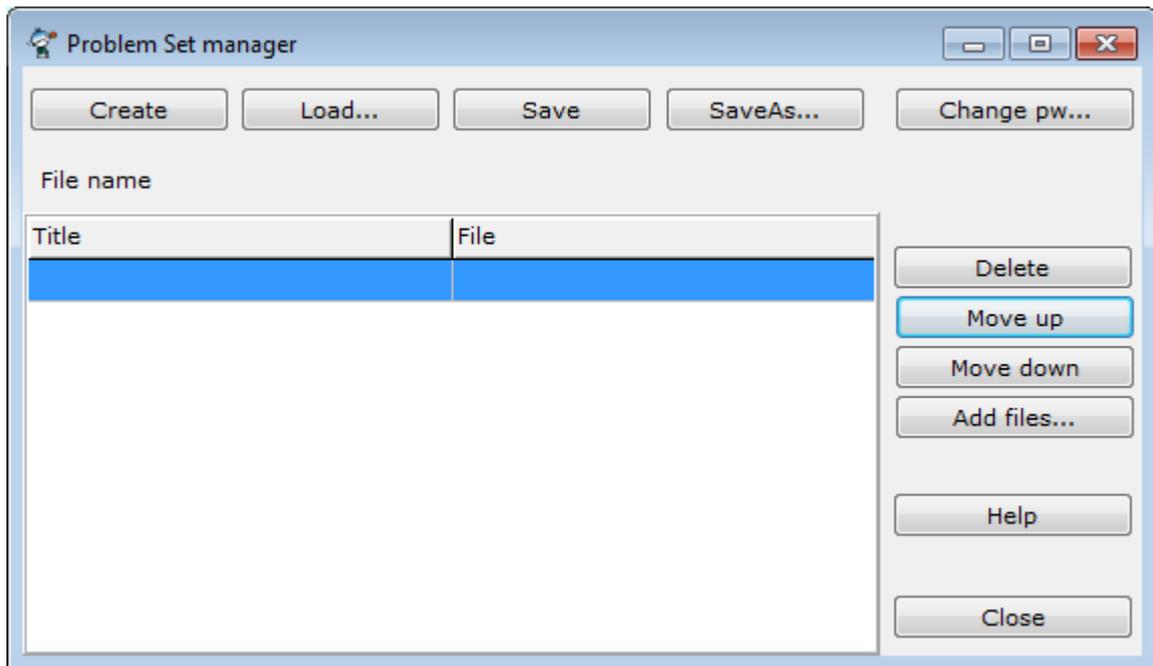
You can carry out these steps in any order. When you are finished, save the problem by clicking on the save icon. In the dialog that appears, locate a combo box named **filter** and select file type .pb. Replace the asterisk (*) with a file name and click on the save button.

Newton automatically switches to problem solving mode after loading a problem file. This hides all the editing and adjustment possibilities, preventing the student from prying into the hints and solutions. In place of the Object bar, you will find the Problem bar, which makes it easier to manage problems and problem sets. If you want to modify a problem file, open it and click on the problem menu edit command. You will be challenged by Newton to enter your password before you can gain access to the normal mode. This is another precaution to prevent inappropriate behavior on the student’s part. After first installation, Newton by default uses the password “Newton.” This can be—and should—be changed soon after installation. If you forget the password, uninstall and install Newton. The password will once again be set to “Newton.”

5.6.2 Creating a Problem Set

Once you have created a number of problems on a given theme, you can bundle them into a “problem set file.” This file contains a list with the problem file name, path, and title. Newton automatically switches to problem solving mode after loading a problem file. The Problem bar will replace the Object bar to help you manage the problem set and scoring.

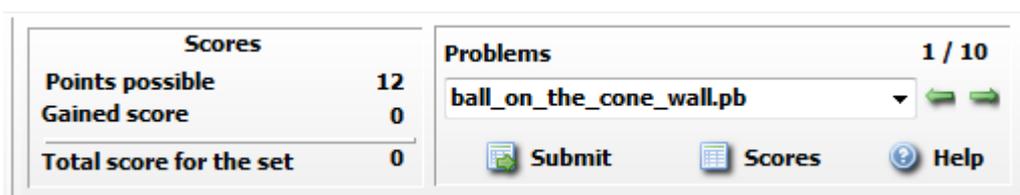
Because the problem set file stores only the filename and path of the problem file, it is a good idea to move the files to their final directory before creating the problem set file. Better still, create a new folder to hold the files, and save the problem set file into the same directory. A result of this is that the path will be relative, and the files can be moved together into other directories.



Click on the File menu and select the 'Problem Set Manager...' command. This will invoke a dialog where all of the tasks associated with problem sets can be carried out. Initially, the table is empty, but its cells eventually will contain the names and titles of the problems. Click on the 'Add **files...**' button and browse the problem files on your hard drive(s). Select the related files and click on the **open** button. The files immediately appear in the table. The order of the files is important, because this will be the order that the program will use when presenting problems to solve. Of course, the student can freely choose the first problem to solve. The up and down buttons near the list allow you to move selected row(s) up or down in the list. If there are rows you don't need anymore, simply select them and click on the delete button. When you have finished collecting the problems and putting them in the correct order, you can save the problem set using the Save button. If you want to make another problem set, click on the New button. If you want to modify an earlier problem set, click on the open button, locate the problem set, and make your changes. Be sure to save the updated file.

5.6.3 Solving a Problem Set

Newton automatically switches to problem solving mode when Loading a Problem is executed. The program closes all open example files and prevents the use of the simulation tools to get the solution of the problem. All the menu titles disappear except the help title, and the problem menu title appears. In the place of the Object bar, Newton presents the Problem bar. This helps you to navigate the problem file and to summarize the scores.



The left panel of this control bar shows the score and how many points you will get if your answer is correct. When you request a hint, the number of points you receive will be reduced. The Gained score shows how many points you have accrued so far. The Total score for the set

is the maximum score you could achieve if you solved all the problems correctly. On the right side of the panel there is a combo box listing the problem titles. Select a problem to bring it to the screen so you can work on it. You can scroll through problem lists with the arrow buttons. Above the arrows you can see that you are currently on problem 1 of a set of 10. In this example the problem is 1/10. This means that there are 10 problems in the set.

Three buttons remain to explain. Use the first to submit your solution. After entering all the answers for this problem, you tell the program that you have finished and your answers are final. The program immediately checks the answer and indicates if it is right or wrong. If the answer is right then the background of the interactive element will be green, if wrong the background will be red. Now that you have completed your first problem, you can ask to see the hints and solution pages hereafter.

Problem title	Points possible	Points earned
ball_on_the_cone_wall.pb	0	Unsolved
ball_on_the_hemispheres_wall.pb	0	Unsolved
ballistic_pendulum.pb	0	Unsolved
box_linked_to_two_spring.pb	0	Unsolved
brick_collide_pail.pb	0	Unsolved
catapult.pb	0	Unsolved
conservation_momentum_two_b...	0	Unsolved
constant_force_30degree.pb	0	Unsolved
constant_force_30degree_frictio...	0	Unsolved
constant_force_size.pb	0	Unsolved
All	0	0

Clicking on the score button invokes a dialog showing each problem and its available score for the correct solution. The last column displays the points you actually received for your solutions. The bottom row gives a summary of the scores. You can close the dialog by clicking on the Close button.

The third button of the group is the help button: use it to get hints if you are stuck.

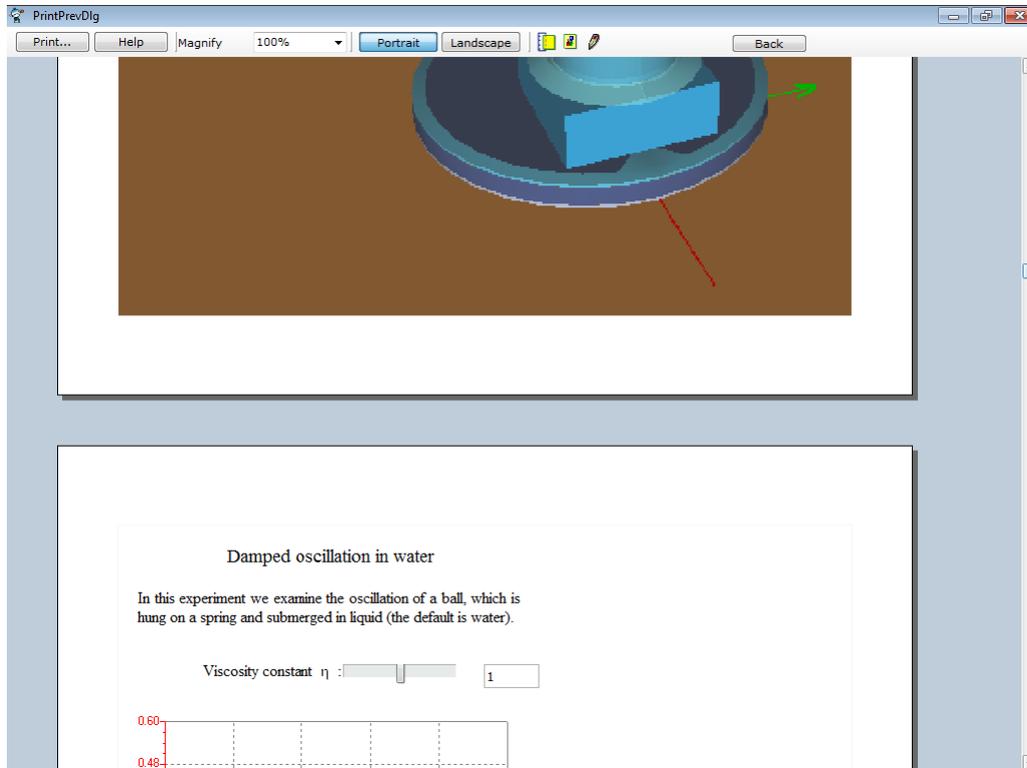
When you have finished all the problems, Newton indicates your actual score. If you want to leave the problem set without finishing completely, you can use the 'close' command in the problem menu.

5.7 Printing and Exporting

The software supports a broad variety of exporting possibilities. The contents of the 3D window and the description window can be exported into picture or VRML files and of course can be printed. Furthermore, simulations can be saved as avi files.

5.7.1 Printing

To print the contents of the 3D or description windows, use the **print** command in the **file menu** (or the shortcut CTRL+P).



After you click on the print command, a print preview window appears (see above). Various aspects of the print can be adjusted with the buttons and icons on the tool bar at the top of the window. When finished, press the **Print...** button to send the image to your printer. Before printing begins, the Print window opens where you can define the choice of printer, the printing range, and the number of copies. You can use the loupe to rescale the print preview. You can choose portrait or landscape mode; set the margins via the () icon; and modify the view of the 3D windows by clicking the 3D () icon.

5.7.2 Exporting

The program has wide range of exporting possibilities. You can save the 3D window (or part of it) to a picture file, you can save the whole 3D window in VRML format, and you can save the simulations as avi files. You will find the Export command in the file menu.

- **Exporting into VRML:** With this command, the whole 3D window can be saved in VRML (Virtual Reality Modeling Language) format.
- **Exporting into AVI:** Saves the last simulation in an avi file, as it was seen on the 3D window.
- **3D Screenshot:** Saves the whole active 3D window or a part of it into a bitmap or a Jpeg file.

5.8 Newton Interpreter

Newton Interpreter is a very useful tool which can be used in several places.

1. Definition of the curve for diagrams

When you make a new curve on a diagram you must define what you want to plot. In this definition you will need to use references for various object quantities (variables) as well as the mathematical operations or functions between them. This definition can be single- or multi-line.

2. Assignment of interactive elements in the Description Window

Interactive elements can be used as both output and input of a variable. This way you can put out the relevant physical quantities on the description window and you can examine their influence faster and more comfortable. Actually you can't use expression here only variable name, but in the dialog named Interpreter's Symbol you can define new variables and link to these elements.

3. Writing mathematical expression in the edit field instead of value only

Generally in Newton you can write simple expressions into the edit fields of the dialogs. For example, if you derived the equation for the position of a body theoretically in a problem, you don't have to calculate in a pocket calculator the result, but directly type into the edit field and the interpreter will evaluate it and substitute the result. It has a special rule you have to use, that these expression should start with the '=' symbol. For example, you can type into a edit field the following:

$$= 1/2*9.81*2$$

After pressing the Enter button it will be changed to 9.81. Or another example:

$$= \sin(\pi*3/2)$$

This gives you the value -1. If you type a wrong expression and want to correct it you can press the **Left Arrow** button on the keyboard and you will get back the earlier expression. With this button you can alter between the last evaluate result and its expression.

In this chapter we will discuss the rules of the syntax, the functions and the variables of the possible expressions.

5.8.1 Simple Mathematical Expressions

In these one-line expressions you can join together any global constants, variables and mathematical functions with arithmetic operators.

5.8.1.1 Constants and Variables

Loading an example file, or creating a new one the program automatically creates several variables. These variables are referred to the environment, to the physical quantities, to the appearance, etc.

They are represented by strings, and have datatypes. Let's see them:

- Integer (`Integer`)

This is the well known natural numbers (1, 2, 3, ...), their negatives (-1, -2, -3, ...) and the number zero.

- Real (`Real`)

This type include both rational numbers, and irrational numbers.

- Boolean (`Boolean`)

It can have two values: **true** or **false**

- String (`String`)

It is a sequences of characters

- Vector (`Vector`)

It is three real number put together to represent vector quantities, such as the position, velocity, acceleration of the bodies.

In the next list, you can find special types, called **References**, which refer someway to other existing variables:

- Alias (`Alias`)

It enables you to refer to a variable with another variable name. For example creating an reference and set it to refer to `ball.p[1]` , which is an existing variable, you can use the (probably shorter) reference name instead of the `ball.p[1]`.

- Initial Values (`Inivalue`)

It enables you refer to the initial value of any physical quantities, which may alter during the simulation. It is used similar way as the alias, you create an Initial Value, set it to refer to a variable, then use the name of the initial value in the expressions.

- Formula (`Formula`)

All formula type variables have an assigned expression which evaluated on the fly, resulting the value of the variable at any time, when it's needed. It is strictly read-only type.

You can browse the global variables in the dialog called Interpreters's Symbol where you will

find some explanatory text either.

5.8.1.2 Mathematical operation

You can use the following arithmetic operations, here i_1, i_2 has integer; r_1, r_2, a, b, c integer or real, v_1, v_2 vector type.

```
-r1          negation
r1 + r2      addition
r1 - r2      subtraction
r1 * r2      multiplication
r1 / r2      division
i1 div i2    integer division
v1 + v2      vector addition
v1 - v2      vector subtraction
v1 cross v2  vector product
v1 dot v2    scalar product
a in [b .. c] comparison, true if b < a < c
```

5.8.1.3 Boolean operation

In this chapter we get through the Boolean operations, which take part in conditional statements:

If a and b are integer or real then it is

```
a < b      is true if a less than b
a > b      is true if a bigger than b
a <= b     is true if a is less or equals to b
a >= b     is true if a is bigger or equals to b
a = b      is true if a equals to b
a <> b     is true if a does not equal to b
```

if c and d are Boolean then it is

```
not d      is true if d is false (negation)
c or d     is true is any of them is true (disjunction)
c xor d    is true if not equals (exclusive disjunction)
c and d    is true if both of them is true (conjunction)
```

5.8.1.4 Mathematical Function

Here we list some of the usable function, but all of them can be find in the dialog of the Interpreter's Symbols. Here x is real or integer, r is real, a is integer, v is vector type variable.

function name	returning type	description
<code>sqr(x)</code>	real	Gives the square of x
<code>sqrt(r)</code>	real	Gives the square root of x
<code>sgn(x)</code>	real or integer	Gives the sign of x : {0, +1, -1}
<code>abs(x)</code>	real or integer	The result is the absolute value of x
<code>exp(x)</code>	real	Exponential function.
<code>ln(x)</code>	real	Natural based logarithmic function.
<code>sin(x)</code>	real	The trigonometric functions
<code>cos(x)</code>		
<code>arcsin(x)</code>		
<code>arccos(x)</code>		
<code>tan(x)</code>		
<code>arctan(x)</code>		
<code>vlen(v)</code>	real	length of v
<code>random</code>	real	random real number between 0 and 1

random(a)	integer	random integer number between 0 and a-1
time	real	time elapsed from the simulation start

5.8.1.5 Miscellaneous Function

Some important examples of the miscellaneous function, here o1,o2 are object type, r is real, v1,v2 are vector :

function name	returning type	description
Dist(o1, o2)	real	distance between the o1 and o2 objects
AtoB(o1, o2)	vector	vector which point from object o1 to object o2
Round(r)	integer	Rounds the real r to the nearest integer
DotNorm(v1,v2)	real	Scalar product dividing by abs(v1)*abs(v2), if any abs=0

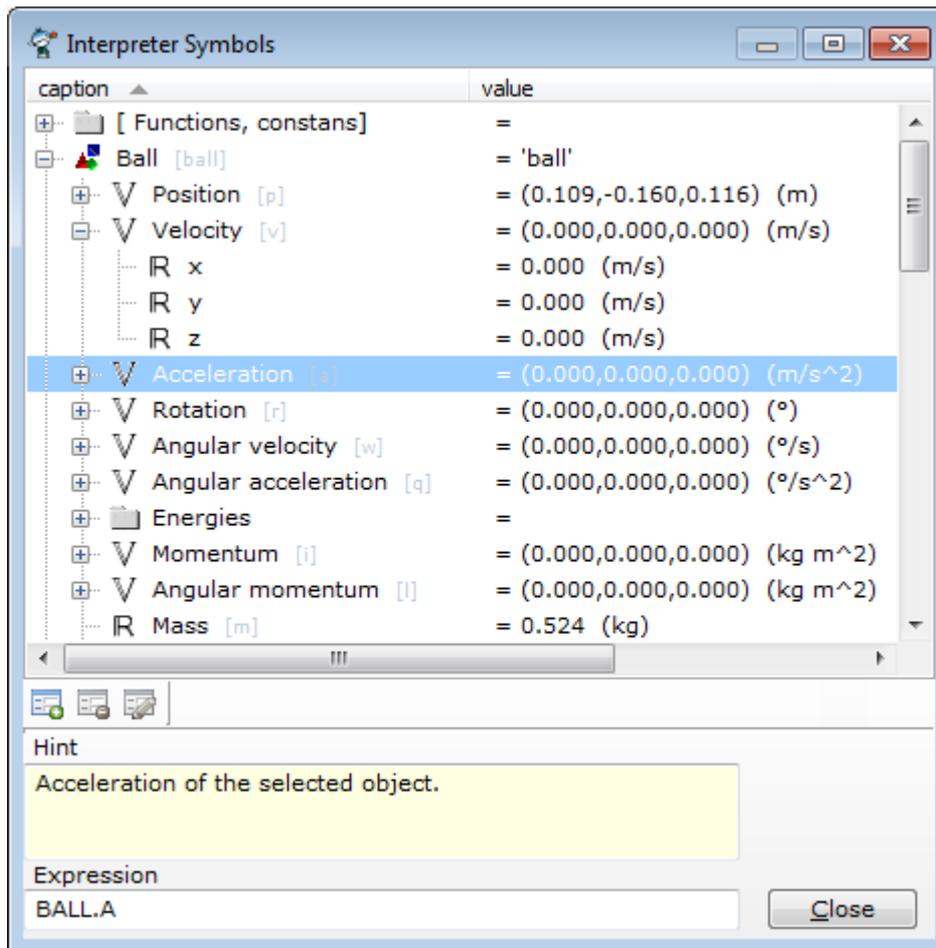
5.8.1.6 Browse Interpreter Symbols

An important feature of Newton is the variables which denote the value of various parameters of objects. In the Variable window you can examine not only the variables defined for this experiment, but also the available functions, constants and operators. This window can be called up where needed; for example when creating a curve or to assign a control to a variable. Look for this icon  in the dialogs and click on the icon to open the window.

The variables are grouped in a tree structure for easier searching. The branches can be expanded by clicking on the  icon, and can be hidden by clicking the  icon. A short hint is displayed when you have selected a branch.

There are three main branches:

- Functions, constants, operators
Available functions include the trigonometric and coordinate transformation functions. Some important constants such as $\pi = 3.1415$, are included, as are the basic mathematics operators of addition, subtraction, multiplication, etc.
- Global variables
This branch contains the variables of the environment, including the time, the gravitational constants, the coulomb constant, etc.
- Objects
Newton lists the objects' variables in this branch. If this branch is empty, no object has been placed on the scene so far.



Every variable in Newton has a type. The functions' return values are also typed. The type of the variables and functions are displayed by way of small icons near the name. There are five possible types: \mathbb{V} vector, \mathbb{R} real, \mathbb{Z} integer, \mathbb{O} object, \mathbb{B} boolean.

Press the **Insert** button and Newton will put the expression into the editfield of the window from where this dialog was visualized.

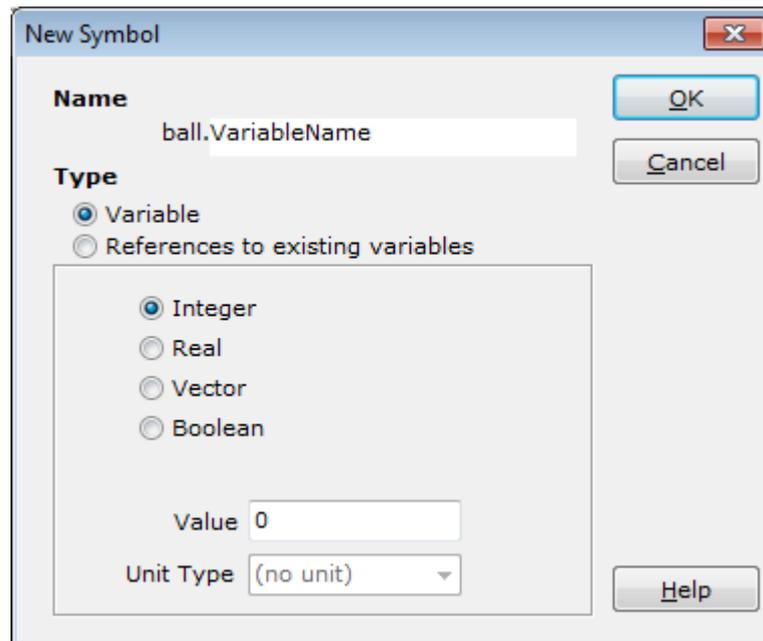
If you select an item in the list, the editfield displays the relevant insertable expression.

The buttons can be used to create, modify and delete user-defined symbols.

5.8.1.7 New Symbol

In Newton program you can create your own symbols: variables and references. The variable is a symbol denoting a quantity whose value may vary over the course of an experiment, you can change it values and use in evaluation. It has type, the possibilities are boolean, integer, real, vector, string.

The following window can be called up from menu of the View / Interpreter Symbols dialog.



To create, type a new variable name, select 'variable' at the type radio box, then select the type of the variable. At the value edit field you can give its value. The variables can have unit types, with the unit type combo box you can set which one it should be.

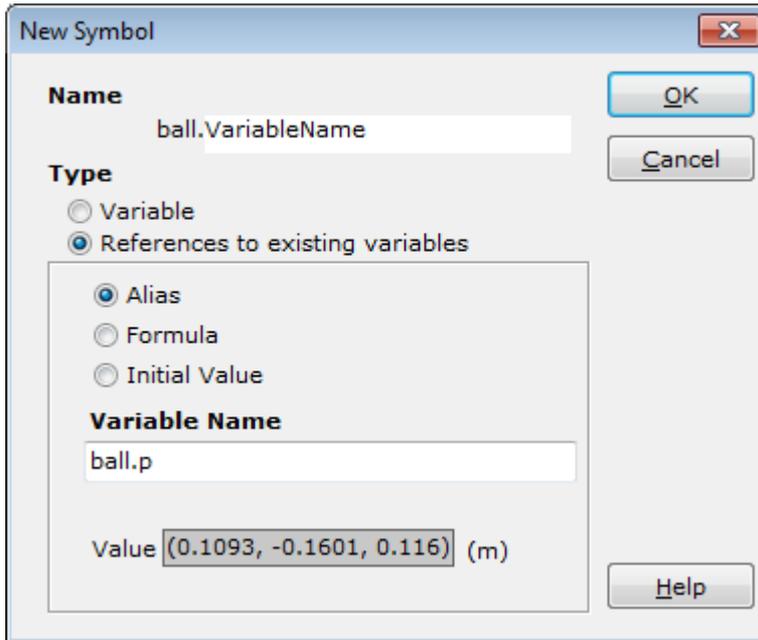
Moreover you can create special type of symbol, it is called reference. They make access to reach the other variable in three certain way. The name of these three types: the alias, formula, initial value.

Alias is the simplest, wherever it is found in a expression or in a script, the interpreter will substitute with the variables it is referring to.

Formula is read-only type symbol, you can create an expression, give a name to it, and you can use it in the expression. When the interpreter found it will evaluate it and use its value. Somehow It is similar to a function, since anywhere it is used it will return with its value.

The initial value store the value of a certain variable at the initial moment and it remains constant at the running.

To create reference, give the variable name, select 'References to existing variables'. Then you can change the appropriate type: Alias, Formula, Initial Value. Into the edit field you have to write the variable name for the alias and for the initial value or the equation for the formula. Last row show the value of the reference with its unit type, which is the same as the referred variable.



5.8.2 Multi-lined Expressions

The NEWTON interpreter can evaluate multi-line expressions also. With the built-in, pascal like language you can write small scripts, it makes the complicated mathematical expressions easy to implement. This language has the Pascal-like terms to create different type of variable, conditional statement, loops, etc. In the next chapter we discuss these things.

5.8.2.1 Global Structure

Let's first take a look at the global structure of a multi-lined code. The main frame is:

```

var

    // variable declaration
begin

    { this is a multiple-line
      comment }

    // this is a one-line comment

    // commands
    result := 2*14+5;
end.

```

You can make variable declaration between the **var** and the **begin** rows, and between the **begin** and the **end** rows you can implement your code. Note that it is important to put a point after the code terminating end. Anywhere in the code you can make comments, there are two kinds of comment, with the // character you can make a single line comment, it begins where you put it, and it remains until the end of the line. The second way you have to sign the beginning point (with the { character) and the end point (with the } character) of the comment.

You also need a `result := ...` line, this assignment define the returning value of the code.

If no variables are needed, the **var** keyword can be omitted:

```
begin
    // commands
    result := 2*14+5;
end.
```

Note that in a block every command must terminate with a semicolon.

5.8.2.2 Variables Declaration and Assignments

In the variable block you should define all your own variables you want to use in the code. Of course the global variable still can be used at anytime.

The possible variable types which can be defined here is the the following:

```
I : integer;    // integer
A : real;      // real
B : boolean;   // boolean
S : string;    // string
P : vector;    // vector
```

As you can see, the variable name(s) is (are) followed by a colon and then comes the variable type. The definition ends with a semicolon. These variable types are already discussed in the chapter 'Constants and Variables'.

Let's see some examples:

```
var
    i: integer;
    R: real;
    S: string;
    b : boolean;
    v1,v2 : vector;
    i1, i2: integer;
    b1, b2, b3: boolean;

begin

    // assignments
    i := 1;
    r := 10.3;
    s := 'text';
    b := true;
    v1 := (0,0.2,1.2);
    v2[1] := 1.2;
    v2[2] := 2.3;
    v2[3] := v1[3] + 1;

    i1 := i;
    i2 := i+1;

    b1 := not b;
    b2 := b1 and b;
    b3 := false;

end.
```

You should use the := characters to assign a variable to another variable or a constant. All text data must be put between apostrophe and for boolean variable you can use the true or false term. To a vector you can give value in two way, above first we used a vector constant directly, it is put in parenthesis and the component are separated by colon. The second we set the vector component separately, this way you have to put after the vector name the index of the component in [] bracket.

5.8.2.3 Conditional Statement

The conditional statements are requests to the computer to evaluate a given condition, and if the condition is true, the statement block following shall be executed, otherwise the execution shall skip the following statement block. If the conditional statement contains **else** branch then that will be executed in case of false value.

The conditional statement is implemented in the following way:

```
if condition then statement1;
```

OR

```
if condition then statement1 else statement2;
```

The condition is a logical expression (results boolean), the statement1 and statement2 are single commands or so called **command blocks**. The command block contains more than one single line between **begin ... end** words. Thus the conditional statement are implemented as the following:

```
if condition then
begin
    // commands

end else
begin
    // commands

end;
```

Examples:

(1)

```
if a < 0 then a := -a;
```

(2)

```
if a < 0 then
begin
a := -a;
end;
```

(3)

```
if a < 0 then
begin
a := -a;

end
```

```
else
begin
  a := 0;
end;
```

5.8.2.4 Loops

A loop is a sequence of statements which is specified once but which may be carried out several times in succession.

There are two kinds of loops:

Count-controlled loops

This loop executes the subsequent statements by an explicit number of times.

Examples:

(1)

```
for i := 1 to 10 do
begin

  // commands

end;
```

(2)

```
for k := 20 downto 5 do
begin

  // commands

end;
```

Condition-controlled loops

The loop condition is evaluated before the loop and executes until the 'condition' is true.:

```
while condition do
begin

  // commands

end;
```

Example:

```
i := 0;
while (i < max) and (arr[i] <> value) do
begin
  i := i + 1;
end;
```


Part

VI



6 Glossary

This glossary chapter contains a short (one or two sentences) description of the commands and icons that can be found in Newton's menus and windows.

6.1 Command in Menus

These are the commands in Newton's menus.

6.1.1 File

Use this menu to open and save your example files or to exit from Newton.

New	Brings up an empty working plate upon which you can build your own mechanisms.
Contents...	Shows the contents dialog.
Open...	Loads a previously saved experiment file. The extension of experiment files is .EX, the template file is .NTP, the problem file is *.PB and the problem set file is .PBS. You can use the dialog box to select the appropriate directory and/or file name. Note that you can open several examples at the same time.
Reload	Loads a just saved experiment file. The program memorizes the last five saved files.
Save	Saves changes that you have made to the example currently open.
Save as...	Saves changes to an example as a new example (and preserves the original example).
Close	closes the file currently selected.
Close all	closes all the opened files.
File information	Shows a dialog with details about the active file.
Export	
VRML file...	Exports the active window into a VRML file. This allows you to use Newton objects in other CAD programs and publish them on the internet. The VRML format allows viewing of the exported mechanisms from any angle using a VRML viewer. VRML viewers are available on the internet. A free VRML viewer can be downloaded at www.parallelgraphics.com/ and

AVI file...	http://www.ca.com/cosmo/ Exports the recorded simulation into an 'avi' video file. It can be played later with any commonly used media player (e.g. Windows Media Player, Winamp, RealPlayer, etc.).
Picture...	Exports the Scene into a bmp or jpg file.
SWF file...	Exports the recorded simulation into an swf file.
XHTML file...	Exports the recoded simulation, and the descriptions into an xhtml file.
HTML file...	Exports the recoded simulation, and the descriptions into an html file.
Print...	Shows the print view of the scene and the description. Several settings can be adjusted and the entire screen can be printed.
<List of recently opened examples>	switches to another loaded file.
Exit	Exit allows you to end your Newton work session. You will be warned if you have not yet saved your example(s).
6.1.2 Edit (3D Window)	
Undo	You can undo the last operations (up to 15).
Redo	You can redo the last undo operations (up to 15).
Cut	Copies the selected objects onto the Clipboard and deletes them from the scene. All the relations (link, anchor) among the objects will be retained.
Copy	Copies the objects on the Clipboard. All the relations among the objects will be retained.
Paste	Takes the objects copied to the Clipboard and places them in the 3D window.
Delete	Deletes the selected objects.
Rename...	Changes the name and/or the identifier of the selected object.
Select All	Select all the objects in the 3D Window.
Select next related	Select the next related object. This

	menuItem is visible only if it's connected to a joint.
Invert Select	The unselected objects become selected and the selected objects become unselected.
Select by Name	Presents a dialog with which you can select an object by name and identifier from a list.
Link/Unlink	Link or Unlink the selected object.
Anchor To	Anchors the selected object to another.
6.1.3 Edit (Description Window)	
Edit mode	Switches to Edit mode. This mode is used to create new text, pictures, diagrams, etc. in the description window.
Undo	You can undo the last operations (up to 15).
Redo	You can redo the last undo operations (up to 15).
Cut	Copies the selected objects onto the Clipboard and deletes them from the scene. All the relations (link, anchor) among the objects will be retained.
Copy	Copies the objects on the Clipboard. All the relations among the objects will be retained.
Paste	Takes the objects copied to the Clipboard and places them in the 3D window.
Delete	Deletes the selected objects.
New Page	Creates a new page.
Delete Page	Deletes page currently selected.
Next Page	Jumps to next page.
Previous Page	Jumps to previous page.
Set Page As	Set the type of the current page. The Normal type page is chosen as default; the other four types are used only in problem files.
Normal	The default type of the description

	window page.
Hint	Hint pages contain the problem solving hints and help.
Solution	Solution pages contain the solution to the problem.
New Item	Creates an item that you chose from the submenu.
Hint Score Reduction...	Displays the dialog for setting how many points the student will lose if he asks for the hint.
Settings	
Pen and Brush	Before drawing, you can select line style, color, and fill style of the ellipse. Line and ellipse objects already drawn can be edited for pen and brush characteristics.
Snap	The snap setting controls the grid upon which the elements are placed. You can switch snap on or off, and you can enter the number of pixels between grid locations.
Papercolor	The background color of the description window can be adjusted here.
6.1.4 View	
Camera	This menu lets you set the camera position.
Normal View:	gives a perspective view.
X-Y Plane	gives a planar (X-Y) top view
Y-Z Plane	gives a planar (Y-Z) side view
X-Z Plane	gives a planar (X-Z) side view
Change To	Select a camera from the list.
<List of Cameras>	
Go To	points the camera to the selected object.
<List of objects and camera positions>	
New Camera	Create a new camera in the Scene and make it active.
Object Properties...	Use the properties window of the selected object to set the location, velocity, appearance, etc.
Interpreter Symbols...	

3D Window Settings

Displays the 3D window setting dialog. Use it to set grid spacing, to turn snap to grid on and off, to choose coordinate system, etc..

Toolbar Visibility**All toolbars**

Turns all the toolbars on/off

<List of the toolbars>

Turns any toolbar panel on/off.

6.1.5 Simulation**Run / Stop**

Starts the simulation. / If the simulation is running already, Newton will display “Stop” in this button. If the simulation has stopped, Newton will display “Run” instead.

Reset

Sets the parameters to their initial values.

Replay

Plays back the recorded simulation.

Faster (2x)

Multiplies the Virtual time and Time Step parameters in the Settings dialog by 2.

Slower(0.5x)

Multiplies the Virtual time and Time Step parameters in the Settings dialog by 0.5.

Force Field...

Displays the Force Field dialog. With it, you can adjust the forces –Gravitation, Coulomb force, and Fluid resistance.

Settings...

Displays the Settings dialogs. Here you can adjust the time step, virtual time rate, initial/final time, record length, and track length.

Units...

Presents the Units dialogs. Here you can select the units to use when displaying physical quantities in the dialogs.

Run DC/AC Analysis

Run an analysis. This function has effect only if there are elements with electrical properties, example resistors, lamps, etc...

6.1.6 Problem**Try as Problem**

It is visible, if a problem file is edited. Switches the program into Problem Solving mode so you can verify the interactive elements.

Next

Jumps to next problem file.

Previous

Jumps to previous problem file.

Edit	Switches to Edit mode.
Close Problem	Close the problem file
6.1.7 Tools	
Edit code	Opens a script editor.
Problem Set Manager...	Presents a dialog where you can manage problem sets.
General Settings	Displays the Newton Global Settings dialog.
6.1.8 Windows	
New 3D Window	Puts a duplicate copy of the selected 3D window on the screen. In the new window(s), you can set another viewpoint(s). You can edit your experiments in any of these windows while viewing from different viewpoints simultaneously.
New Description Window	Puts an empty description window on screen. Because only one description window can be used in Newton in an example, you cannot create a new description window if there already is one.
Close active Window	closes the active window.
Tile	Arranges the open windows so that they are not overlapped.
Examples	You can jump to any loaded experiment file listed in the submenu.
<List of loaded examples>	switches to another loaded file.
<List of Windows of current example>	Lists the windows of the current example.
6.1.9 Help	
Access Newton's help system with this command.	
Help Topics	Anytime you don't know how to proceed or want more information on a topic, use this menu item or press F1 to access the help system.
Authorization	Everything about the software authorization. See more details in the file DSPNewton_en.chm.
Send us feedback	If you have some suggestion, feedback or wishlist for Newton software please use

DesignSoft Discussion forum	this form to send us. Link to our Company's forum.
Contact technical support	Link to the technical support page.
DesignSoft on the Web	Offers a link to browse DesignSoft's web pages.
Check for Update	Check for available update through the internet.
About	gives you information about DesignSoft, the program version number, and certain other details.

6.2 Commands in Context Menu

If you click on a dialog or a window with the right mouse button, you will generally find a context menu. The menu that appears gives access to commands that are specifically useful in the present context. The commands explained next are listed and grouped according to the context.

3D Window

Click Over Background

Select All	Selects all the objects in the 3D Window.
Transparent mode	Shows all the objects in the 3D window as transparent. It is useful if you want to move a point or a vector, but an object hides it.
Hide Vectors	All the vectors (velocity, acceleration, force) will be hidden.
Store current camera position	stores the current position of the camera, so you can navigate back here by selecting one of the subitems of View / Camera / Go to.
Ray trace	switches between different raytracing modes.
Show All Tracks	Switches on the display of tracks that show an object's path. Affects all the bodies.
Hide Tracks	Switches off the display of all the bodies' tracks.

Click Over Body

Fix at Running	Entering this command causes the body to be fixed in a static position during the simulation; however, the object still
-----------------------	---

	participates in collisions, gravitational, and Coulomb interactions
Show	
Velocity	Shows the velocity vector of the body.
Angular Velocity	Shows the angular velocity vector of the body.
Acceleration	Shows the acceleration vector of the body.
Angular Acceleration	Shows the angular acceleration vector of the body.
Track	
Line	The body will leave a trail as it moves along its trajectory line.
Point	The body will leave points along its trajectory line as it moves.
Add Point	Adds a point on the surface of the body.
Group	puts/removes the selected object into a group.
Properties...	Displays the properties window of the object.
Click Over Joint	
Link To...	Makes a link between a Joint and a body. Click on the command first, then the objects to be linked.
Visible	Makes the joint visible or invisible.
Click Over Spring	
Equilibrium Position	Allows you to change the spring from its initial unstrained length to its desired length.
Click Over Force	
Delete Force	Deletes the force currently selected.
Rotate With Object	If it is switched on, the direction of the force will change with the body's rotation. If it is switched off, the force will remain pointing in the same direction, independently of the rotation of the body.

Description window

Edit mode	switches to Edit mode. This mode is used to create new text, pictures, diagrams, etc. in the description window.
Settings	
Pen and Brush	Before drawing, you can select line style, color, and fill style of the ellipse. Line and ellipse objects already drawn can be edited for pen and brush characteristics.
Snap	The snap setting controls the grid upon which the elements are placed. You can switch snap on or off, and you can enter the number of pixels between grid locations.
Papercolor	The background color of the description window can be adjusted here.
New	
Page	Create new page.
<Items>	Select an item from the list in the submenu reached from the description window.
Set Page As	Set the type of the current page. The Normal type page is chosen as default; the other four types are used only in problem files.
Normal	The default type of the description window page.
Hint	Hint pages contain the problem solving hints and help.
Solution	Solution pages contain the solution to the problem.
Hint Score Reduction...	Displays the dialog for setting how many points the student will lose if he asks for the hint.
Diagram Context menu	
Clear Curve Points	Deletes only the points of the curve and leaves the curves themselves. If the simulation continues running, the curve will continue being drawn.
Properties...	Displays the dialog of the diagram properties.

6.3 Icons

Newton has a number of toolbars. Use the View/Toolbars command to see and change their visibility. Here's a list of the commands on the various toolbars.

Standard bar

	New	Create new experiment file.
	Contents	Open the contents window.
	Open	Open a new experiment file.
	Save	Save the current experiment file.

Scene bar

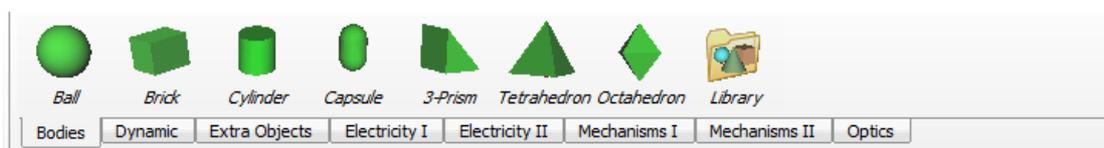
	Geometric mode	The geometric edit mode is useful for move and rotation operation when you don't want the dynamic relations, collisions, or the joint linkages to interfere with your editing.
	Physical mode	Sometimes during editing you will want to see how objects collide or how they move when they are linked or constrained by a joint. Select the Physical mode to change to this behavior.
	Move Up/Down	To change the position of an object along the z direction, use this icon.
	Rotate	Use this icon if you want to rotate an object around the x, y, or z-axis. To change the axis, press the spacebar on the keyboard.
	Size	Use to set the size of objects. Press this button, select the object, and—while holding down the left mouse button—increase the size by moving the mouse up, or decrease the size by moving it down.
	Link	Use to establish relationships between joints and bodies. Click on the Link icon, then select all the bodies and elements that should be linked.
	Anchor	Use to anchor one object to another, Now the anchored object will follow the other –if is moved by some edit operation. Select one or more objects that should be anchored, click on the Anchor icon, and lastly click on the other object.
	Properties	Displays the properties window.
	Ray trace	Switch on/off ray tracing, and controls the ray trace modes.

Simulation bar

	Run:	Starts or continues the simulation.
	Stop:	Stops the simulation.
	Reset:	Sets the parameters to their initial values.
	Replay	Plays back the simulation recorded earlier.

-  **Settings** Displays the Settings dialog.
-  **Force Fields** Displays the dialog of the force fields permitting you to adjust them.
-  **Scene Properties** Displays the dialog of the scene so that you can adjust the scene properties.

Object bar



Use the Object bar to build an experiment in the 3D window.

Camera bar



These icons select the camera position as follows:

- | | |
|------------------------|---------------------|
| 1 st button | original view |
| 2 nd button | side view X-Y plane |
| 3 rd button | side view X-Z plane |
| 4 th button | top view Y-Z plane |

The first button is used to jump back to the original view. If you are in planar view, you will find that you can move the object only in that plane.

-  **Zoom In** Set the camera lens to show a smaller field of view and “get in closer” to the scene.
-  **Zoom Out** Set the camera lens to show a greater field of view and “take in more” of the scene.
-  **Rotate upward:** Use to rotate the selected 3D scene up in 5-degree steps.
-  **Rotate downward:** Use to rotate the selected 3D scene down in 5-degree steps.
-  **Rotate Left:** Use to rotate the selected 3D scene left in 5-degree steps.
-  **Rotate Right:** Use to rotate the selected 3D scene right in 5-degree steps.
-  **Go To:** With the go to function the camera can move to any of the objects that are listed in the context menu.
-  **Show** Controls the visibility of supplementary elements.

Description bar

-  **Line** Use to draw straight lines and line segments. When complete, press the right mouse button or the ESC key.

-  **Ellipse** Use to draw ellipses or circles.
-  **Pen and Brush** Set the line style, the color, or the fill style of the ellipse before drawing them. Change the line style, the color, or the fill style of the selected ellipse after they have been drawn.
-  **Picture** Places an image from a Windows bitmap file onto the Description Window.
-  **Text** Create and place captions, equations and text into the Description Window.
-  **Diagram** Create diagrams of plotted curves. The diagram properties window opens and lets you define the curves to be plotted.
-  **Oscilloscope** Create a diagram of an Oscilloscope in the description window.
-  **Button** Button placed on the description window, used to initiate predefined sequences of action, such as running the simulation.
-  **Editfield** Editfield is an interactive element used for two purposes: to display and modify parameters of the simulation or to use in a problem set to accept student solutions.
-  **Trackbar** The Trackbar is an interactive element used to display and set a simulation parameter between certain limits.
-  **Radio** The Radio button is used in problem files to select the right answer from several possible choices.
-  **Checkbox** The checkbox is used to receive an answer from the student to a yes/no question. It's also handy when displaying and modifying Boolean parameters on the description window.
-  **Send selected to back** Used with overlapping elements, this command sends the top element to the back.
-  **Bring selected to front.** Used with overlapping elements, this command sends the back element to the front.

Properties bar

This icon denotes the different property groups of the selected objects.

-  **Location** You will find here the position and rotation of the object. You can move the anchor and fix the object at edit or at runtime.
-  **Velocity** Velocity and angular velocity can be changed here. You may set the velocity vector to be visible or invisible.
-  **Size** Use to change the size of an object.

**Appearance**

Several cosmetic properties can be changed here, such as model file, color, texture, etc.

**Inertia**

Use to change the mass, center of mass, and moment of inertia.

**Material**

You can choose the material of which a body is made. A number of predefined materials are provided in Newton, but you can define your own material by setting the individual material properties separately.

**Special**

Many objects have their own special properties page. Pressing this icon will get you there.

**Point**

If a body has one or more points assigned to it, this icon will show their position and properties.

**Force, Torque**

If a constant force or torque has been assigned to a body you can change the properties here; for example, the acting point and the direction of the constant force.